



Project ID# ELT204

Charging Infrastructure Technologies: Development of a Multiport, >1 MW Charging System for Medium- and Heavy-Duty Electric Vehicles

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DOE Vehicle Technologies Program
2021 Annual Merit Review and Peer Evaluation Meeting

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Overview

Timeline

- Project start date: October 2018
- Project end date: December 2021
- Percent complete: 83%

Budget

- Total project funding: \$ 7.0 M
- DOE Share: \$ 7.0 M
- Contractor Share: \$ 0
- Fiscal Year 2020 Funding: \$ 2.0 M
- Fiscal Year 2021 Funding: \$ 2.0 M

Barriers Addressed

- Integration of Medium Duty (MD) and Heavy Duty (HD) vehicle charging loads consistent with smart grid operation
- Power conversion topologies, electronics, and connectors for megawatt charging.
- A need to develop and enable reduced costs for electric charging infrastructure.
- Developing new control analytics for MD/HD vehicle charge control

Partners

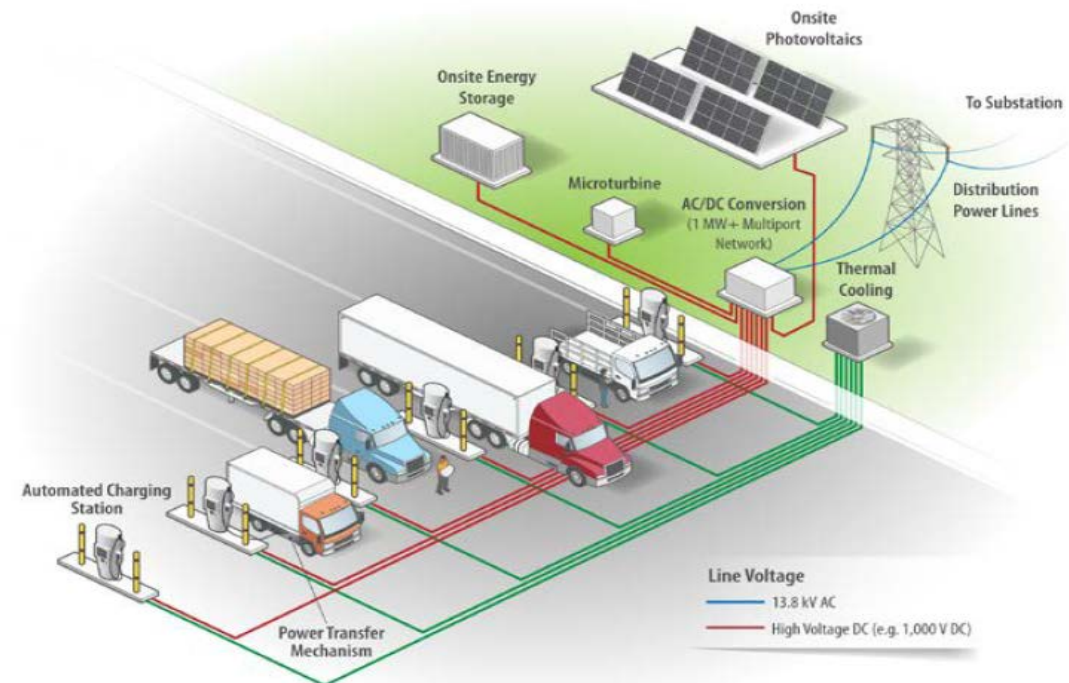
- Oak Ridge National Laboratory (ORNL)
- Argonne National Laboratory (ANL)
- National Renewable Energy Lab (NREL)

Relevance

This project will: develop research tools for a framework to design, optimize, and demonstrate key components of a multi-port 1+ MW medium-voltage connected charging system.

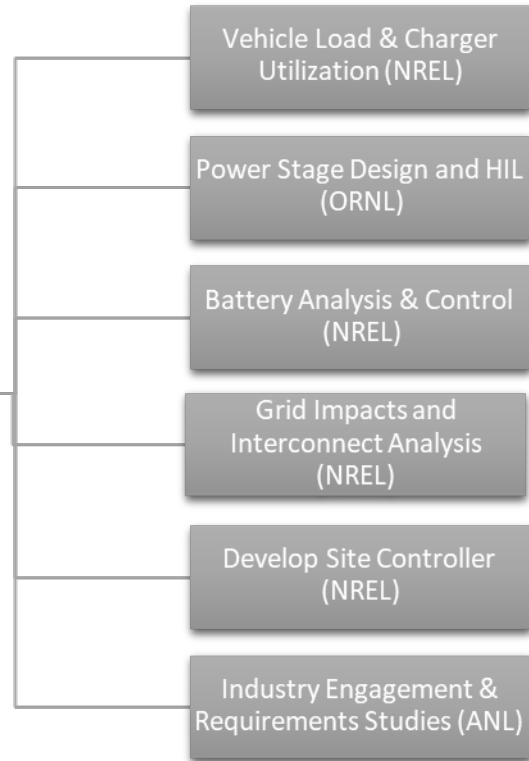
Objective(s): Develop strategies and technologies for multi-port 1+ MW grid-connected stations to recharge MD/HD electric vehicles at fast-charging travel plazas or at fleet depots; through:

- Industry Engagement
- Charging station utilization and load analysis
- Grid impacts and interconnection analysis
- Detailed power electronics component design and controller demonstration
- Site and battery charge control design and controller demonstration
- Charging connector design



Resources

Three Lab Approach



NREL Team:

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ORNL Team:

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Brian Rowden
Madhu Chinthavali
Rafal Wojda
Shilpa Marti
Aswad Adib

Total Funding:
\$7M over 3 years

NREL: \$3M (\$1M/yr)
ORNL: \$3M (\$1M/yr)
ANL: \$1M (\$0.3M/yr)

HIL: hardware-in-the-loop

Milestones: All Labs

Milestone Name/Description	Deadline	Milestone Type
Quarterly reports on progress of year 1 activities (include tasks 1, 2, 6, 7, 8, 12)	End of Q1, Q2, Q3 FY 19	Quarterly Progress Measures
Complete the simulation and performance analysis of at least one power conversion topology	9/30/2019	Go/No-Go Milestone
Provide Draft Summary Report on Industry Engagement and Charging Requirements for MDHD, EV Transit Bus and DC-as-a-Service	9/30/2019	Annual Milestone
Quarterly reports on progress of year 2 activities (include tasks 3, 4, 5, 8, 9, 10, 12)	End of Q1, Q2, Q3 FY20	Quarterly Progress Measures
Battery modeling grid interface control architecture prototype design for power stage; prototype design for power mechanism	9/29/2020	Go/No-Go Milestone
Quarterly reports on progress of year 3 activities (include tasks 10, 11, 12)	End of Q1, Q2, Q3 FY21	Quarterly Progress Measures
Complete integration of the overall control architecture and virtual 1 MW evaluation platform; verify through control HIL simulation; evaluate power transfer mechanism using prototype hardware	9/29/2021	Quarterly Progress Measures
Prepare journal quality papers to document outcomes	12/31/2021	Annual Milestone

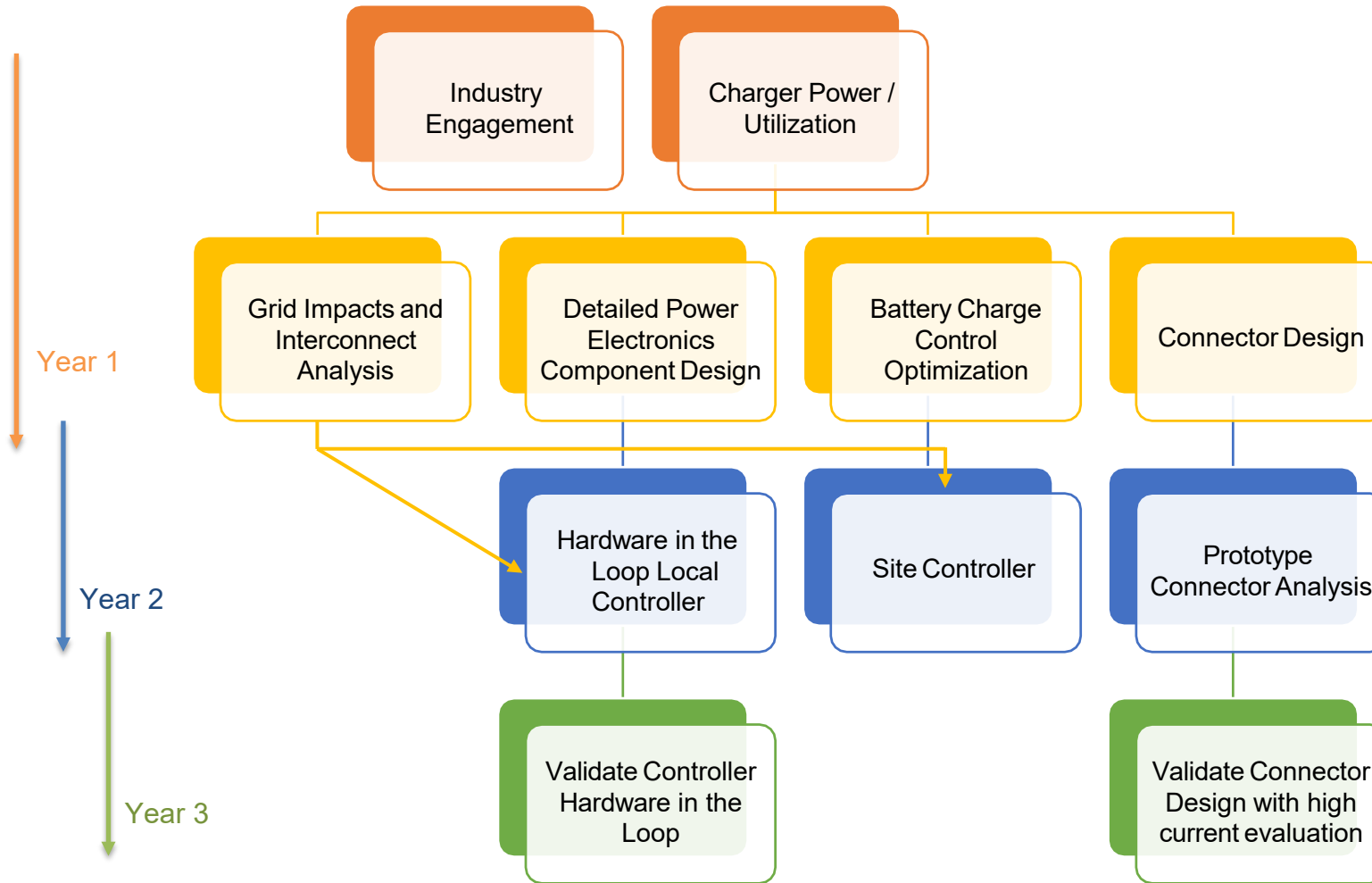
Year 3 Milestones will show:

