



Moving Beyond 2% Uncertainty: A New Framework for Quantifying Lidar Uncertainty

Jennifer F. Newman and Andrew Clifton

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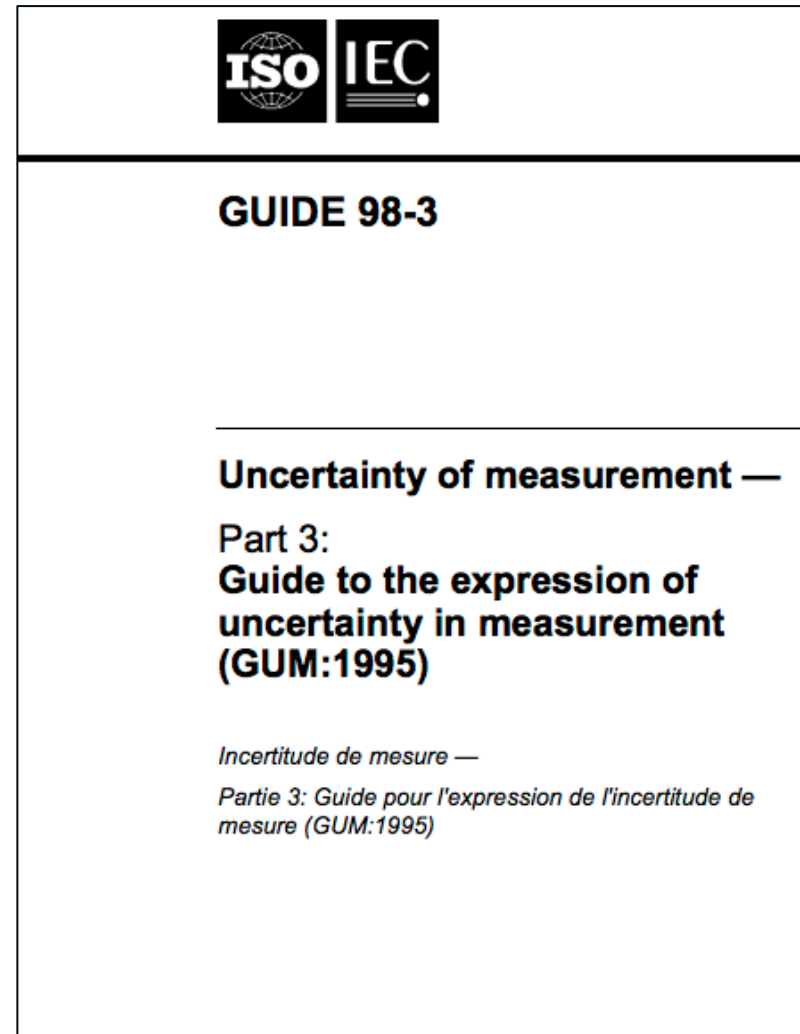
[NREL/PR-5000-67642](#)

What is Uncertainty?

- Parameter that characterizes the **spread of values** that could be reasonably attributed to a measurand
- Measure of **possible error** in an estimated value
- Quantity characterizing **range of values** within which the actual value of a measurand is expected to lie

General Definition:

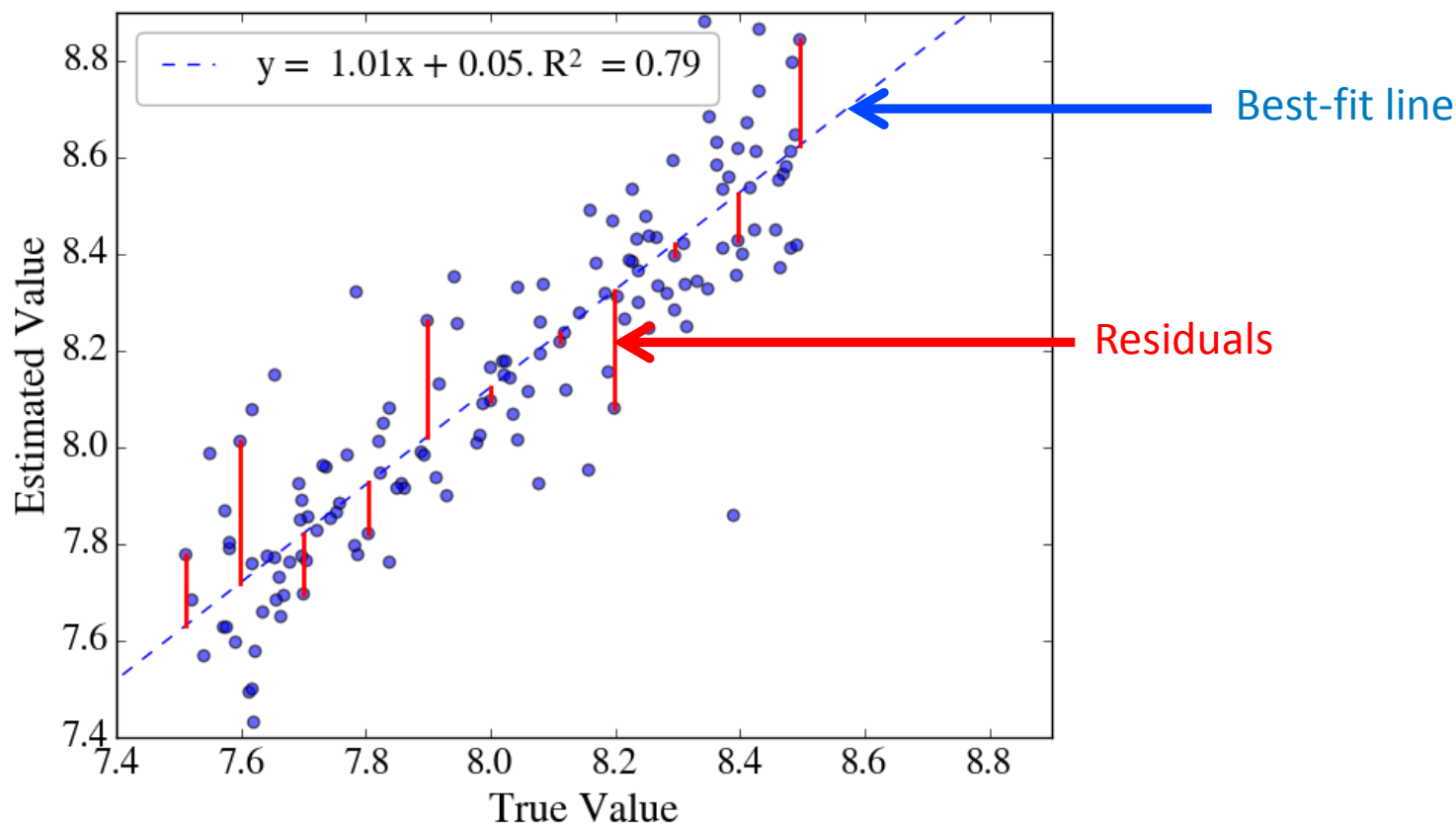
***Doubt about the validity** of a measured quantity.*



Source: ISO/IEC GUIDE 98-3 ed1.0 (2008-09), *Uncertainty of measurement - Part 3: Guide to the expression of uncertainty in measurement*. JCGM, 2008.

