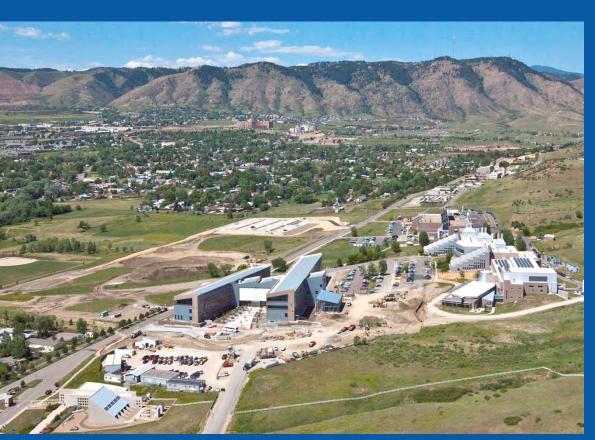


Real-World PHEV Fuel Economy Prediction



DOE Annual Merit Review

PI & Presenter: Jeff Gonder VSA Task Lead: Robb Barnitt

Organization: NREL

May 11, 2011

Project ID: VSS047

This presentation does not contain any proprietary, confidential or otherwise restricted information

PHEV = plug-in hybrid electric vehicle

Up-Front Summary

- Estimating PHEV fuel economy on standard cycles is complicated
 - Issues: Fuel and electricity use; CD and CS operation
 - Extensive procedure development (ANL led, NREL et al. support)
- "Raw" standardized test results do not represent real-world
 - Objective in-use predictions critical for technology assessment
- Real-world fuel economy prediction is also complicated
 - Which drive cycles to use and how to combine the results
 - Changing rate of fuel and/or electricity use
 - Considerations for CD vs. CS mode
 - Potential variation in depletion distance
 - Appropriately weighting each operating mode
 - Impact from different powertrain topologies
- Project is developing various options, evaluating strengths/ weaknesses and recommending preferred approach(es)

Project Overview

Timeline

Activities specific to current effort:

- Started late 2009
- Ending late 2011
- Project is 60% complete

Budget

Corresponding funding:

• Total (all DOE): \$250k

– FY11: \$100k– Prior: \$150k

Barriers Addressed

- Lack of standardized test protocols
- Real-world performance prediction
 - Assess realistic fuel savings
 - Justify development costs
 - Set reasonable expectations
- Simulation and prediction methodologies

Project Partners

- ANL (procedures & dyno testing)
- SAE J1711 task force (procedures)
- INL (field evaluation results)

Project Relevance

Important to understand real-world energy use

- Address barriers from overview slide
 - Lack of standardized protocols
 - Simulation and prediction methodologies
 - Set expectations prior to developing/deploying each vehicle generation
- Objective technology evaluation
- PHEV fuel economy <u>very</u> sensitive to driver behavior
 - Driving aggressiveness and accessory loads
 - Distance driven between recharge opportunities
 - · CD vs. CS proportioning



Elaborating on Project Relevance

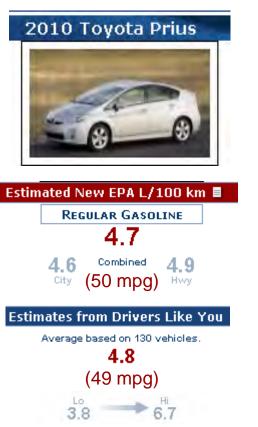
Established real-world prediction for CVs/HEVs (No consensus approach for PHEVs!)

- Existing standard vehicle test procedures
 - E.g., Federal Test Procedure (FTP or city test)
 and Highway Fuel Economy Test (HFET)
 - "Raw" result for Prius ≈ 3.4 L/100 km (≈ 70 mpg)
- Official adjustments to raw results



EPA window sticker estimate

 Provides reasonable realworld prediction



CV = conventional vehicle HEV = hybrid electric vehicle Picture and data accessed 3/3/2011 from www.fueleconomy.gov

PHEV Fuel Economy Milestones/Outputs

SAE standards (ANL led, NREL et al. supported)

- 6/10 SAE J1711: Recommended Practice for Measuring the Exhaust Emissions and Fuel Economy of Hybrid-Electric Vehicles, Including Plug-in Hybrid Vehicles
- 9/10 SAE J2841: Utility Factor Definitions for Plug-In Hybrid Electric Vehicles Using Travel Survey Data

NREL deliverables to DOE on real-world evaluation

- 6/10 Multi-day GPS Travel Survey Data Report: Using GPS Profiles, Including Multi-day, to Assess PHEV Fuel Efficiency
- 9/11 Report on Real-World PHEV Fuel Economy Prediction