- 1) Evaluation of vehicle charge connectors
- 2) Development of optimized battery charging algorithms for multi-port charge control
- 3) Site controller development for grid interface and distributed energy resources
- 4) Complete switch-level control and detailed physics-based models for power conversion
- 5) Complete full system controller hardware-in-the-loop evaluation

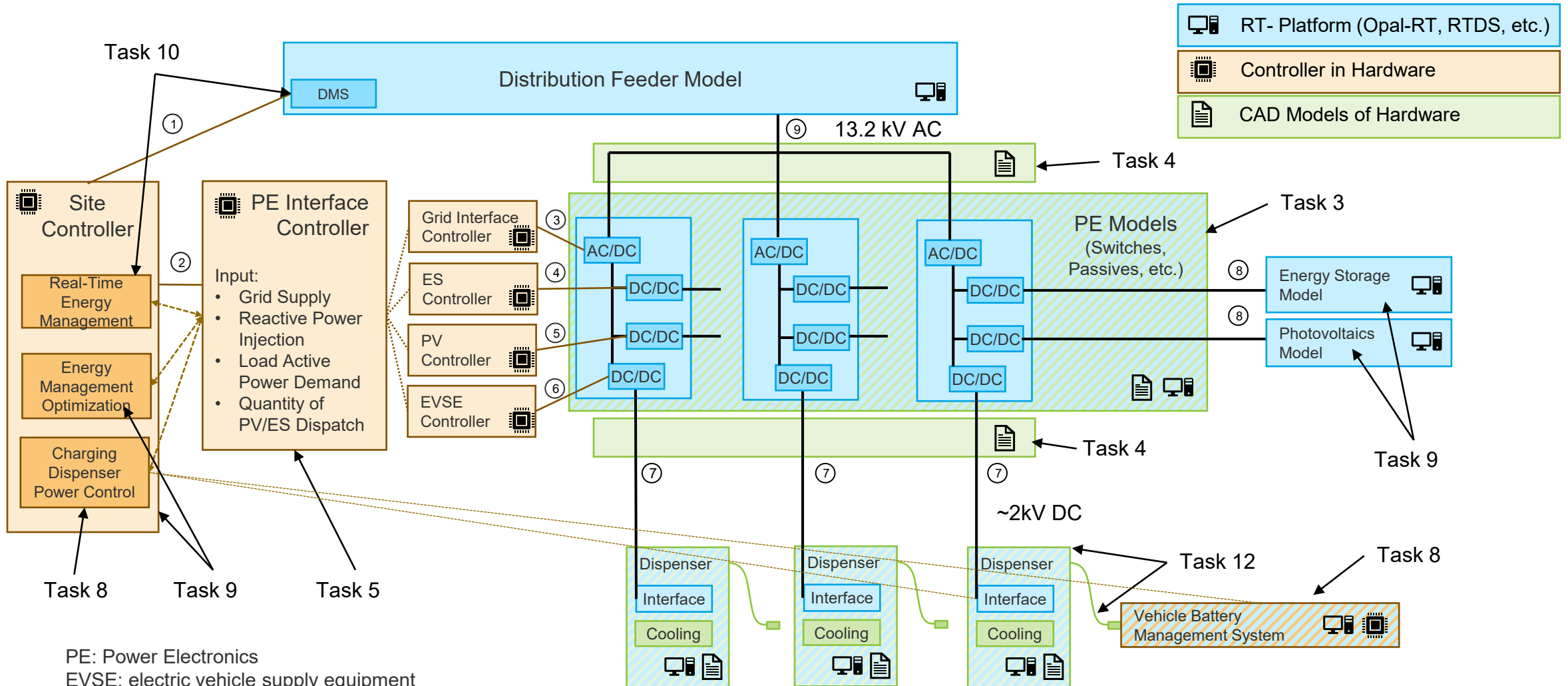
EV: electric vehicle
 DC: direct current
 DCaaS: DC as a Service

PE: power electronics
 FMEA: Failure Modes and Effects Analysis

Approach: Multi-Task, Multi-Year



Approach: Multi-Task, Multi-Year



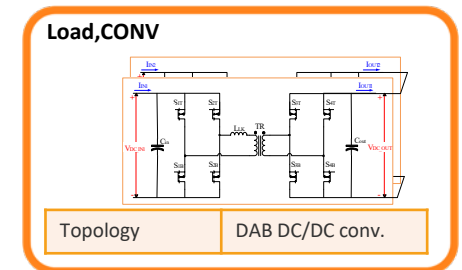
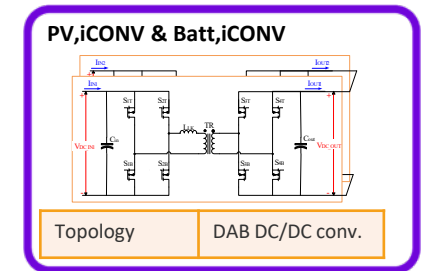
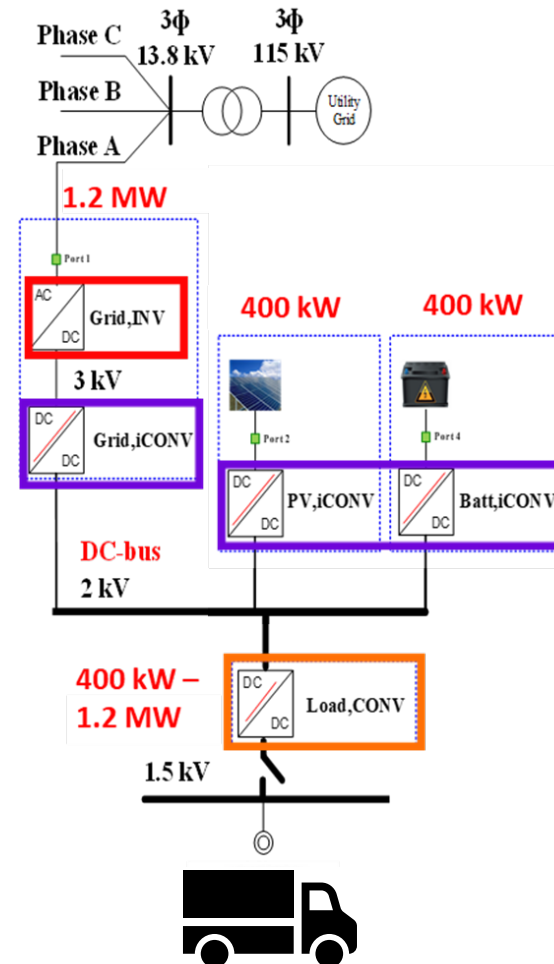
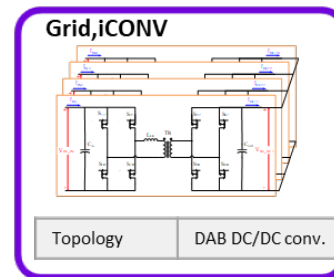
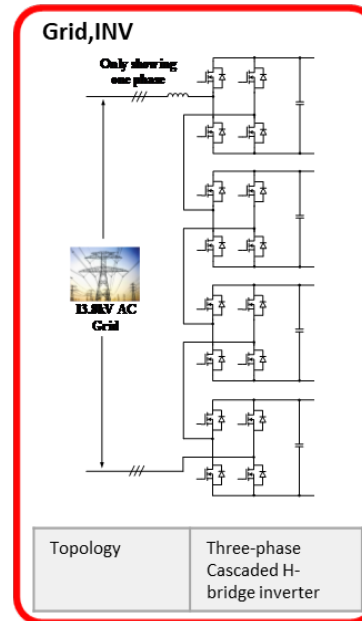
PE: Power Electronics
 EVSE: electric vehicle supply equipment
 ES: energy storage
 PV: photovoltaics
 CAD: Computer aided design

Technical Accomplishments and Progress:

Task 1 / 2 / 3 – PE Topology Review, Simulation, and Selection

PE Models
(Switches,
Passives, etc.)