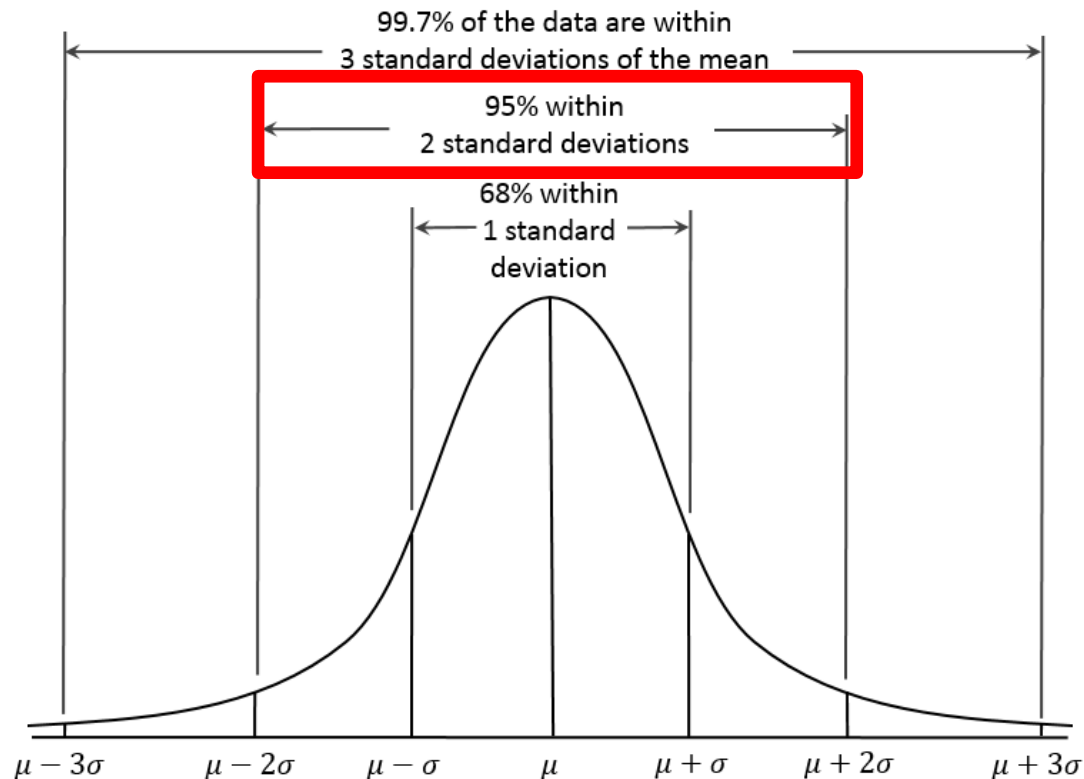
How Do We Quantify Uncertainty?

- Lots of different ways!
- In this presentation, we define uncertainty as the *standard deviation of the normalized error* about the best-fit line.



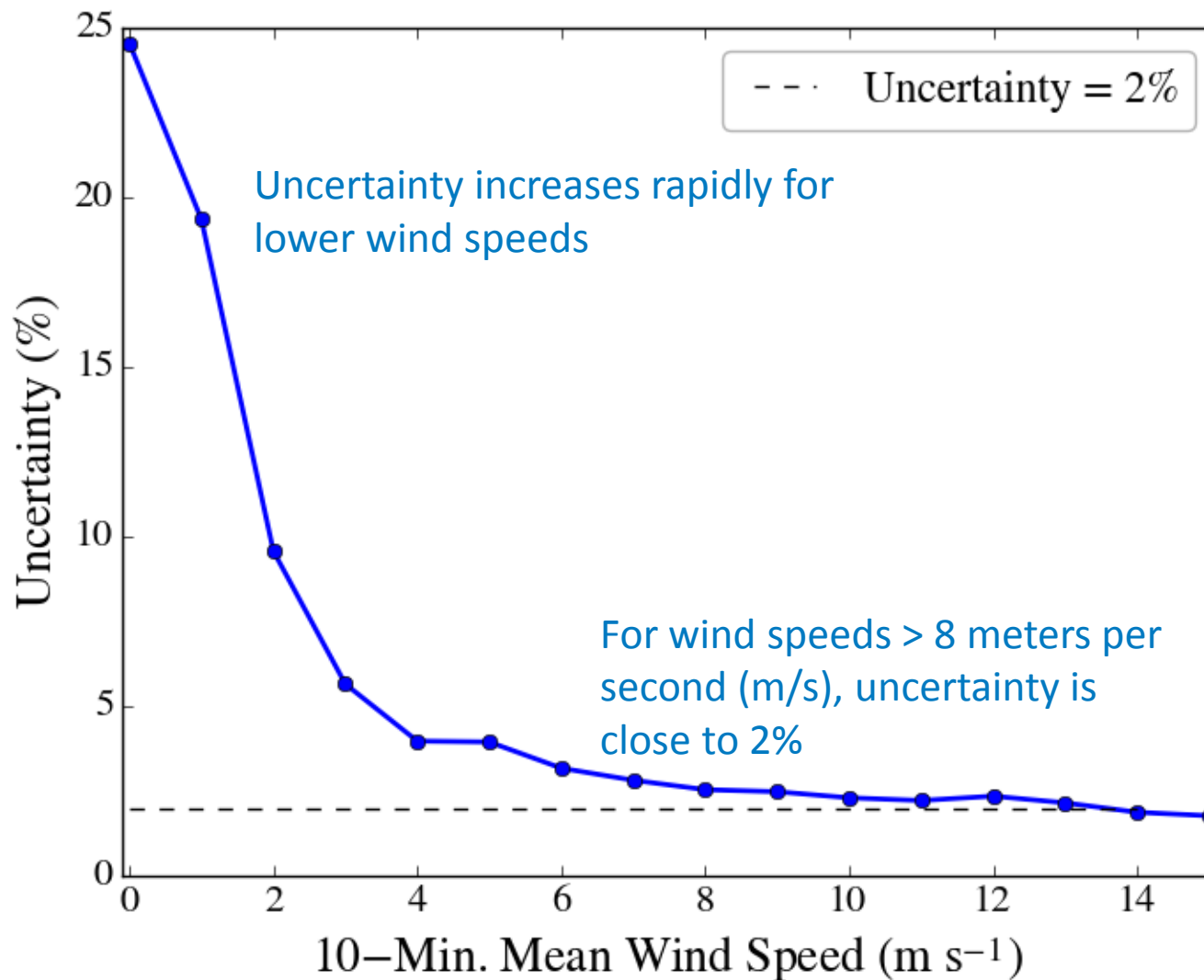
A Statistical Look at Uncertainty

- Assume the wind speed errors in each bin follow a Gaussian distribution
- The uncertainty gives us an idea of the range of true wind speed values that are associated with our estimate.



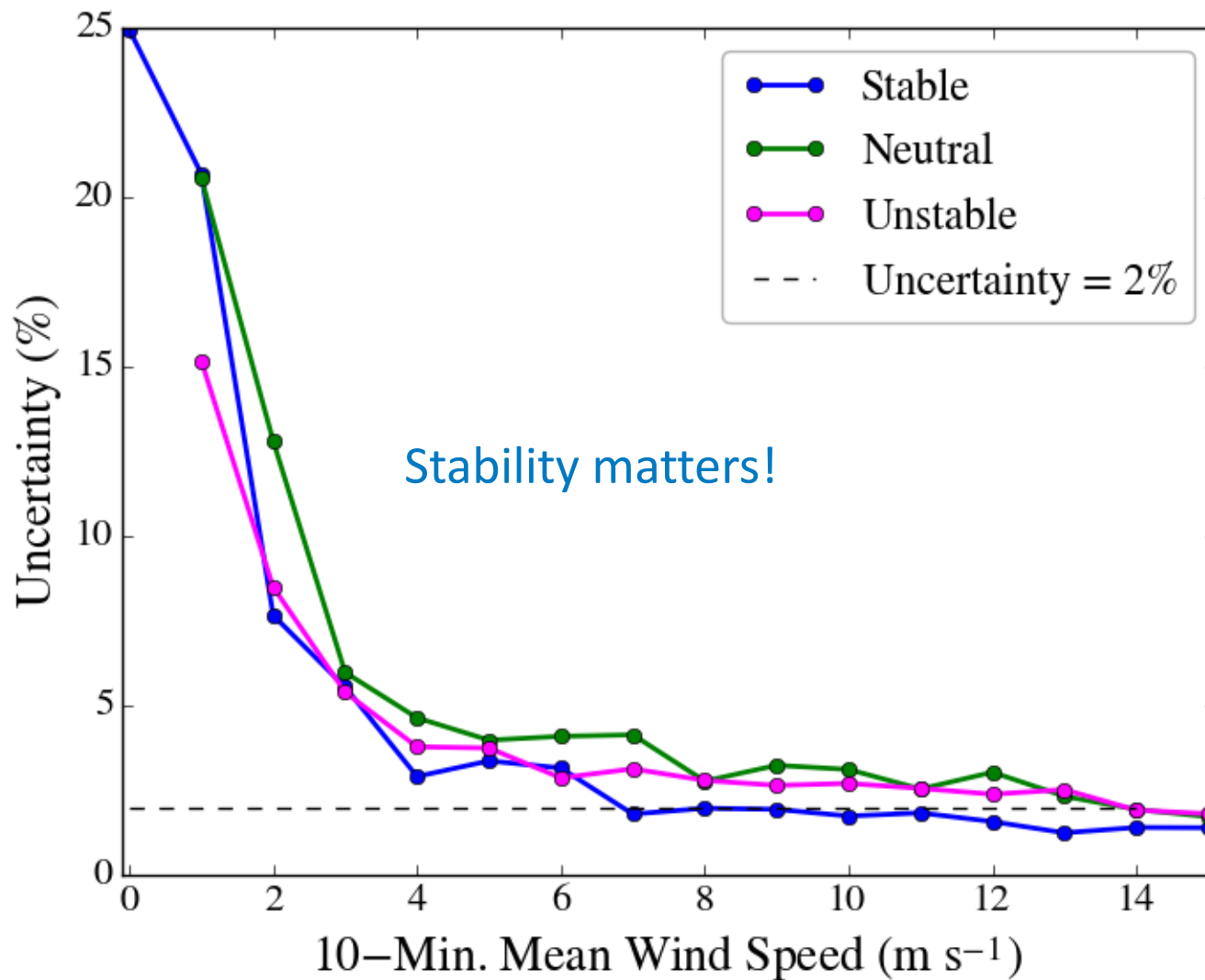
Source: Dan Kernler - Own work, CC BY-SA 4.0, <https://commons.wikimedia.org/w/index.php?curid=36506025>