Project Approach

Building Blocks

 Revise PHEV calculation procedures for standard test cycles

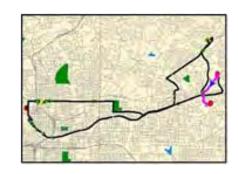


- Identify in-use fuel economy issues and basic prediction options
 - Evaluate against aftermarket conversion PHEV test data



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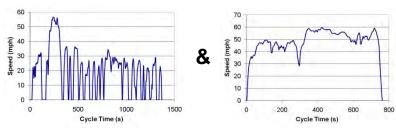
 Develop vehicle simulations over large realworld driving sample



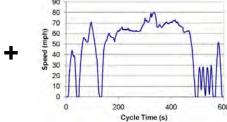
Project Approach

Develop details for variety of prediction approaches

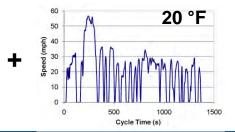
- Based on different standard cycle options (CD & CS tests)
 - Just using historic city and highway cycles

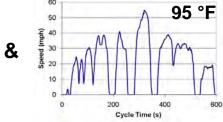


City/hwy plus US06 (adds aggressiveness component)



Full 5-cycle test (adds temperature/accessory load component)





Project Approach

Evaluate the potential prediction approaches

- Confirm real-world simulations provide reasonable basis
 - Adjusted CV and HEV certification tests vs. real-world results
- Consider issues with different PHEV powertrain designs
- Summarize strengths and weaknesses of different approach options
- Also evaluate against automaker PHEV data
 - E.g., as results become available from DOE's PHEV
 Technology Acceleration and Deployment Activity (TADA)



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Progress made in a variety of areas

Revising standard cycle calculation procedures

Detailed on following slides

- Understanding real-world prediction issues
- Developing basic adjustment options with simplifying assumptions
 - Using "MPG-based approach" with historic city and highway cycles

City MPG =
$$\frac{1}{\left(0.003259 + \frac{1.1805}{\text{FTP FE}}\right)}$$

$$Highway MPG = \frac{1}{\left(0.001376 + \frac{1.3466}{HFET FE}\right)}$$

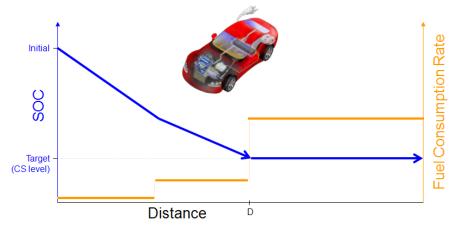
- Applying one option to aftermarket conversion PHEV data
- Leveraging on-road GPS cycles to evaluate other powertrains
- Performing utility factor analysis with diverse multi-day data sets
- Further adjustment method development
- Confirming existing CV and HEV adjustment methods agree with corresponding distribution of real-world simulation results

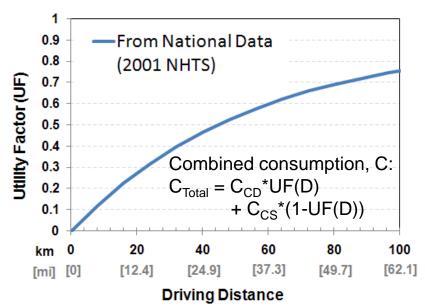
MPG = miles per gallon; FTP = Federal Test Procedure; HFET = Highway Fuel Economy Test; FE = fuel economy in mpg

Supported J1711 revision to address PHEV testing issues

- Repeat cycles for full CD and CS testing
- Measure both fuel and electricity, and keep separated
- Combine modes using a utility factor (UF) and once daily charging assumption
- Obtain "raw" L/100 km (mpg) and kWh/100 km (Wh/mi) values for given test cycle

SOC: Vehicle battery's state-of-charge NHTS: National Household Travel Survey

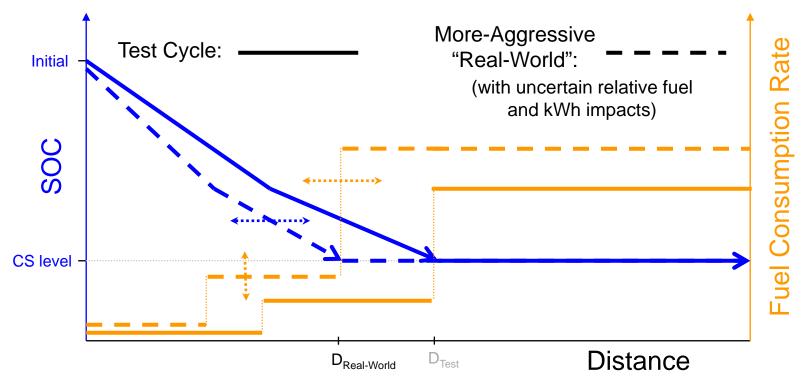




Understanding PHEV real-world adjustment issues

(Adjustments represent additional road loads vs. historic cycles)