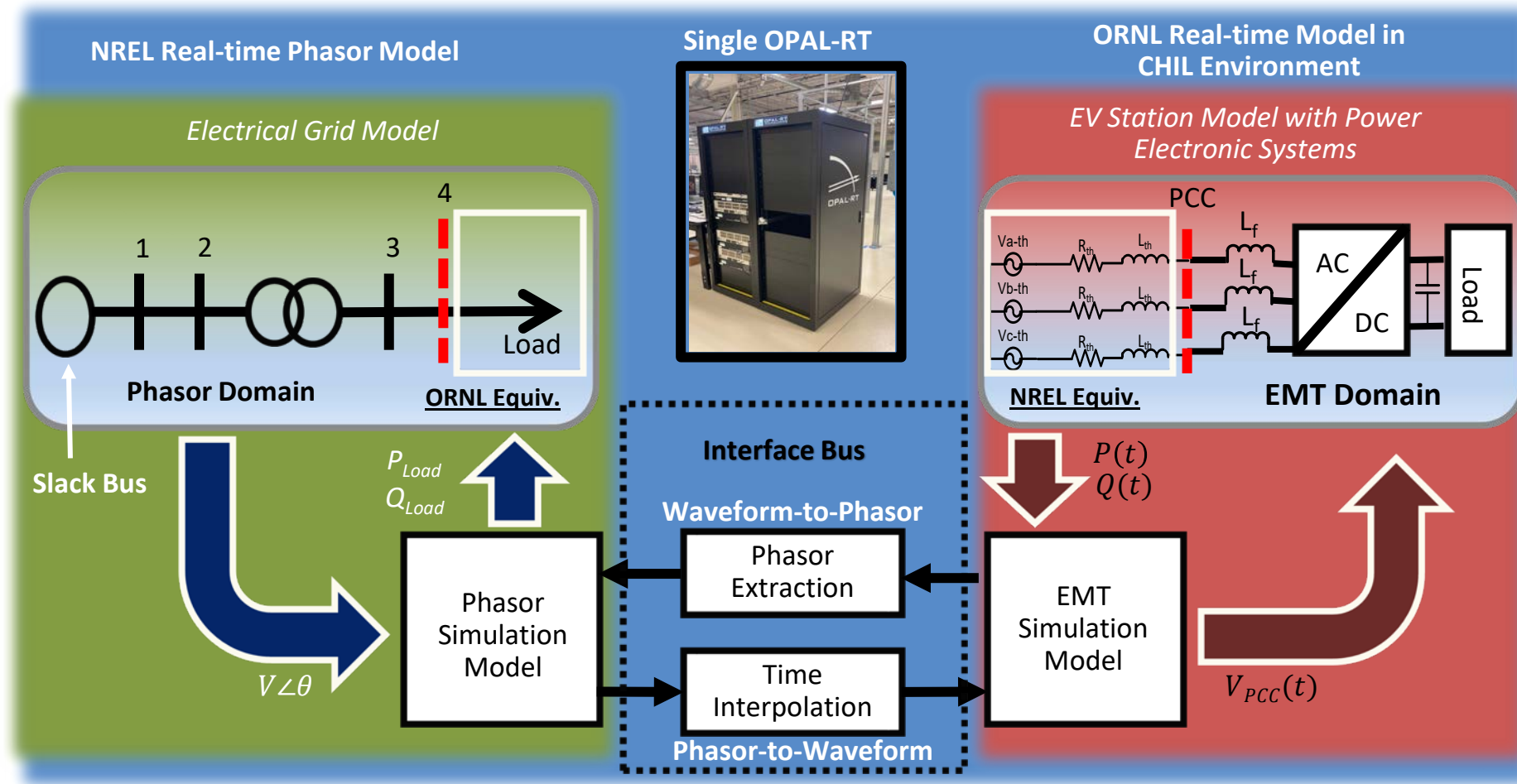
- Detailed MV Architecture investigation
 - Detailed loss values including passives, protection, and interconnects**
 - Translation to thermal management requirements
 - Final device selection**
- MV Gate Drive Test Hardware
 - MV Si/SiC Device level testing providing detailed PE model input**
- Thermal Management
 - Strategy, sizing, and ancillary impact
- Cabinet level AC Grid Connection and Protection
- Cabinet level DC interconnects (DER/Load)
- DC interface to Charge connector



Technical Accomplishments and Progress:

Task 11 – Grid Model Linkage to Real-time Simulation

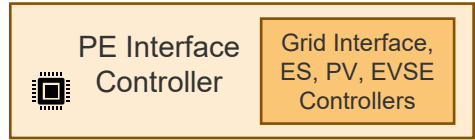
PE Models (Switches, Passives, etc.)



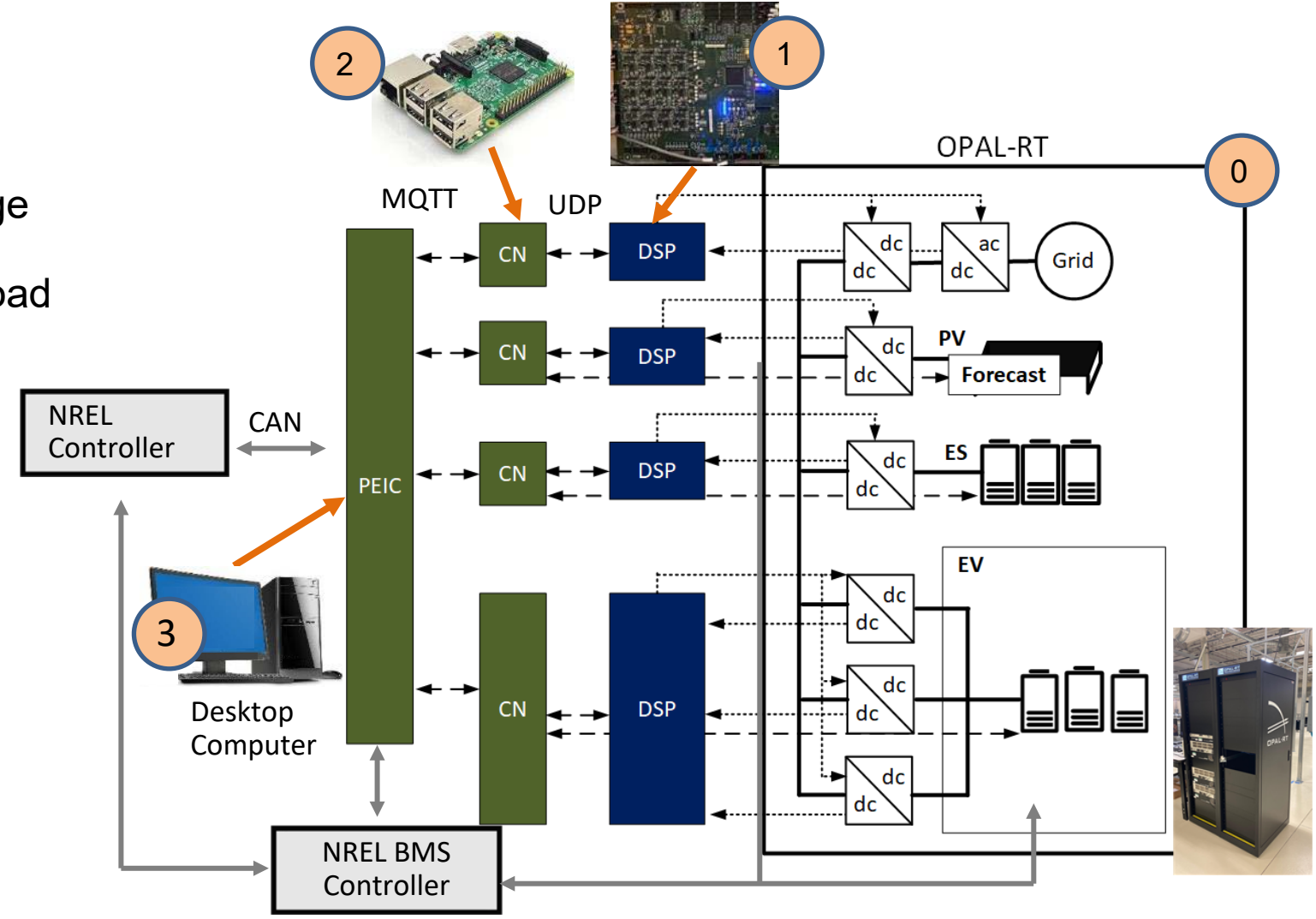
EMT- Electromagnetic Transient

Technical Accomplishments and Progress:

Task 11 – CHIL Demonstration: Controller Hardware Architecture



- 0 **Simulation:**
 - DAB+CHB (3 phase x 4 Converters), 12 converters with DC bus voltage control
 - 2kV DC bus controllable load
- 1 **Controllers:**
 - 1 x ORNL DSP
- 2 **Closed loop control of 12 converters avg model**
 - 1 x Raspberry Pi Full agent systems running
- 3 **Central System:**
 - Desktop Computer Autointegration and CAN communications



CN - Controller Node

Technical Accomplishments and Progress:

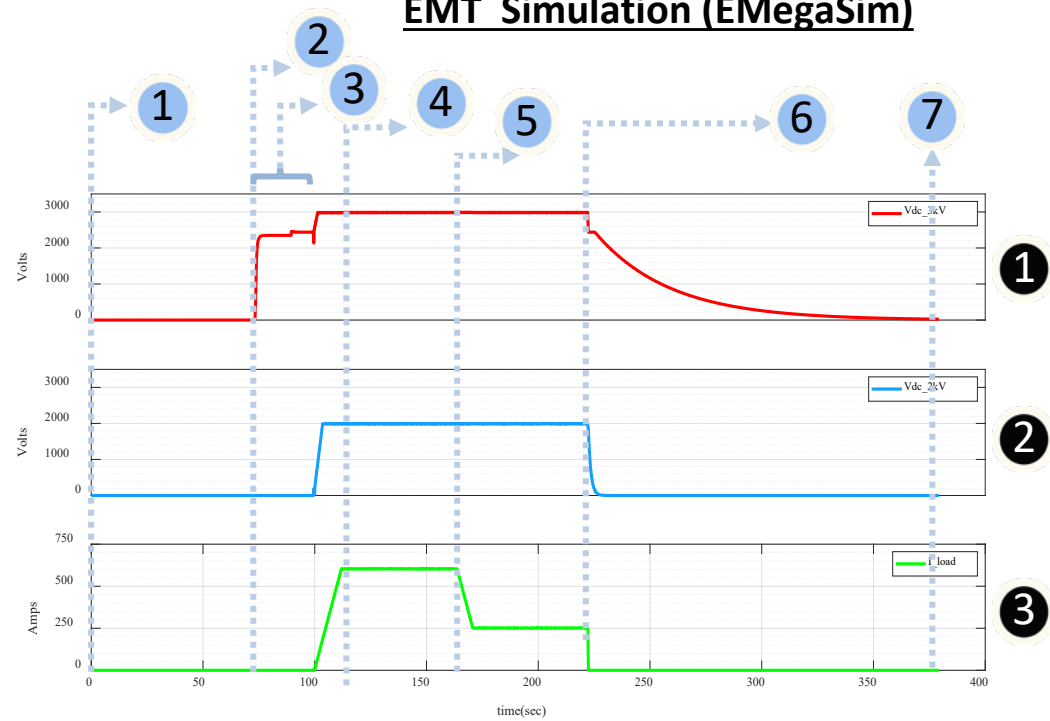
Task 11 – Startup and Shutdown of Resources in Simulation



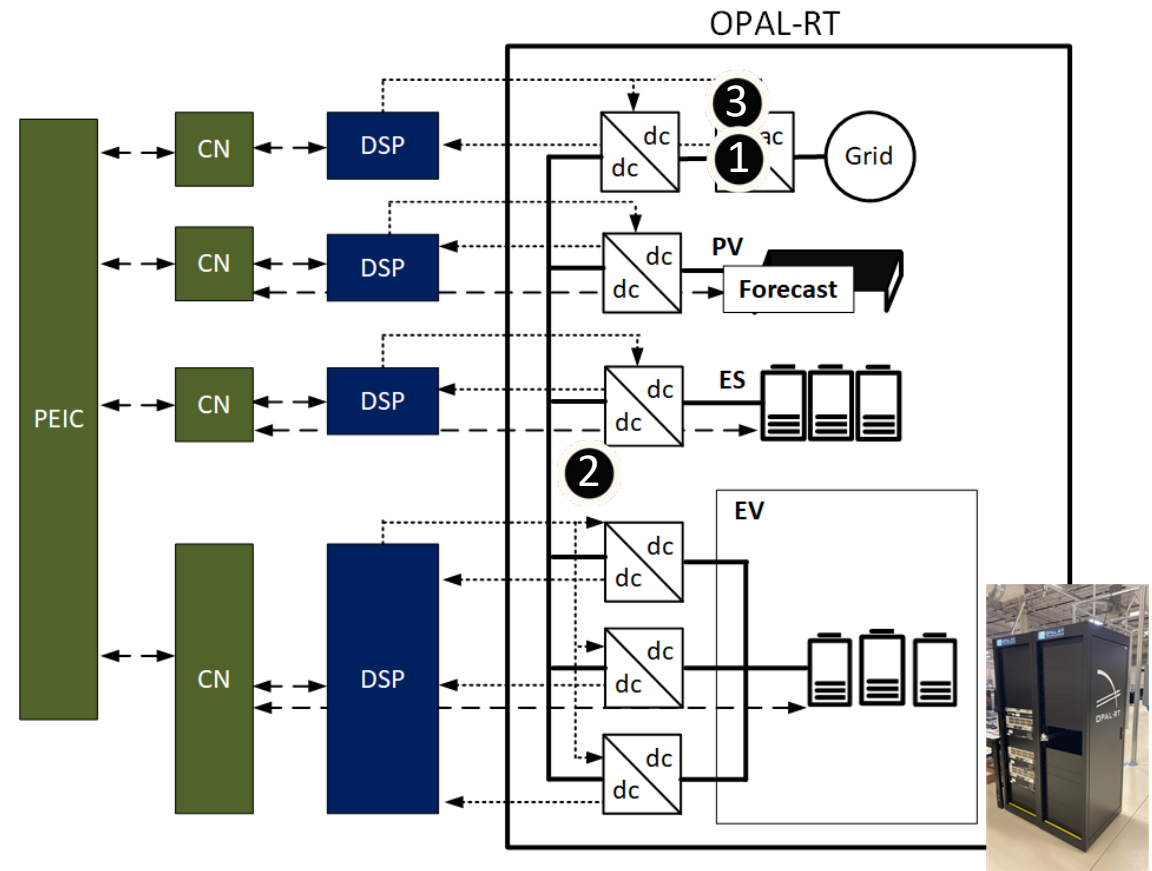
PE Interface
Controller

Grid Interface,
ES, PV, EVSE
Controllers

**Model of a single 1+MW port
EMT Simulation (EMegaSim)**



- 1) Start of HIL Simulation
- 2) Start-up Sequence Commenced
- 3) Pre-charging sequence
- 4) Converter start-up complete
- 5) Load Change from 1.2MW to 500kW
- 6) Shut-down sequence commenced
- 7) HIL Simulation Complete



Technical Accomplishments and Progress:

Task 6 – Site Utilization and Load Profile



- Supporting the 21st Century Truck Partnership to identify charging infrastructure technology targets.
 - Cost of charging from site utilization and equipment requirements
- Linear programming used to define usage vs charge needs in Western Region
- Dataset is from telematics of conventional CL 8 vehicles

Class 8 Tractor Dataset Description

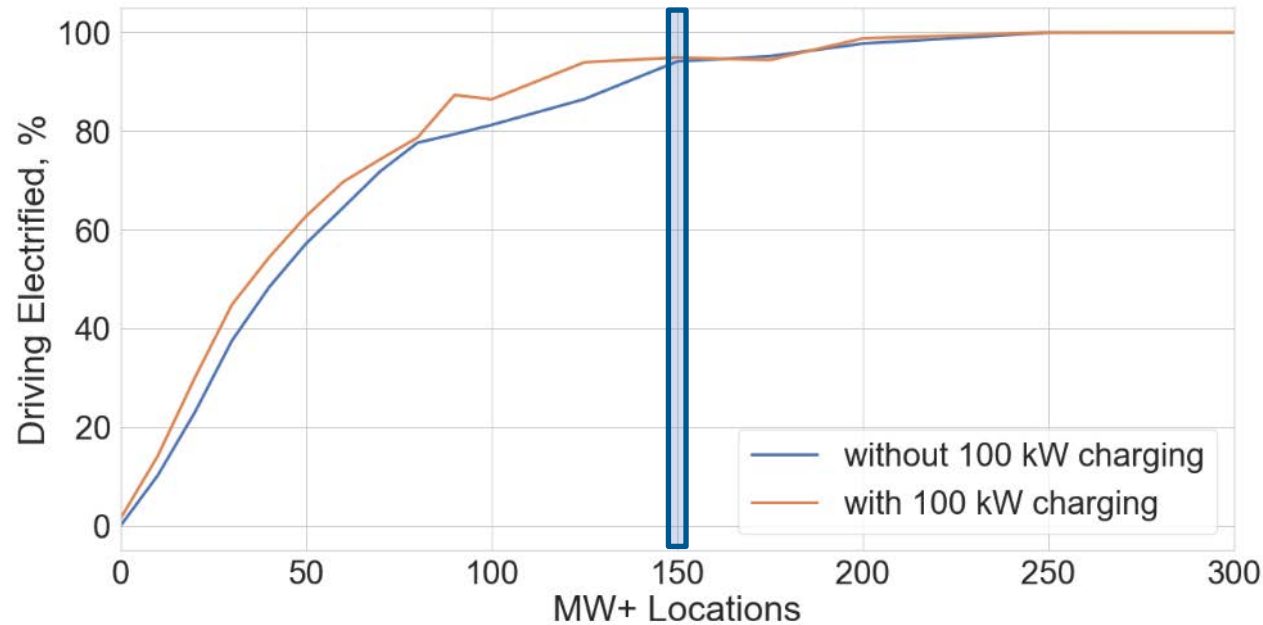
	FAF VMT/day	Dataset VMT/day
All of USA	290M	17.23M
5-state region	31.35M	2.16M
5-state exclusive	-	0.716M