Example of Lidar Wind Speed Uncertainty



Data from 60 m above ground level (AGL) at Southern Great Plains ARM site

Example of Lidar Wind Speed Uncertainty



Stability matters!

Current Uncertainty Framework: International Electrotechnical Commission (IEC) 61400-12-1

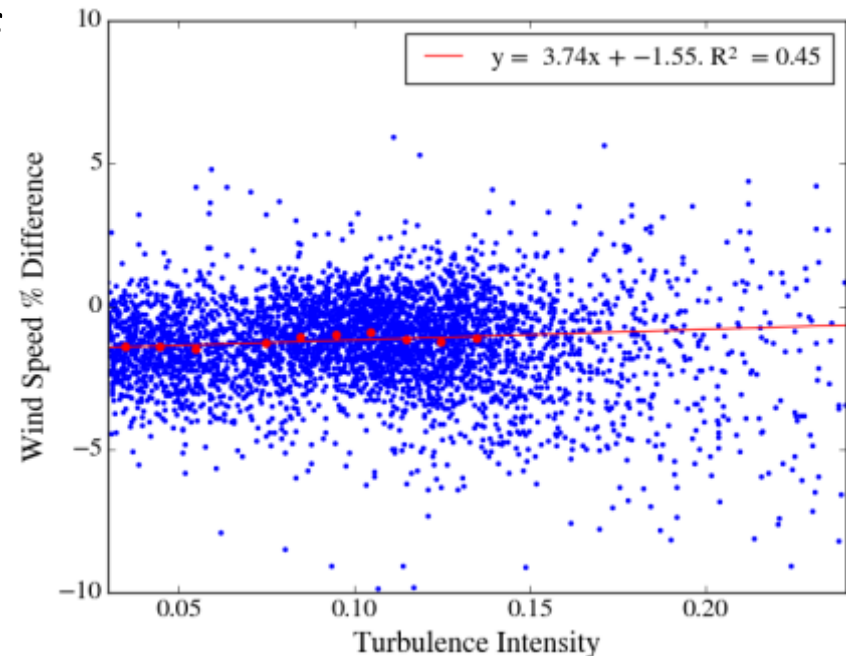
- Estimate uncertainty due to:
 - Calibration
 - Classification
 - Nonhomogeneous flow within probe volume
 - Mounting effects
 - Variation in flow across site
- Assume that:
 - Uncertainty components are independent of one another
 - Components can be added in quadrature
 - **Total uncertainty is a single, climatological value.**



Photo by Andrew Clifton, NREL 24383

Sensitivity to External Parameters: IEC 61400-12-1

- From Annex L: Classification of remote sensing devices
- Bin input data and calculate regression line for binned data vs. % difference between remote sensing device (RSD) and reference cup
- **Sensitivity:** Product of slope of regression line and standard deviation of input variable
- Sensitivity is used to identify significant variables and calculate RSD accuracy class.

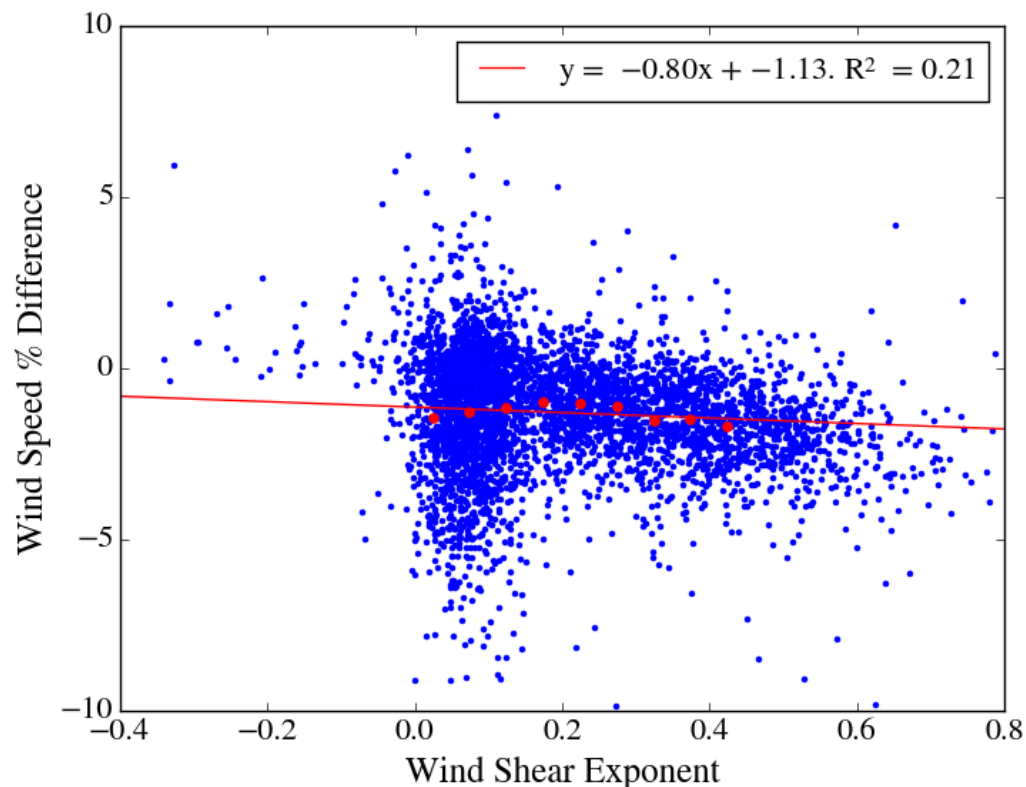


Limitations of Current Framework

- Sensitivity analysis assumes linear relation between external variables and RSD error
- Physical processes that cause these errors are not considered.

Example: At this site and measurement height, relation between shear and RSD error is not strictly linear.

But shear could be related to physical processes in the atmosphere that increase uncertainty in RSD measurements.



Brainstorming an Uncertainty Framework

method → L1/L2X npt/gov

WCS?

ultra soft? de base?