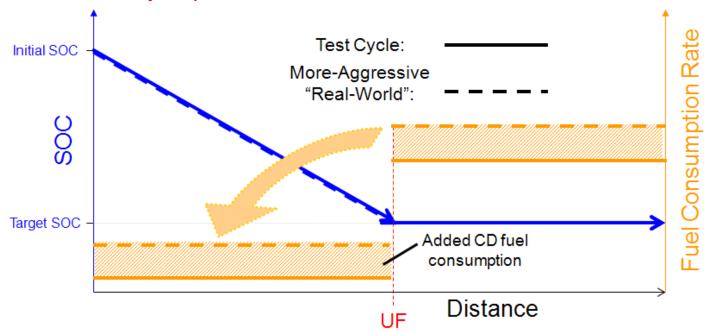
- CS mode will use more fuel (straight forward)
- CD mode will use more fuel and/or change battery depletion rate
 - This impacts fuel, electricity and depletion distance for UF calculations



Develop potential methods via simplifying assumptions

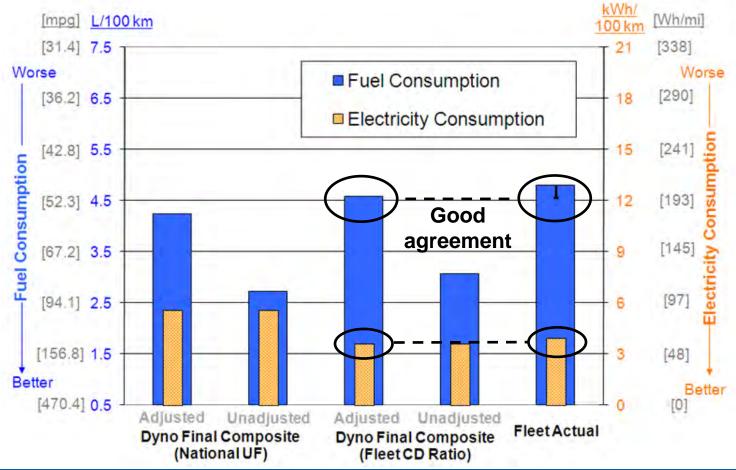
E.g., "blended"/constant depletion rate method

- Apply adjustment equation to CS result
- Retain the same UF-weighting distance from the actual test cycle results
- Assume "extra road loads" simply add CD fuel consumption at the same rate increment as for CS driving
- Actual PHEV may deplete slower or faster in the real-world



Evaluate "blended method" against Hymotion Prius data

- In collaboration with ANL and INL
- Works well for blended PHEV; may not work as well for other designs

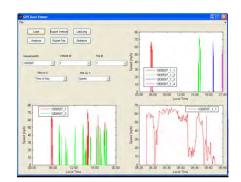


Leverage on-road drive cycles for PHEV evaluation

- Travel surveys increasingly use GPS (e.g., to aid regional transportation planning)
 - Improved technology and cost
 - Better accuracy and respondent burden



- Data sets from Texas DOT
 - 783 vehicles in San Antonio and Austin, TX
 - Collected in 2006
 - 24-hr, sec-by-sec drive profiles
 - Capture real-world aggressiveness and distances driven between stops

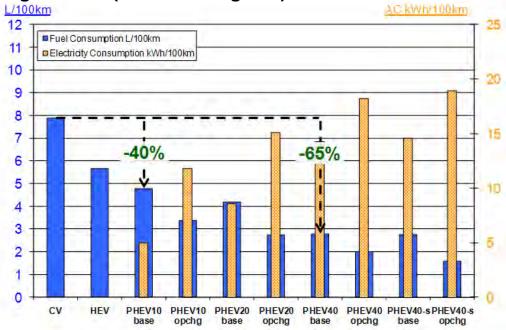


Assess different scenarios via simulation

Mid-size car assumptions

				PHEV			
	Units	CV	HEV	<i>10</i>	20	40	40s
Engine Power	kW	123	77	77	78	80	85
Motor Power	kW	n/a	36	40	41	43	130
ESS Energy (total, DC)	kWh	n/a	1.7	4.5	8.2	16.4	16.4
Curb Mass	kg	1473	1552	1578	1614	1694	1789