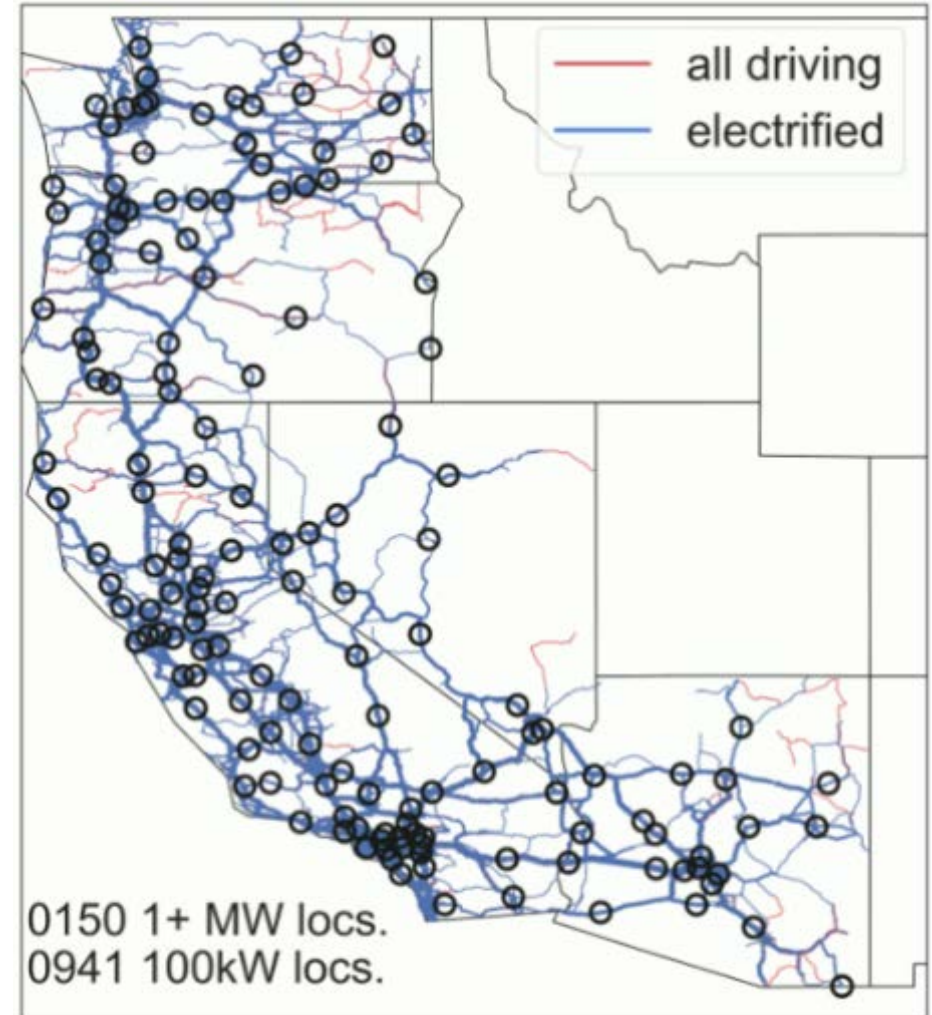
5-state exclusive uses data from trucks which did 100% of their driving in AZ, CA, NV, OR, and WA.
10 to 12 M VMT/day estimated for FAF in 5-state exclusive zone.

Technical Accomplishments and Progress:

Task 6 –Site Utilization and Load Profile

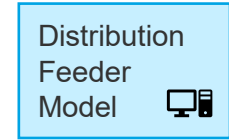


- 1+MW Charging Infrastructure is the primary driver of vehicle electrification.
- California's major cities and shipping corridors are electrified first due to traffic density.



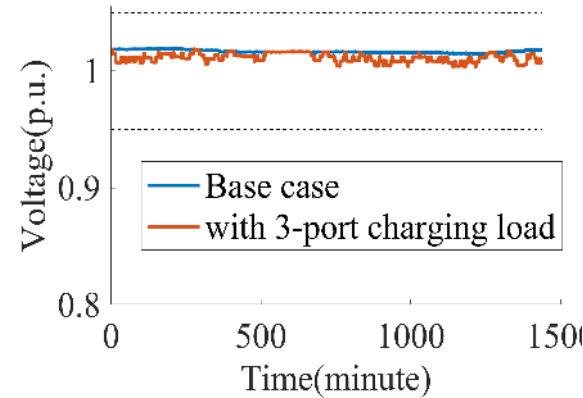
Technical Accomplishments and Progress:

Task 7 – Grid Impacts Analysis

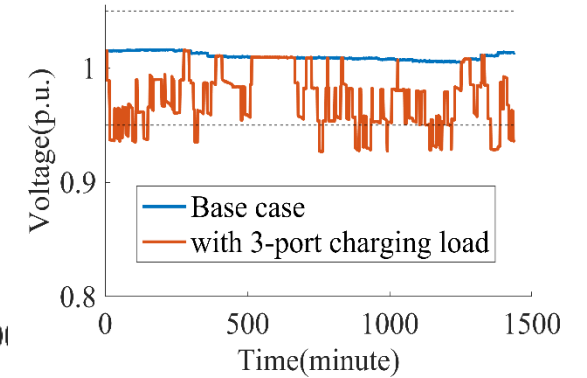


- Best location
- Good location
- Worst location

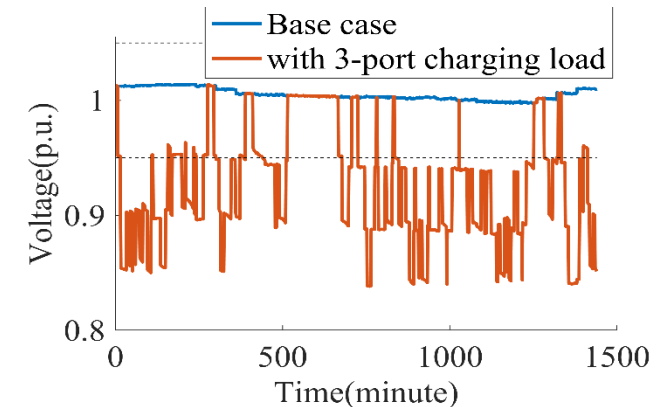
One day voltage profile on selected best location



One day voltage profile on selected good location



One day voltage profile on selected worst location




- ✓ Voltage sensitivity analysis ^[1] to determine best- and worst-case areas for HD charging stations
- ✓ Four representative distribution systems including different single-feeder cases and multi-feeder cases have been selected for grid impact analysis
- ✓ Impact mitigation solutions have been developed using onsite PV and ES and reactive power support from charger

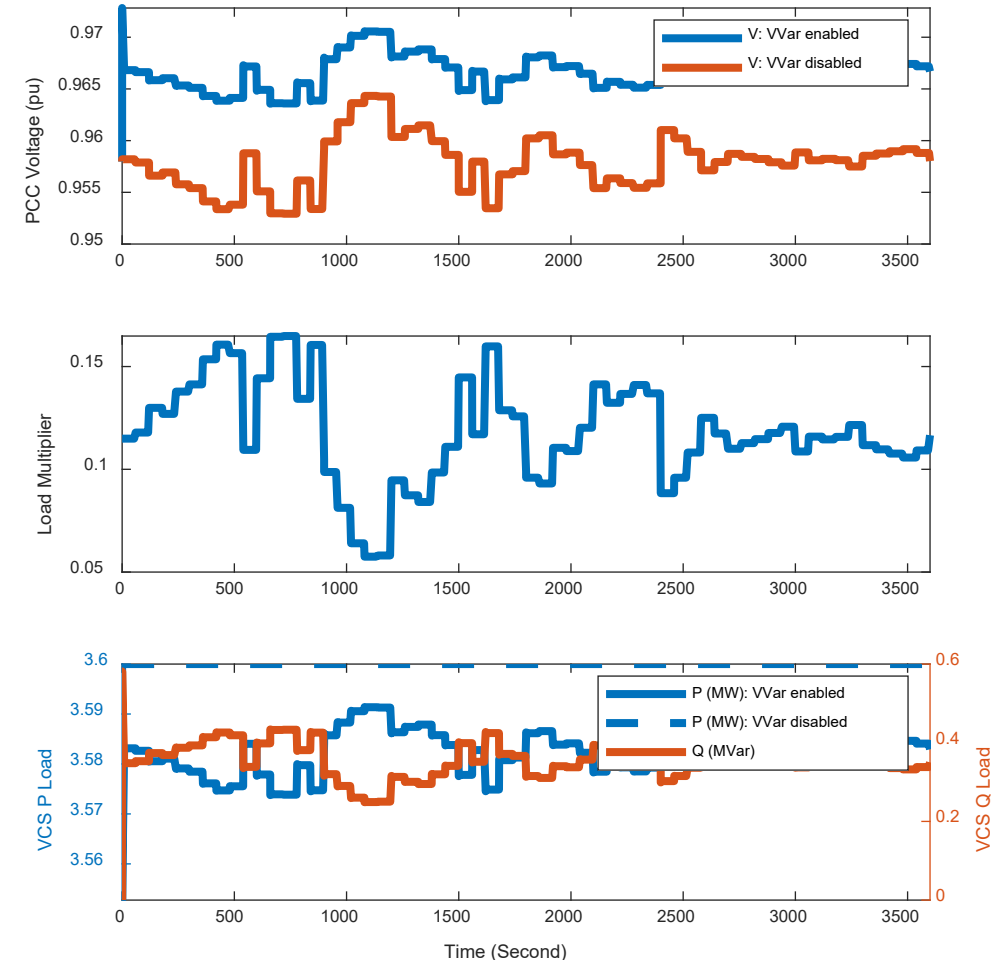
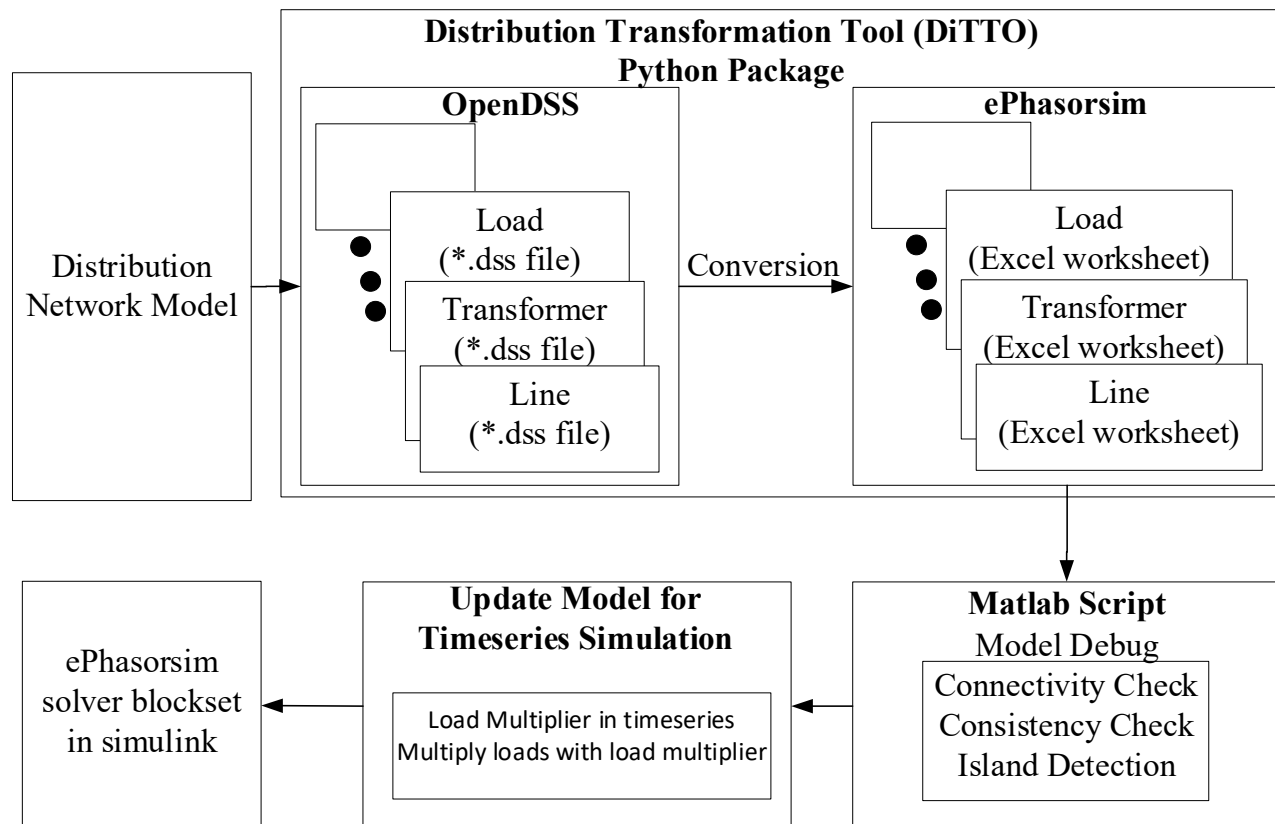
[1] Xiangqi Zhu, Barry Mather and Partha Mishra, "Grid Impact Analysis of Heavy-Duty Electric Vehicle Charging Stations", Proc. of 2020 Conference on Innovative Smart Grid Technologies (ISGT), 2020 IEEE