Predictors	Predictand
T_i (corrected) [-]	T_i [-] ← $\frac{\sigma_U}{U} \frac{[LT^{-1}]}{[LT^{-1}]}$
α [-]	
SNR_{ss} [-]	
$(\sigma_w)^2$ [$L^2 T^{-2}$]	
spectral broadening [LT^{-1}]	
Internal temp [K]	
off-vertical pitch of lidar [-]	
Scanning circle ϕ [L]	

length scale - integral

- ϕ
- integral / ϕ
- probe length (FWHM)
- $(\sigma_w)^2$

$\frac{L^2}{LT^2}$

α : cone angle / off-vertical angle

System performance - SNR

- Internal temp

"Characteristic scales"

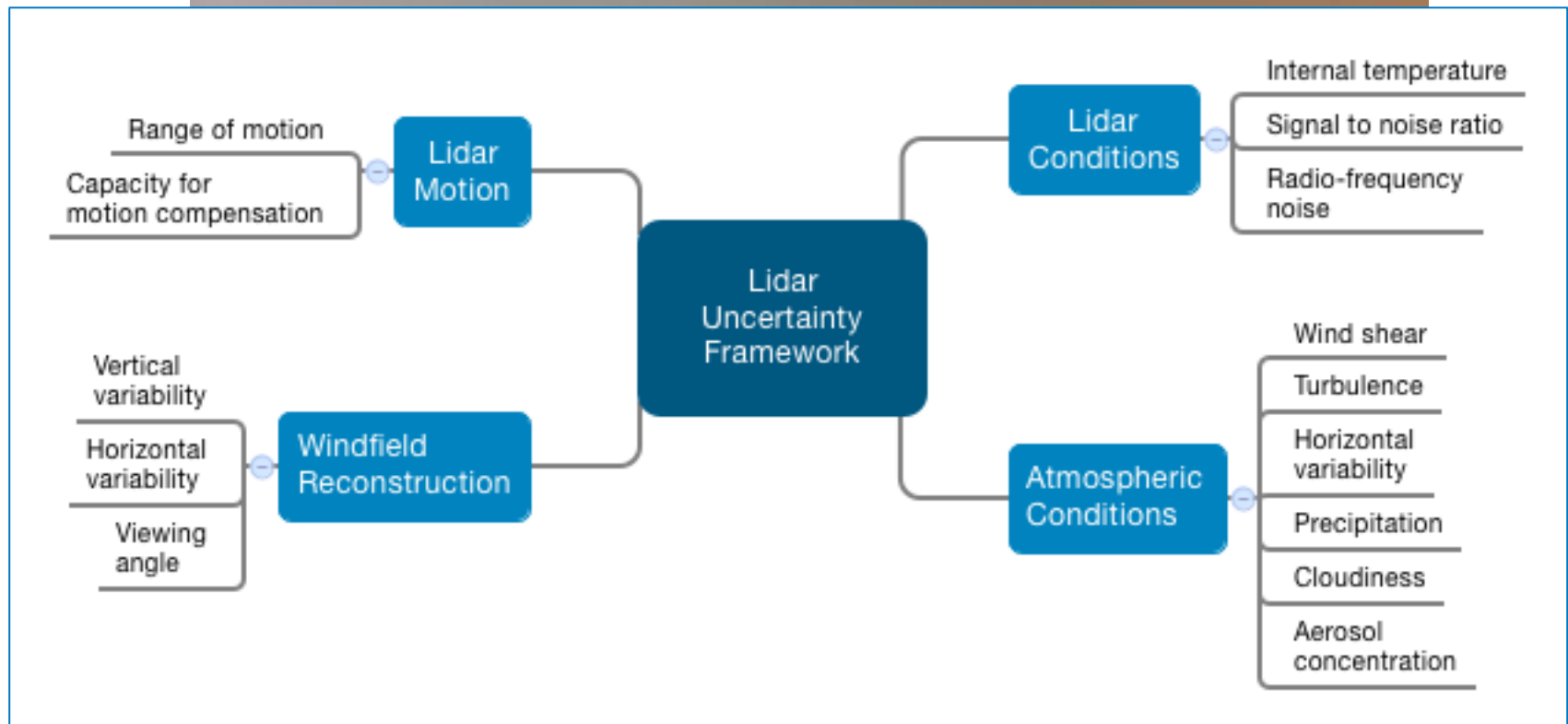
timescale = ϕ/U ← correlation

" = integral timescale ← T. correlation

= $1/(\phi/U)$

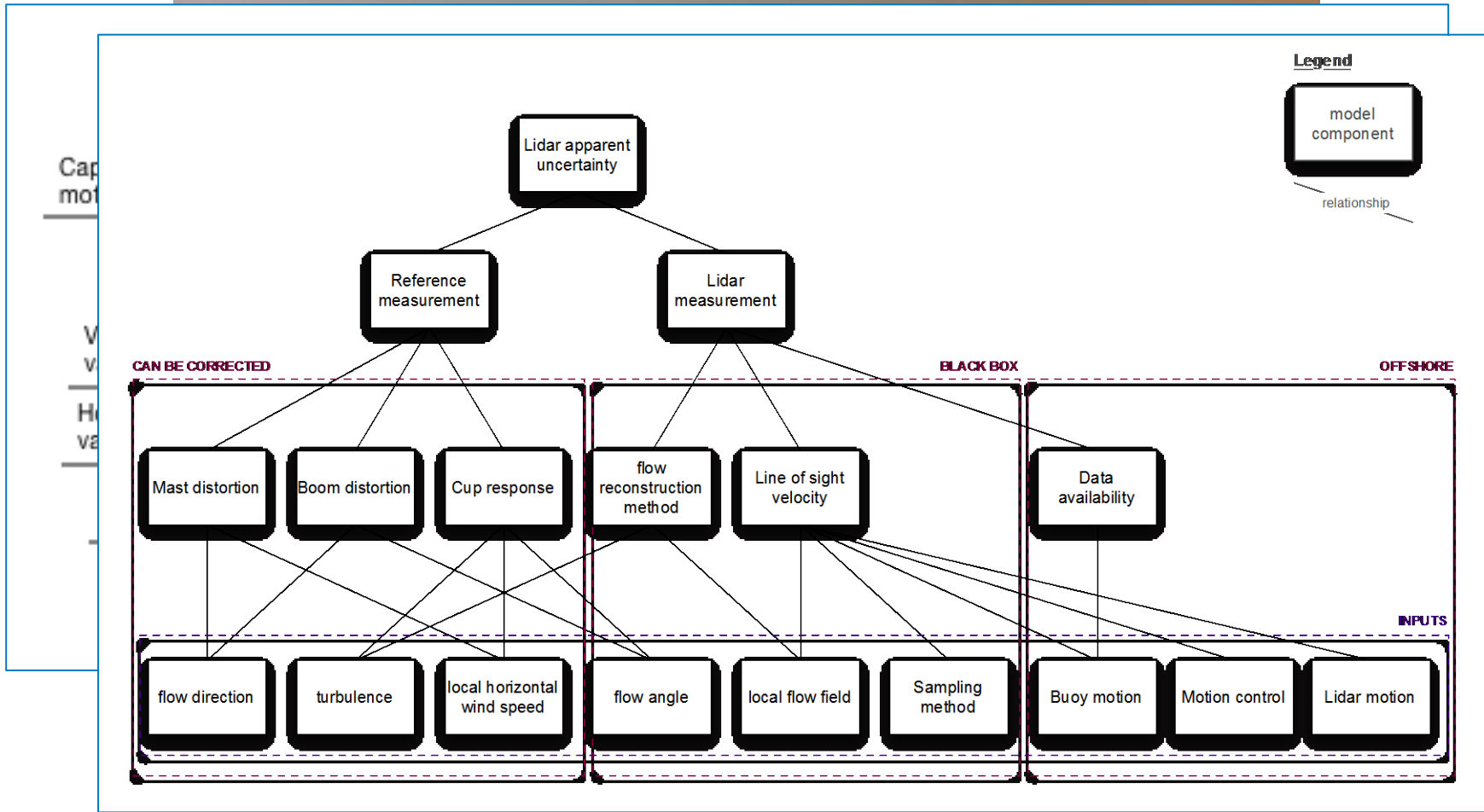
Variance - $\frac{\sigma_w}{\text{spectral broadening}}$