Average results (distance-weighted) from real-world simulations



Collaboration and Coordination



 ANL – procedure development and chassis dynamometer testing



SAE J1711 – task force participation



VSATT – present potential approaches



 EPA – share approach presentations; comment on proposed rulemaking



 INL – past and potential future fleet evaluation data sharing

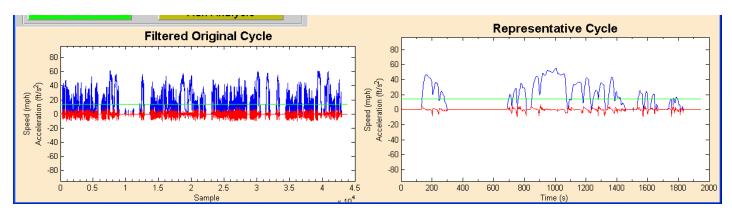
Future Work

FY11

- Complete remainder of project plan
- Deliver milestone to DOE
- Recommend preferred prediction approach(es)
 - Based on strengths and weaknesses of considered options

Options for Future

- Further evaluation against automaker PHEV fleet demonstration data
- Develop better test cycle(s) to represent real-world
 - Leverage NREL fleet duty cycle evaluation tool



Reiterating Project Plan

Details for developing and evaluating potential realworld prediction approaches

- Based on different standard cycle options (CD & CS tests)
 - Just using historic city and highway cycles
 - City/hwy plus US06 (adds aggressiveness component)
 - Full 5-cycle test (adds temperature/accessory load component)
- Confirm real-world simulations provide reasonable basis
 - Adjusted CV and HEV certification tests vs. real-world results
- Consider issues with different PHEV powertrain designs
- Analyze/examine results to identify strengths and weaknesses



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Summary

- Estimating PHEV fuel economy on standard cycles is complicated
 - Issues: Fuel and electricity use; CD and CS operation
 - Extensive procedure development (ANL led, NREL et al. support)
- "Raw" standardized test results do not represent real-world
 - Objective in-use predictions critical for technology assessment
- Real-world fuel economy prediction is also complicated, e.g.:
 - Adjust rate of fuel and/or electricity use in each operating mode, as well as depletion distance for CD vs. CS weighting
 - Different impacts for different powertrain topologies (blended vs. "EREV"/high electric power PHEV)
- Project is developing various options, evaluating strengths/ weaknesses and recommending preferred approach(es)

Special thanks to:

Lee Slezak and David Anderson,
 DOE Vehicle Technologies Program

NREL contacts:

- Jeff Gonder jeff.gonder@nrel.gov
- Robb Barnitt <u>robb.barnitt@nrel.gov</u>

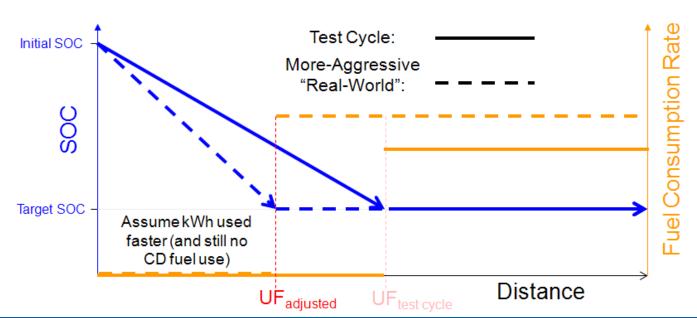
Questions?

Technical Back-Up Slides Description of Additional Accomplishments and Related/Synergistic Activities

Develop potential methods via simplifying assumptions

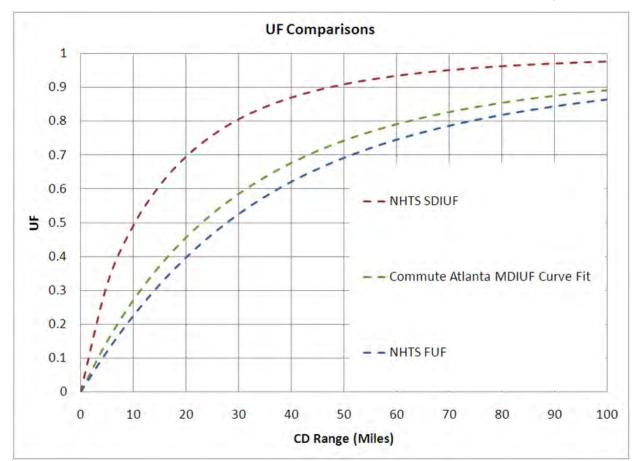
E.g., "All-electric"/CD distance reduction method