Technical Accomplishments and Progress:

Task 7/10 – RT-EMS and Dist. Network Real-Time Simulation

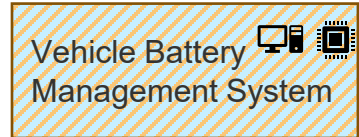
Distribution Feeder Model 

A Model conversion process, from OpenDSS to ePhasorSim, for real-time simulation

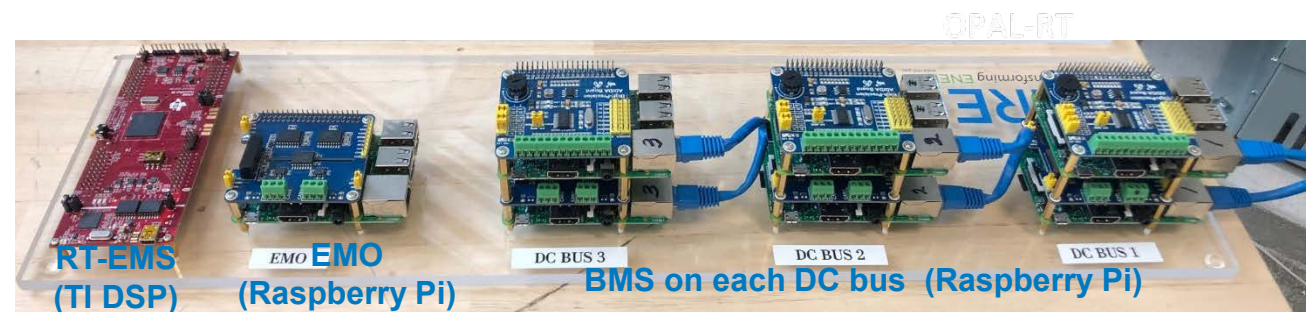
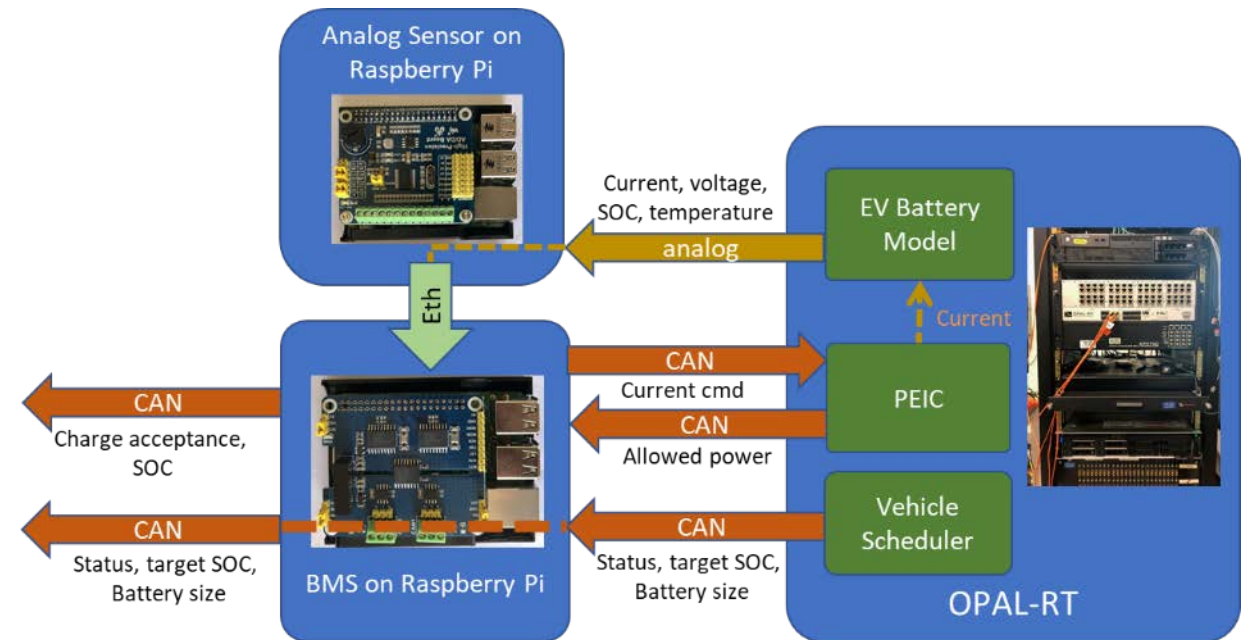


Technical Accomplishments and Progress:

Task 8 – Battery Load Profile and Optimal Charge Control



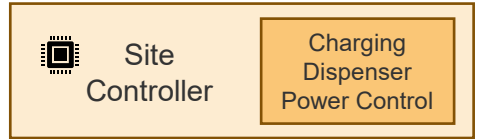
- **Objective** of Battery Charging emulation:
 - (a) Implement battery management system's (BMS) charging algorithm using real-time hardware,
 - (b) Demonstrate adaptivity of BMS charging algorithm in response to change of reference setpoint from site controller
- **Algorithm:** Model predictive control (MPC) framework using electrochemical-thermal models of Lithium-ion battery
- **Real-time hardware:** algorithm resides on a raspberry pi, acting as the BMS