Brainstorming an Uncertainty Framework



Brainstorming an Uncertainty Framework

method → Lidar method



Brainstorming an Uncertainty Framework

SB = Spectral Bandwidth
CD = Cantilever deflection

cell: 305 513 0145

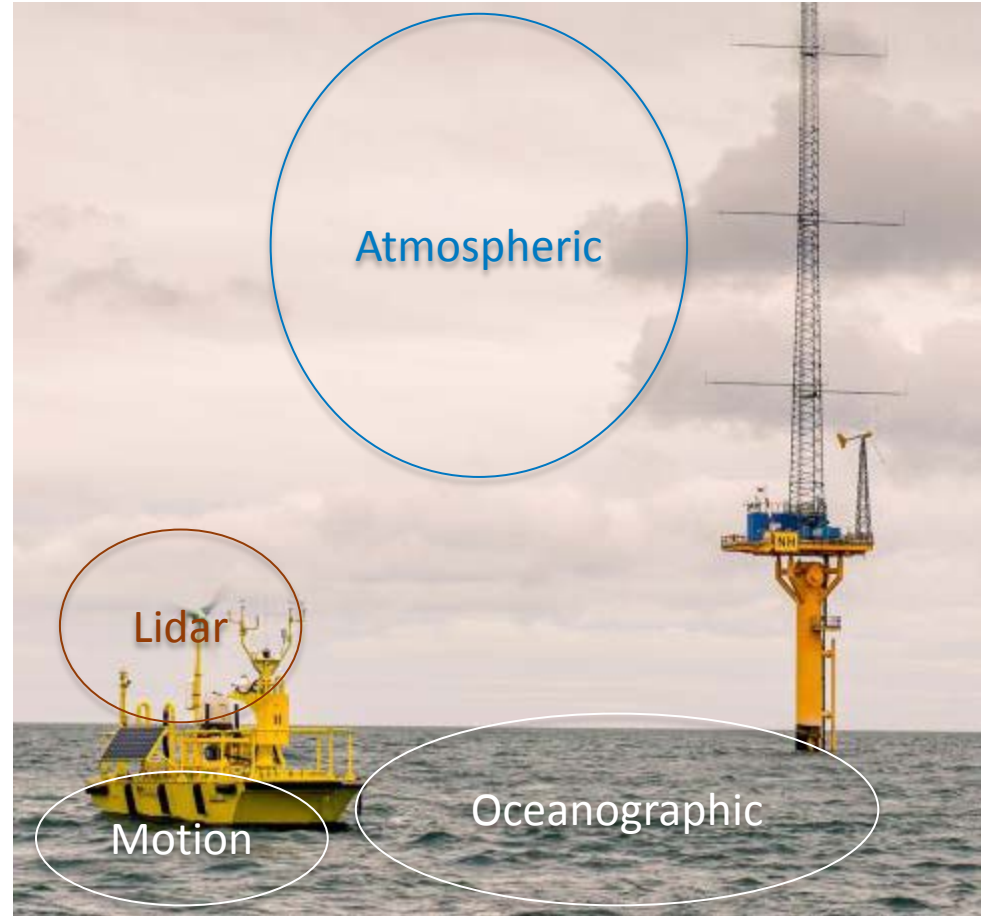
High level Category	Physical Basis	How these fit into the Uncertainty Framework	Available In advance		Available w/ Lidar
			Observation	Proxy	
LOS = FRT centroid detection	Probe length (SB, CD)	Lidar	FWHM(ϵ)	SNR	Loss of focus?
	Aerosol distribution (SB)	Atmosphere			
	Lidar noise (SE)	Lidar	Lidar q.u. SNR	Range, aerosol, height, range gain	"
	Access to signal strength (SB)	Lidar			
	SNR		Range	aerosol, height, range gain	"
	Flash homogeneity w/ LOS direction	Atmospheric $\sqrt{\frac{\partial U}{\partial x} \frac{\partial U}{\partial z}}$	Vertical star T _i	variability across scanning circle	"
	Interception (SB, CD)	Motion			"
Windfield Reconstruction Algorithmic app.	Assumed homogeneity	Atmospheric - Homogeneity	Pointing accuracy	Sheet	Homogeneity
	Lidar Range/angle	- Height accuracy		Pitch, roll, yaw	stationarity
	Pointing accuracy	- Motion - compensation			
	Assumed stationarity	Lidar - pointing accuracy			

Diagram on the left:

- Cap mot
- V
- V
- H
- V
- flow direction
- Mast distortion
- CAN BE CORRECTED

What's an Uncertainty Framework?

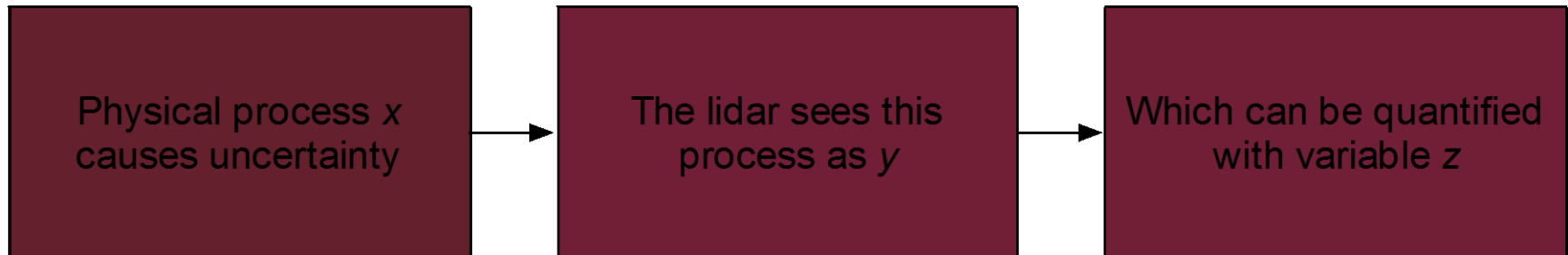
- Assign all sources of uncertainties to clear categories
- Create models for each of them
 - Physics or data-driven
- Apply them to every measurement.



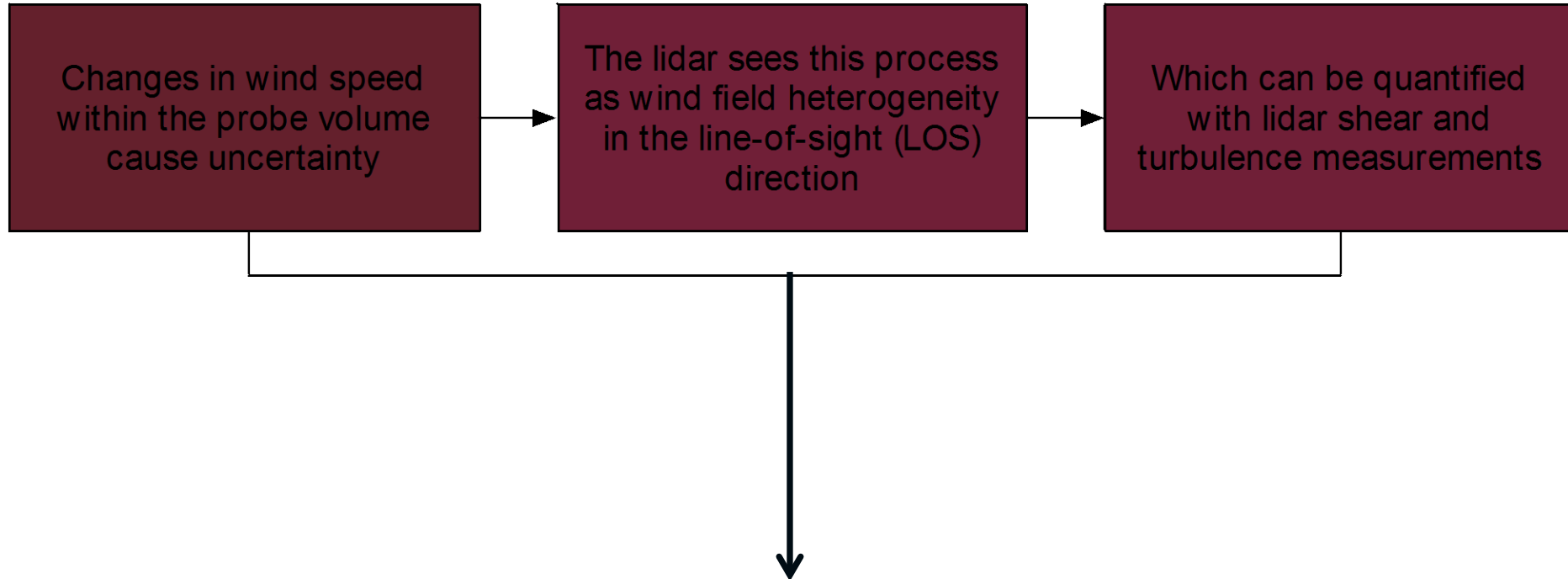
AXYS FLiDAR 6-meter buoy. Photo from AXYS Technologies

New Uncertainty Framework

- Uncertainty is *dynamic* and depends on current flow conditions during each 10-minute period
- Relate what the lidar sees to physical processes and sources of error.

