

Machine Learning-Based Security Assessment and Control for Bulk Electric System Operation

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Background

Traditional power grid \rightarrow Future power grid





Uncertainty and variability

Stochastics



Vulnerability



Low inertia and weak grid

Challenges

There is a need for real-time dynamic security assessment and situational awareness for the future power grid with high renewable energy penetrations.



Key question: How do we solve the trade-off between computational accuracy and speed?

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Building the Machine Learning Model for Security Assessment

Step 1: Representation:

- What to learn?
- What's the input? What's the output?

Step 2: Feature selection



Step3: Model selection









SVM Deep learning



Α

Stable



B

Unstable

Stability margin

How Do We Define the Stability Margin?

- Transient stability (critical clearing time [CCT]):
 - The ability to maintain synchronism when subjected to a severe disturbance, such as a short circuit on a transmission line.
- Frequency stability (frequency nadir):
 - The ability of a power system to maintain steady frequency following a severe system upset, resulting in a significant imbalance between generation and load.
- Small-disturbance rotor angle stability (damping ratio):
 - The ability of the power system to maintain synchronism under small disturbances.



Transient stability



Framework



* For preliminary testing, we use only 1-day dispatch data (288 scenarios for 1 day).

Stability margins:

- Transient stability assessment (CCT <5 cycles, 0.0833 s)
- Small-signal stability assessment (critical damping ratio <5%)
- Frequency stability assessment (frequency nadir <59.6 Hz).

Small Test System



Features:

- Generator dispatch (real power and reactive power)
- Inertia of units
- Unit commitment.

1-day generator dispatch



Training data set:

Scheduling model \rightarrow 288 scenarios with 5-min step over 24 h.

Machine Learning for Transient Stability Assessment



- Machine learning tool can accurately predict CCT.
- Estimation error is less than 20 ms.

Inter-Day Testing: Predict Critical Clearing Time for the Other Day

- Intraday validation: 70% of 288 dispatch scenarios in Day A were used for training, and the remaining 30% were used for validation.
- Inter-day testing: The 288 scenarios in Day B were used in testing.



- The validation and training error levels are very close and small, whereas the testing error levels are large.
- This is most likely because the training data set might be insufficient and not diverse enough for the machine learning model to predict the transient stability in the dispatch scenarios in Day B.

Improvement of Inter-Day Testing for Critical Clearing Time

 To support this hypothesis, a percentage of scenarios were randomly selected from Day B and added to the training data set in Day A. (Random forests)



• With limited additional data, the accuracy can be highly improved.

Summary of Three Security Assessments

• Test system: 18-bus system

Stability	Input	Output	Data Set		Estimation Accuracy	
			Training Data Set	Testing Data Set	Random Forests	Neural Network
Frequency	Generation dispatch results, inertia	Frequency nadir	70% data of Day A	The remaining 30% data of Day A	98.30%	99.72%
			100% data of Day A + 20% data of Day B	80% data of Day B	94.91%	99.37%
Transient	Generation dispatch results, transmission network	ССТ	70% data of Day A	The remaining 30% data of Day A	98.44%	99.29%
			100% data of Day A + 20% data of Day B	80% data of Day B	93.39%	97.38%
Small-Signal	Generation dispatch results, transmission network	Damping ratio +Frequency	70% data of Day A	The remaining 30% data of Day A	98.61%	98.59%
			100% data of Day A + 20% data of Day B	80% data of Day B	91.81%	98.70%

Comparison of Assessment Time

Stabilities	Time for Stability Assessment (86 Scenarios)			
	Simulation	Machine Learning-Based		
Transient stability	~16 h	~0.18 ms (with trained model)		
Frequency stability	~1 h			
Small-signal stability	~1 h			

• The machine learning-based tool can significantly reduce stability assessment time with minimal sacrifice on accuracy.

Frequency Control of Photovoltaic Inverter

- Advanced inverter design can enable photovoltaics (PV) to provide **frequency control**.
- PV needs to be **curtailed** to provide upward response.
- Model-based approach to determine the optimal reserve requirement is **computationally intense**.

Frequency control block





• More headroom leads to better frequency response but might not be economic.

Machine Learning Approach for Reserve Determination

- Offline simulation of different operation conditions (approx. 2,000 cases) of the 60% inverter-based resources Western Electricity Coordinating Council case (10,000 + buses).
- Inputs include system inertia, governor capacity, and targeted frequency nadir.
- Outputs the optimal PV reserve amount.





Validation on Unseen 1-Day Profile

- For each interval, the H_{syst} and G_{gov} as well as the 59.55-Hz target are input to the machine learning model to find the optimal headroom.
- For validation, the GE PSLF (positive-sequence load flow simulation) using the optimal headroom is performed, and the actual f_{nadir} is found.
- 40% headroom is saved compared with flat requirement.
- The prediction error is within 0.01 Hz.





Optimal headroom reserve







Conclusion

- The proposed machine learning tool is used to assess three stability metrics of the 18-bus test system using steady-state dispatch results.
 - Transient stability: CCT
 - Frequency stability: frequency nadir
 - Small-signal stability: damping ratio of oscillation mode.
- The proposed machine learning strategy can determine the optimal PV headroom reserve of an interconnection-level system for frequency control.
- It is demonstrated that machine learning-based tools can reduce the computational burden of dynamic simulations, making them suitable for online security assessment and stability control for systems with high penetrations of renewable generation.

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