Embedded Controllers for Site Controller and Vehicle BMSs

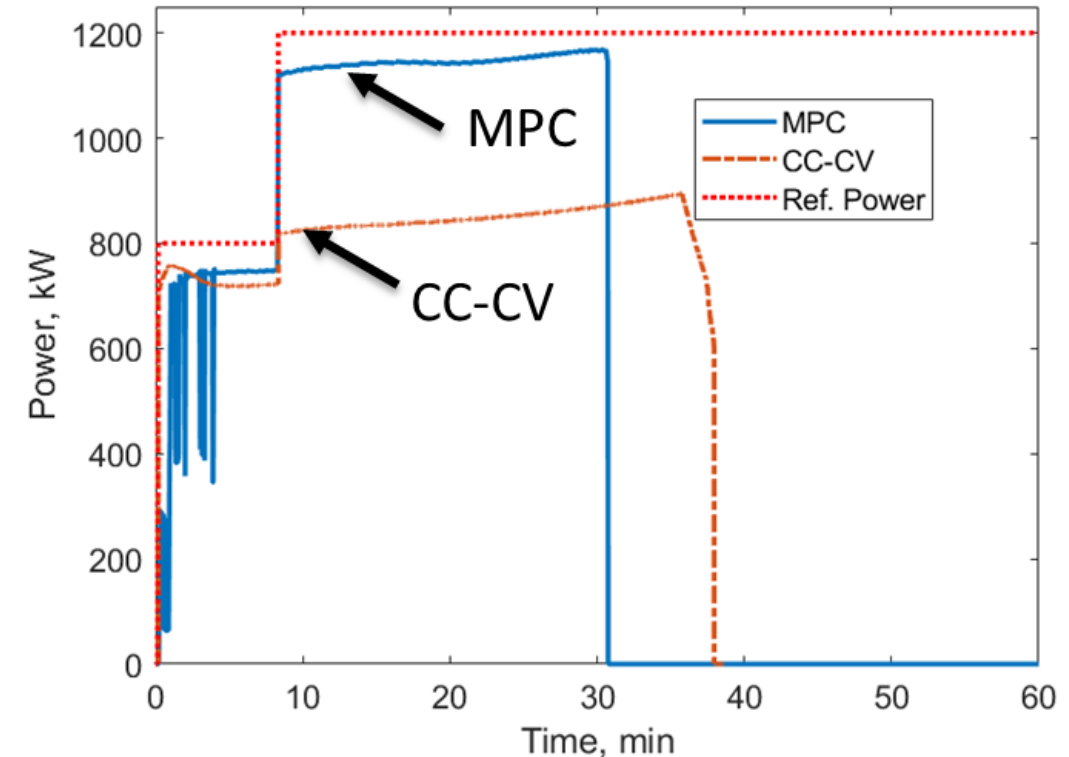
Technical Accomplishments and Progress:

Task 8 – Battery Load Profile and Optimal Charge Control



Coordination between the Site Controller (EMO, RT-EMS) and the BMS of each vehicle

- **EMO optimizes the allotment of power setpoints** for every controllable load and energy source for the station
 - A critical input to the EMO is the battery's forecasted charging power outlook over a time horizon
 - This horizon is used to plan the charging across multiple charging ports, and DER at the site
- **BMS optimizes the charging current** using an MPC-based control algorithm such that the vehicle is charged as fast as possible while satisfying all operational constraint
- These results show that the BMS adjusts battery charge current command based on EMO reference power setpoints
- When compared with a conservatively designed CC-CV algorithm for the same power curtailment the MPC takes advantage of increased charging power allocation

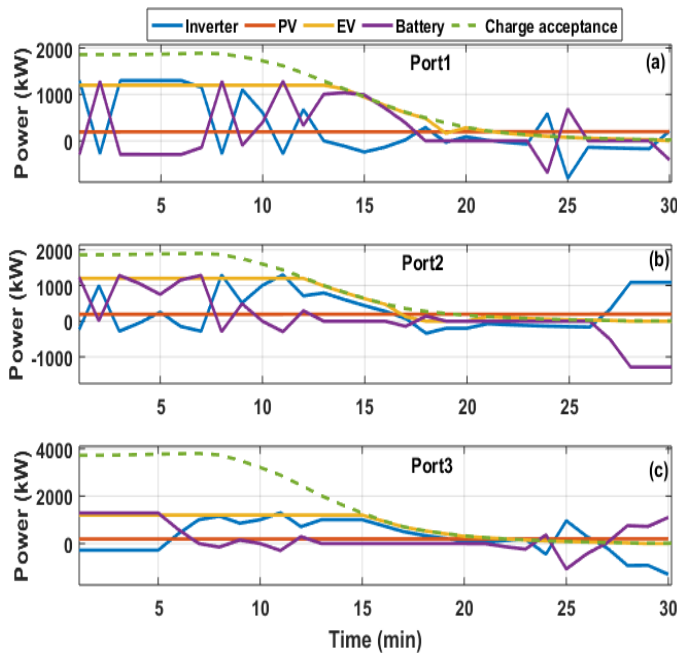
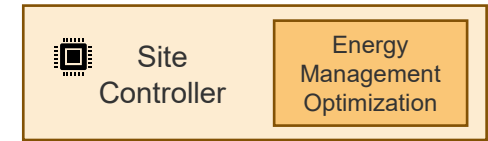


Comparison of CC-CV and MPC BMS response to EMO load curtailment

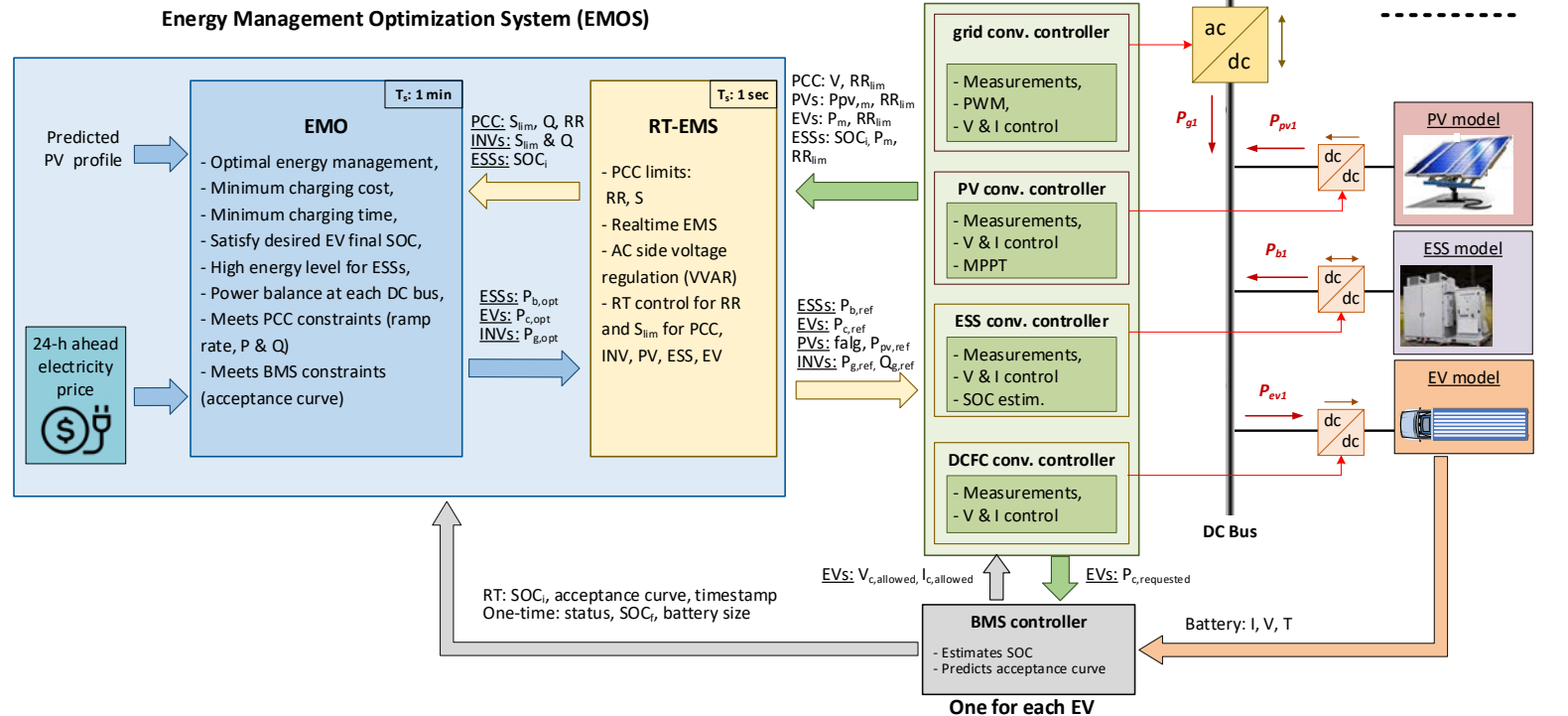
Technical Accomplishments and Progress:

Task 10 – Energy Management Optimization

- Site controller is a **bi-level real-time energy management system that manages operation** of EV charging and PV(s); and dispatches ESS(s).
- It incorporates an energy management optimization (EMO) and a real-time energy management system (RT-EMS)