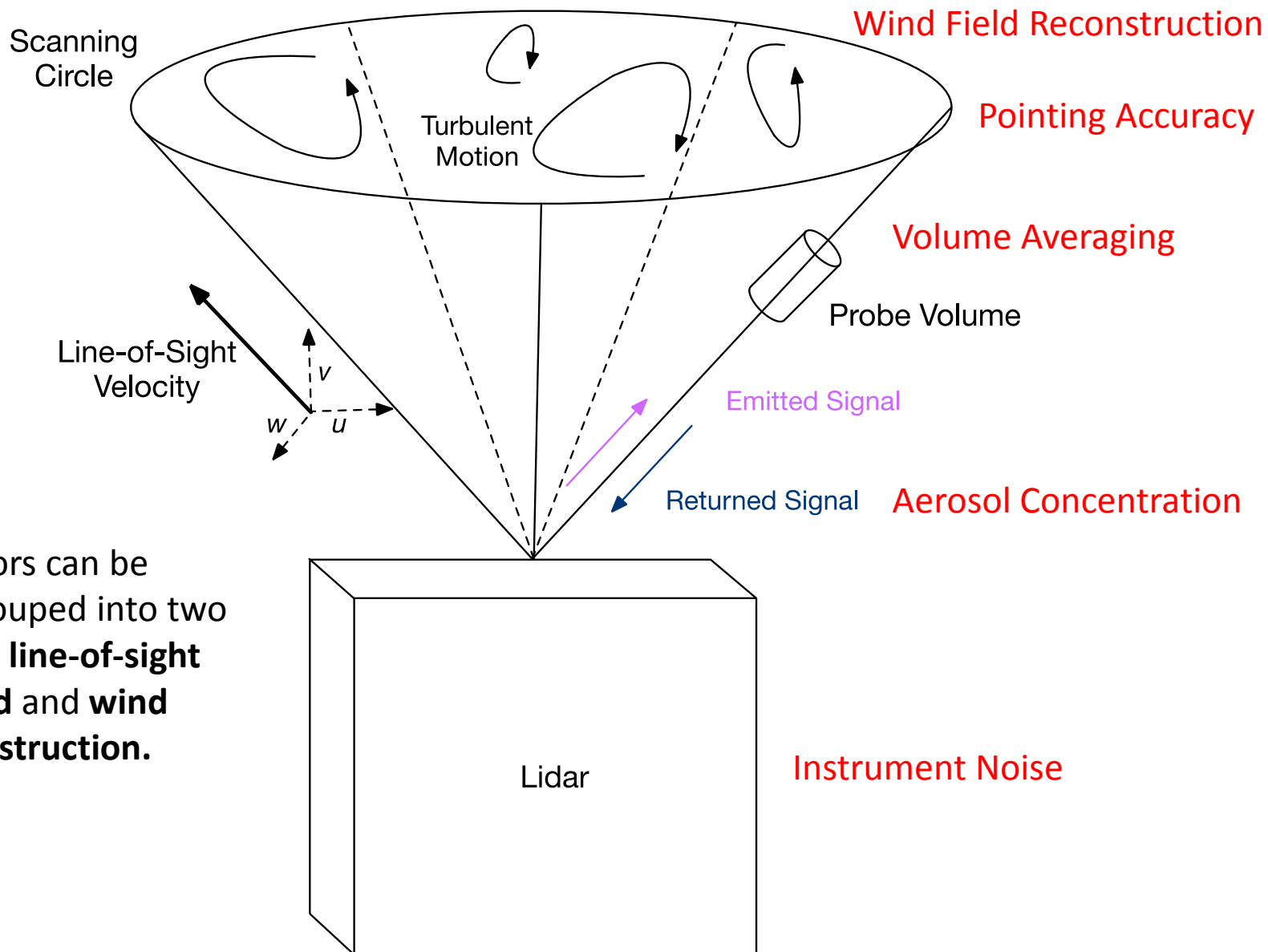


Example: Wind Shear



The key of the framework is figuring out this relationship.

Factors That Affect Uncertainty



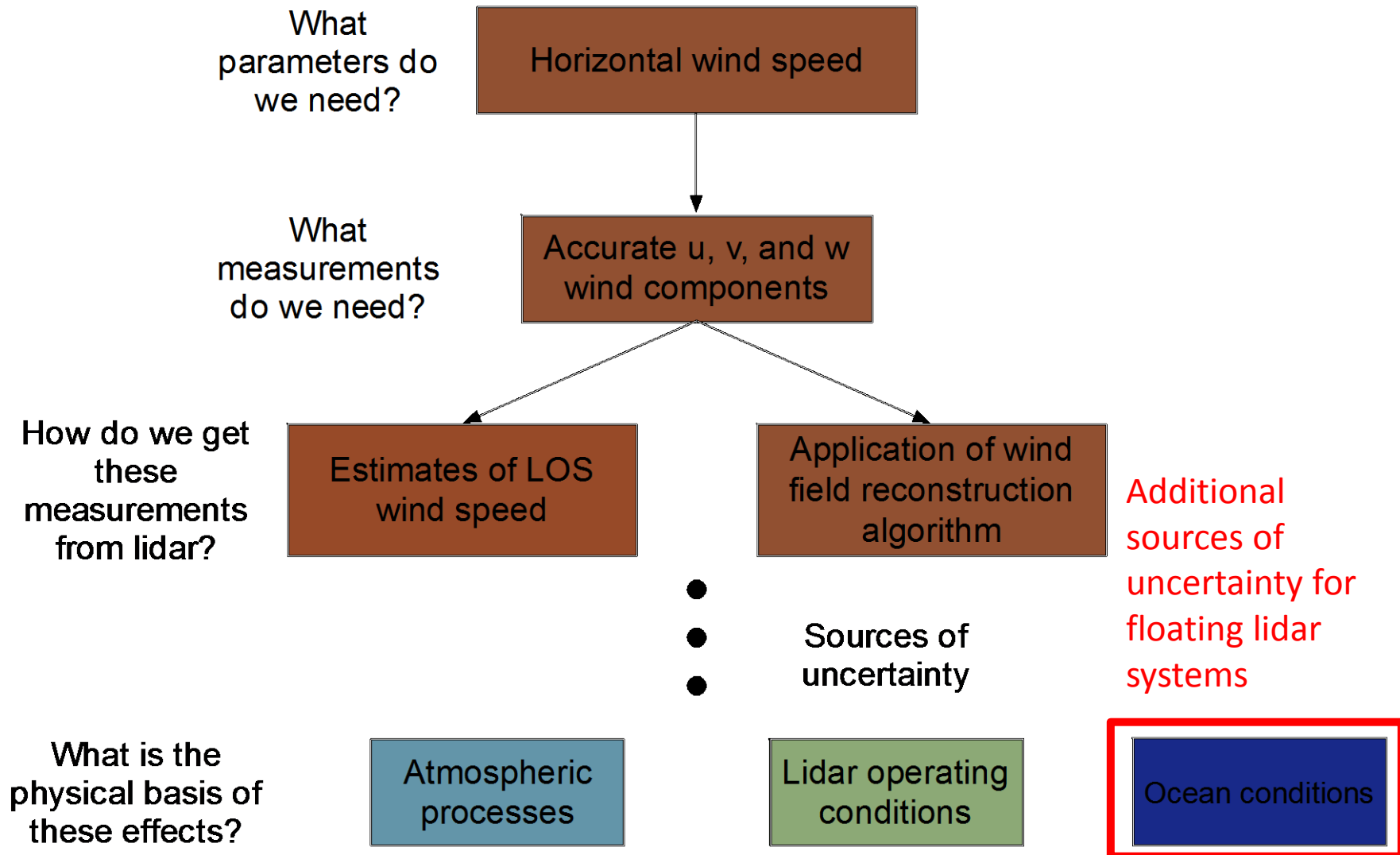
These factors can be broadly grouped into two categories: **line-of-sight wind speed** and **wind field reconstruction**.