- CS fuel use can be adjusted as normal
- Only adjust electricity in CD mode (problematic to calculate)
- If made, adjustment yields new UF distance (usable energy depleted faster)
- But, result could be unachievable if motor/battery power insufficient to deplete energy over shorter distance



Examine UF options with multi-day data

- Fleet (distance-weighted) vs. individual (vehicle-weighted) predictions
 - Individual expected value should use multi-day data

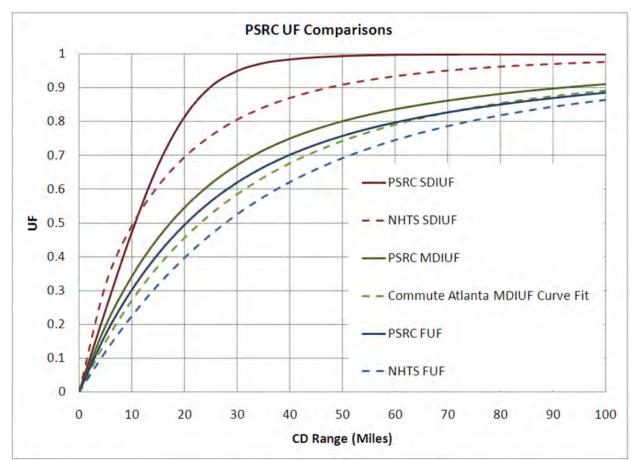


SD/MDIUF = single-day/ multi-day individual utility factor

FUF = fleet utility factor

Examine UF options with multi-day data

- Similar trends from additional regional data set, but offset
 - Other data/statistical expansion required



PSRC = Puget Sound Regional Council, data from 18 mo. Seattle area Traffic Choices Study

NREL Fleet Duty Cycle Tool Capabilities

Analyze and Characterize

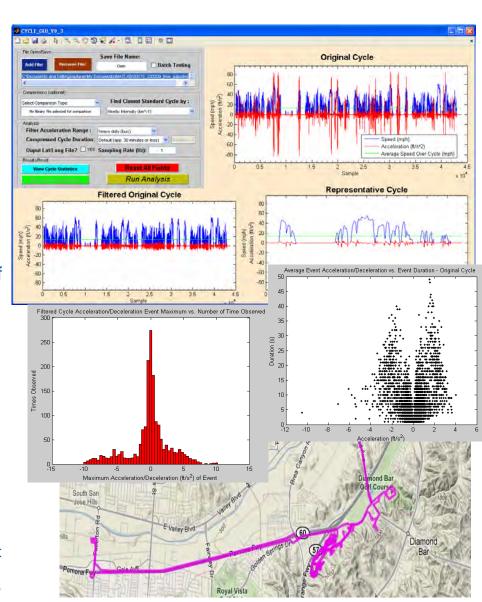
- Calculates over 150 unique driving statistics
 - Stats for both raw data and generated test cycle
 - Max Speed, Average Speed, Stops per Mile, etc.
 - Filters and corrects for data errors
- Finds closest existing cycle.
 - Matched based on user selected driving statistics

Visualize

- Displays graphs, tables, and histograms of drive data
 - · Graphs speed vs. time
 - · Tabulates driving statistics
 - · Acceleration histograms
- Creates Latitude and Longitude files for route visualization
 - Use Latitude and Longitude output to create route maps with Google Earth or other mapping software

Test Cycle Generation

- Generates custom duration test cycles for simulation and modeling
 - Cleans raw source data prior to custom test cycle creation
 - Outputs custom cycle speed vs. time points for dynamometer testing



Transportation Secure Data Center (TSDC)

www.nrel.gov/vehiclesandfuels/secure_transportation_data.html

Secure archival of and access to detailed transportation data

- Travel studies increasingly use GPS → valuable data
- TSDC safeguards anonymity while increasing research returns
 Various TSDC functions
 - Advisory group supports procedure development and oversight
 - Original data securely stored and backed up
 - Processing to assure quality and create downloadable data
 - Cleansed data freely available for download
 - Controlled access to detailed spatial data
 - User application process
 - Software tools available through secure web portal
 - Aggregated results audited before release

Sponsored by the U.S. Department of Transportation (DOT) Operated by the NREL Center for Transportation Technologies and Systems (CTTS); Contact: Jeff.Gonder@nrel.gov



NRC report*



GPS = global positioning system

* See recommendations from this 2007 National Research Council report: books.nap.edu/openbook.php?record_id=11865