What The Framework Might Look Like



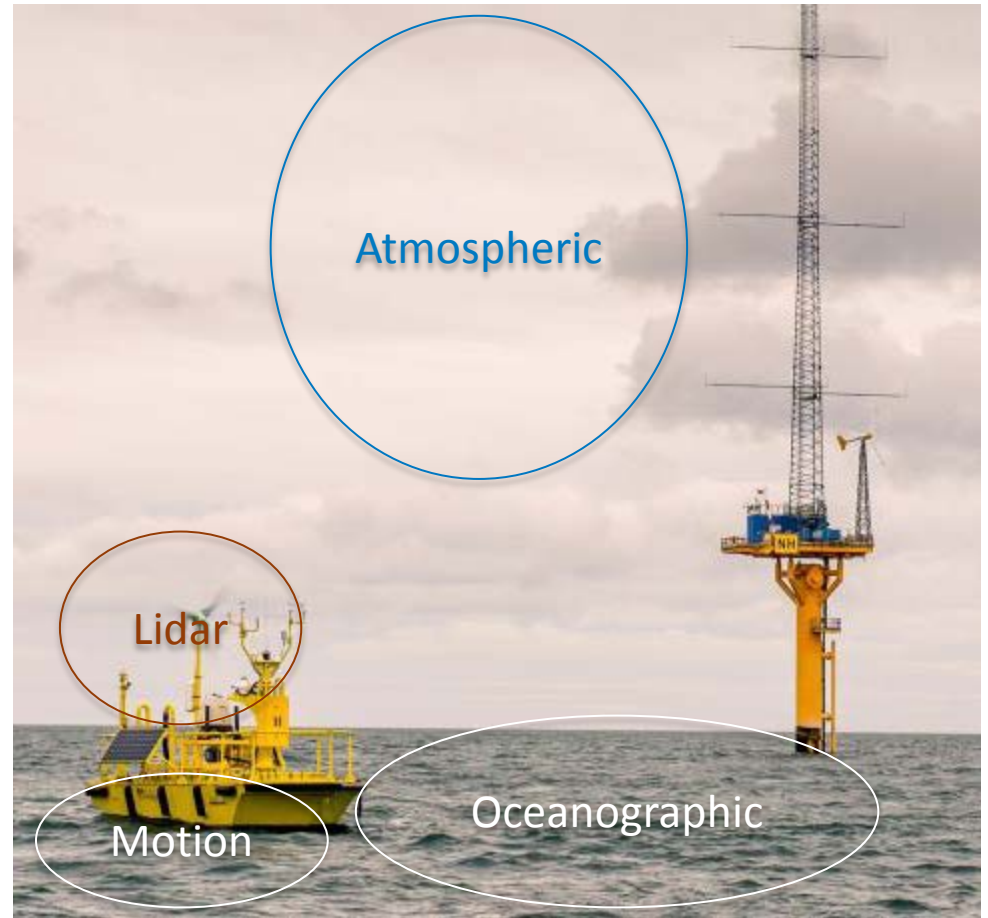
PRELIMINARY:
EXAMPLE ONLY

Simplified Framework



What's an Uncertainty Framework?

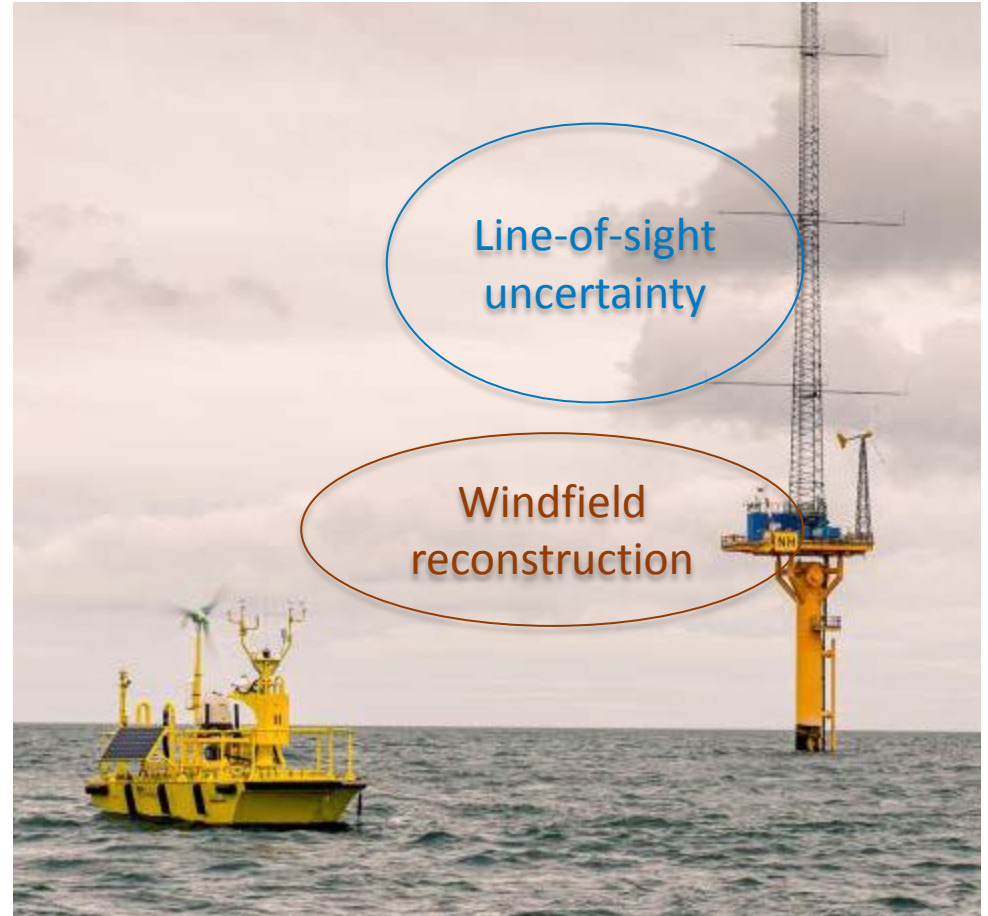
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AXYS FLiDAR 6-m buoy. Photo from AXYS Technologies

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AXYS FLiDAR 6-m buoy. Photo from AXYS Technologies

Workflow: Framework Development



- Start with the ideal measurement case



- Consider factors that cause deviations from the ideal case



- Identify the physical basis of these effects



- Determine how the lidar sees these effects



- Identify proxies for these effects

Workflow: Framework Development

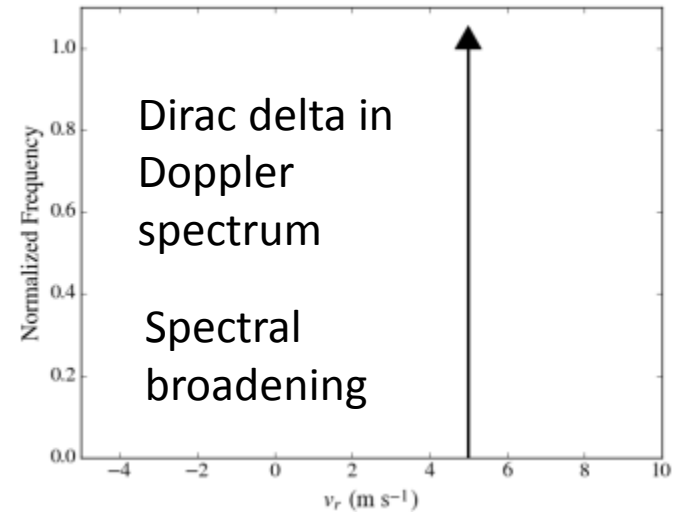
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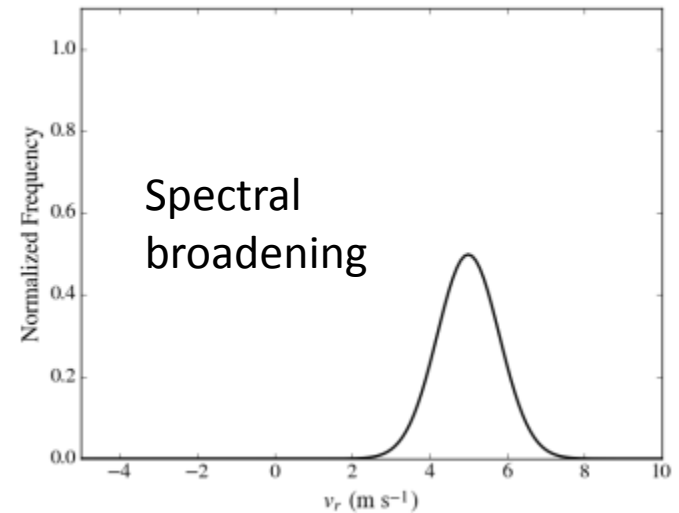
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- Identify proxies for these effects



Workflow: Framework Development

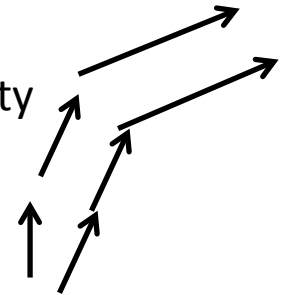
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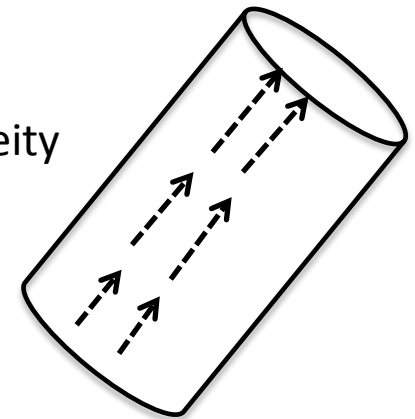
Heterogeneity
in wind field



Workflow: Framework Development

- Start with the ideal measurement case
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Heterogeneity
along LOS
direction



Workflow: Framework Development

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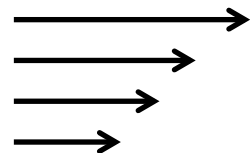
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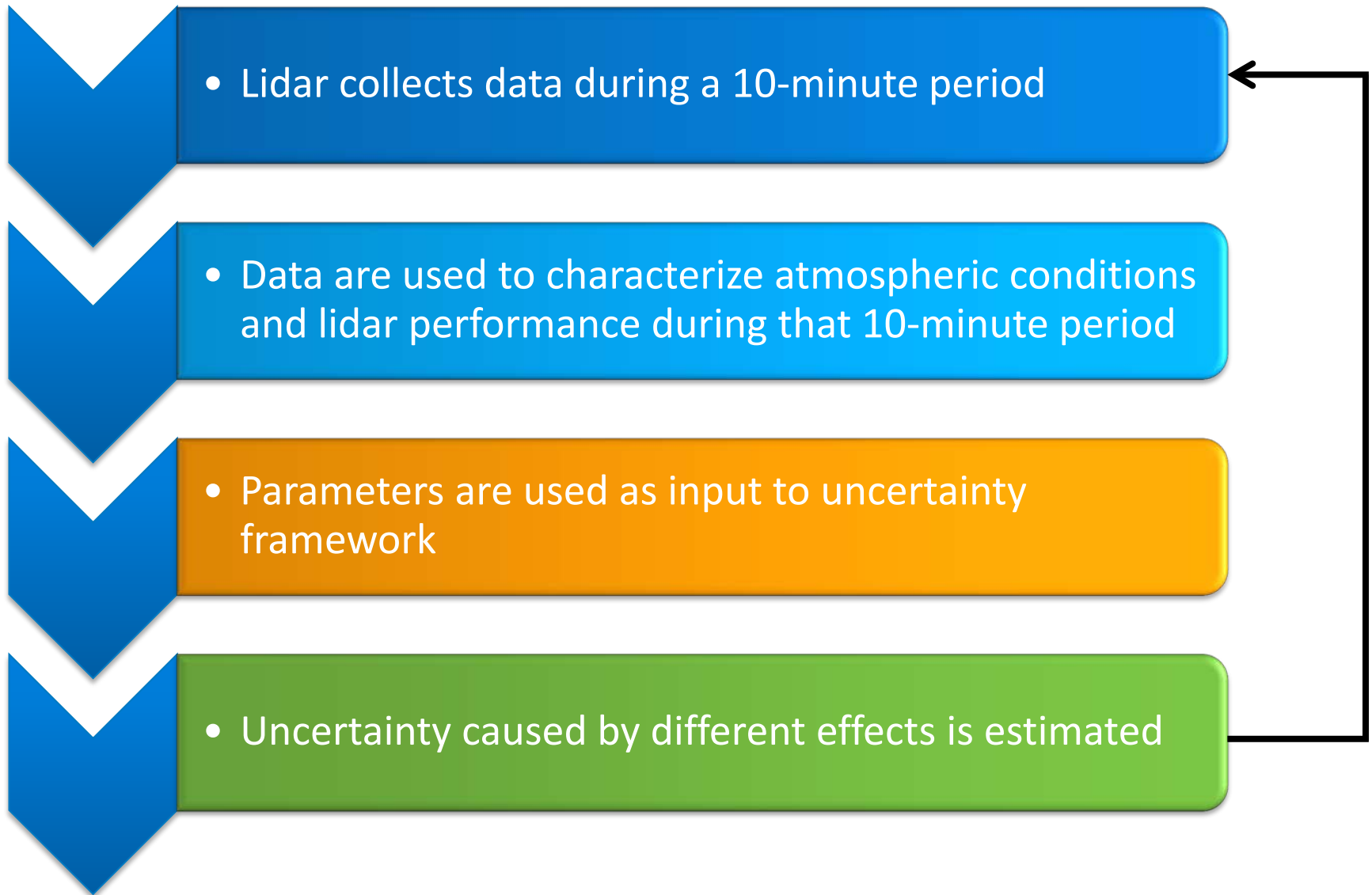
- Determine how the lidar sees these effects

- Identify proxies for these effects

Lidar measurements
of vertical wind
shear



Workflow: Framework Application



How to Move Beyond Climatic Uncertainty Values

Develop an Uncertainty Model

- “White box” uncertainty models for every 10-min. measurement for LOS and windfield reconstruction
 - Use knowledge of lidar measurement process
 - Use physics first, then correlations from observations, then informed estimates
- Include random “noise” as well (unresolved physics)
- **Need a low-uncertainty reference, not just a cup on a tower.**

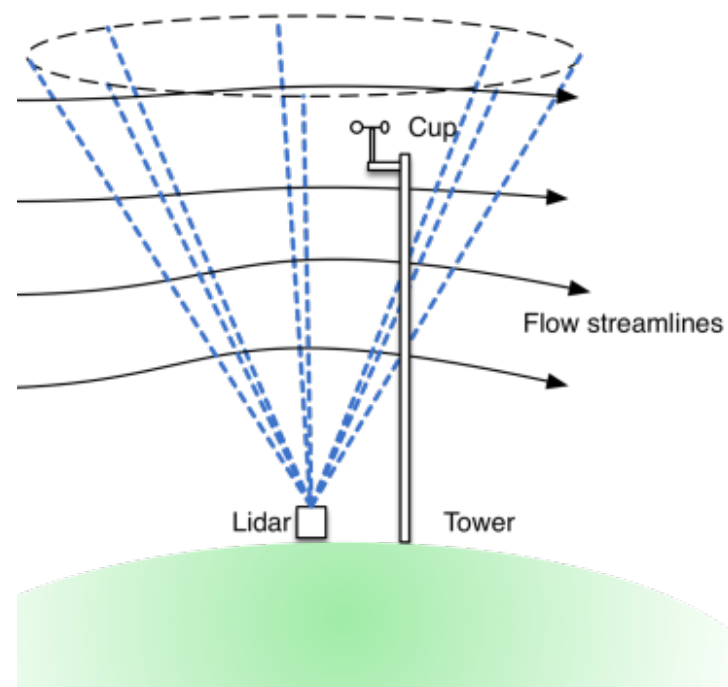
Questions and comments to:

Jennifer Newman, jennifer.newman@nrel.gov

Andrew Clifton, andrew.clifton@nrel.gov

Apply the Model

- No extra data required (based on measurements made by the lidar)
- Calculated online or afterward.



Let's talk!

andrew.clifton@nrel.gov

+1 303 513 0095

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A multimegawatt wind turbine and 1-megawatt photovoltaic field at the National Wind Technology Center at the National Renewable Energy Laboratory. *Image by Dennis Schroeder, NREL*