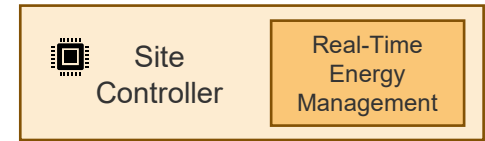


30-minute EMO results for three-port station

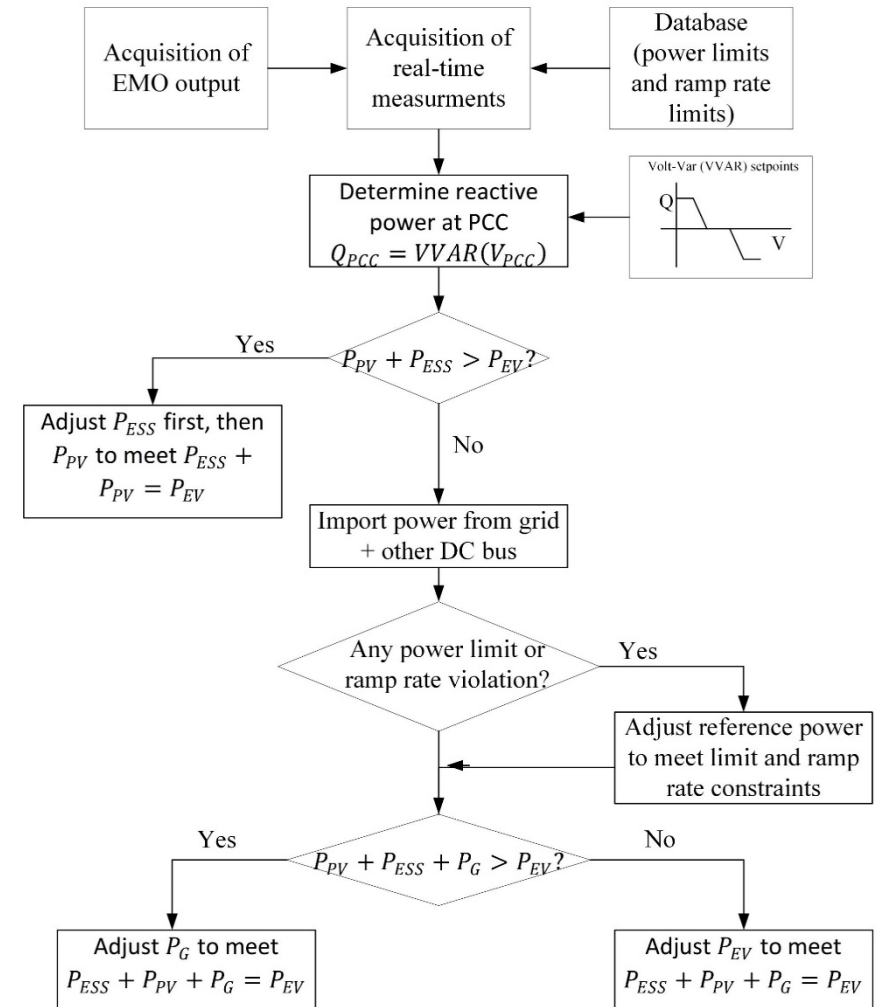
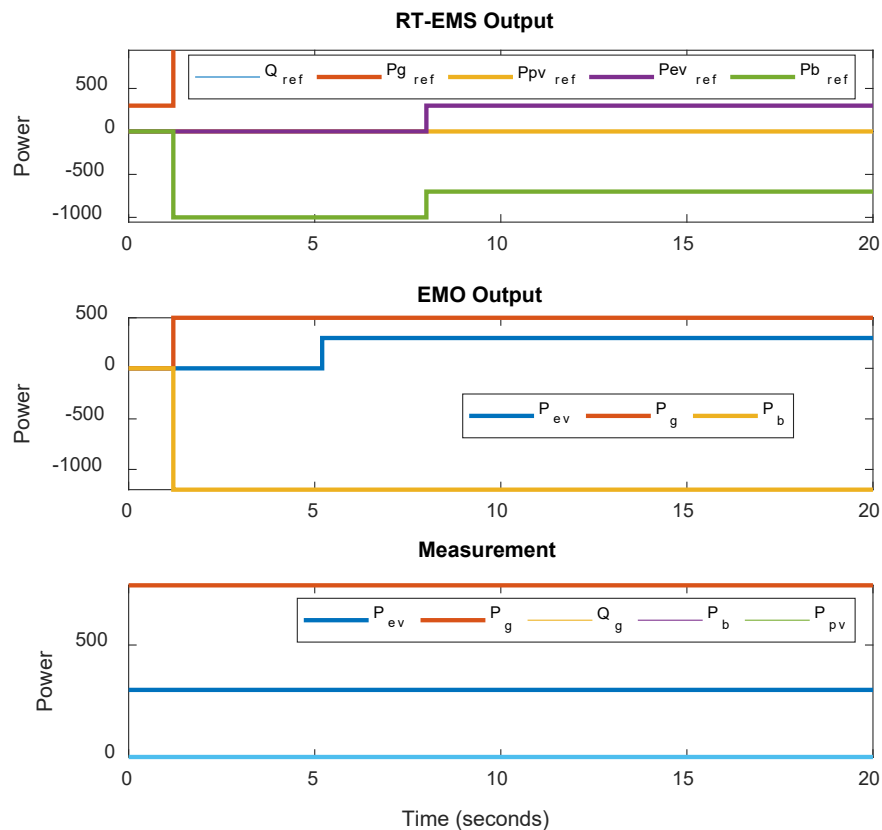


Technical Accomplishments and Progress:

Task 10 – RT-EMS

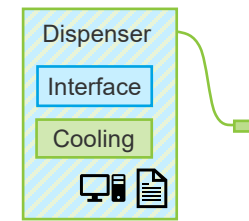


- RT-EMS adjusts the optimum control actions to compensate for fast disturbances:
 - Supports AC voltage using Volt-VAR method
 - Regulates site power within ramp-rate limits



Technical Accomplishments and Progress:

Task 12 – Design and Thermal Management of 1+MW Connector



- Supporting the CharIN Megawatt Charging System (MCS) Task Force to evaluate performance of prototype connector hardware from industry partners
 - Developed approach to support four levels of evaluations
 - Level 0: Unpowered fit and ergonomics / mechanical strength
 - Level 1: Powered without cooling up to 350 A
 - Level 2: Powered with connector cooling up to 1000 A
 - Level 3: Powered with connector and inlet cooling up to 3000A
 - Developed draft hardware specification setup and shared with MCS task force members and industry partners
 - Developed experiment hardware designs for each evaluation level
- The first evaluation event was completed in Fall 2020 and results disseminated to the taskforce
- A second event planned for Summer 2021 (June/July) will support mechanical and further fit and thermal evaluation to support design results to support a standardization effort.



Thermal Evaluation



Fit and Ergonomics Evaluation

Technical Accomplishments and Progress:

Task 13 / 14 / 15 – Industry Engagement and Recommendations

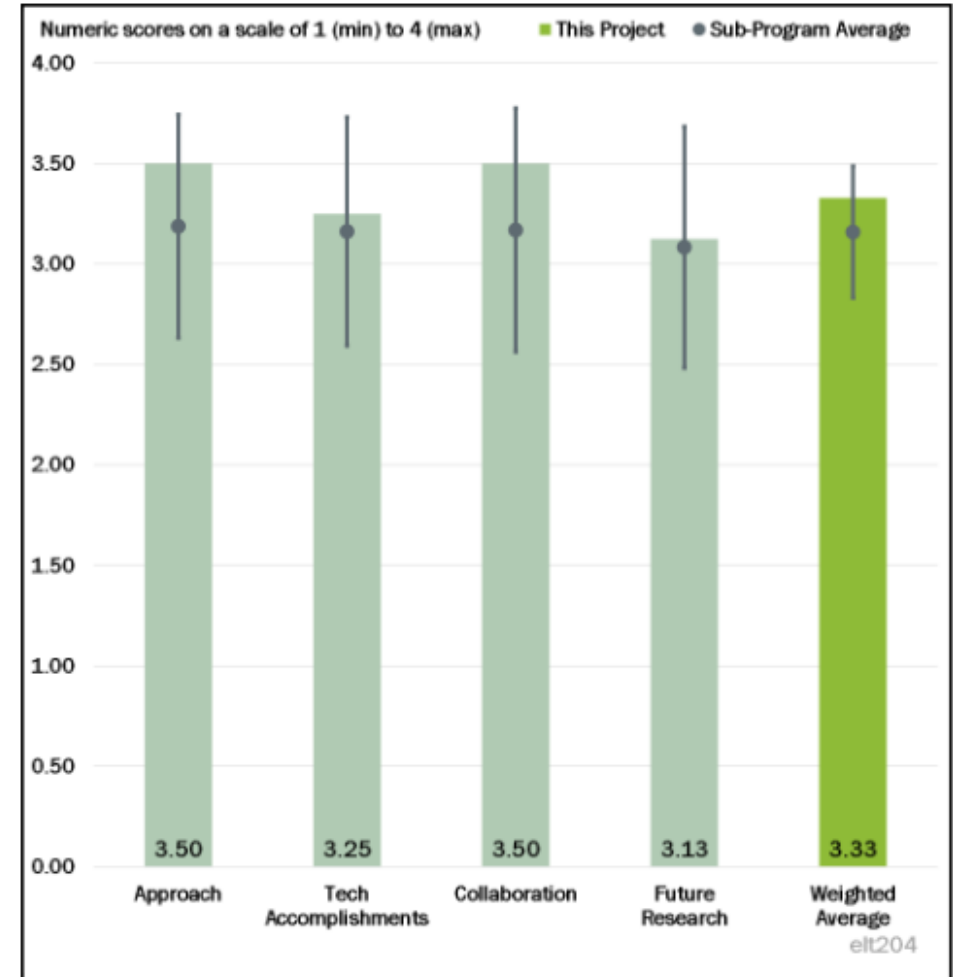
- MD/HD truck-bus charging and DC as a Service distribution Topics:
 - Year 1: collect requirements from industry input; generate summary
 - Year 2: discuss case studies, develop use cases/test cases, test bed capabilities
 - Year 3: perform 3000A cable testing, communication signal testing, monthly meetings
- Sept. 2020 workshop hosted with mini-panel discussion by stakeholders from the ~450 member industry engagement group covering sub-transmission utility inter-connection to battery terminal charging pathway in megawatt level multiport charging systems.
- FY19-20 version of **gap analysis report "Industry Engagement Insights into MD/HD EV MW+ Charging systems"** updated in FY21 with case studies and subsystem benchmark testing examples in support of the CharIN Megawatt Charging Standard (MCS).
- Successfully tested 3000A liquid cooled charging cables (without coupler) for losses and stability in tandem with physical layer communication interference testing. This testing is in support of interoperability within the weekly CharIN MCS safety and communication subcommittee meetings with industry subject matter experts.



Responses to Previous Year Reviewer's Comments

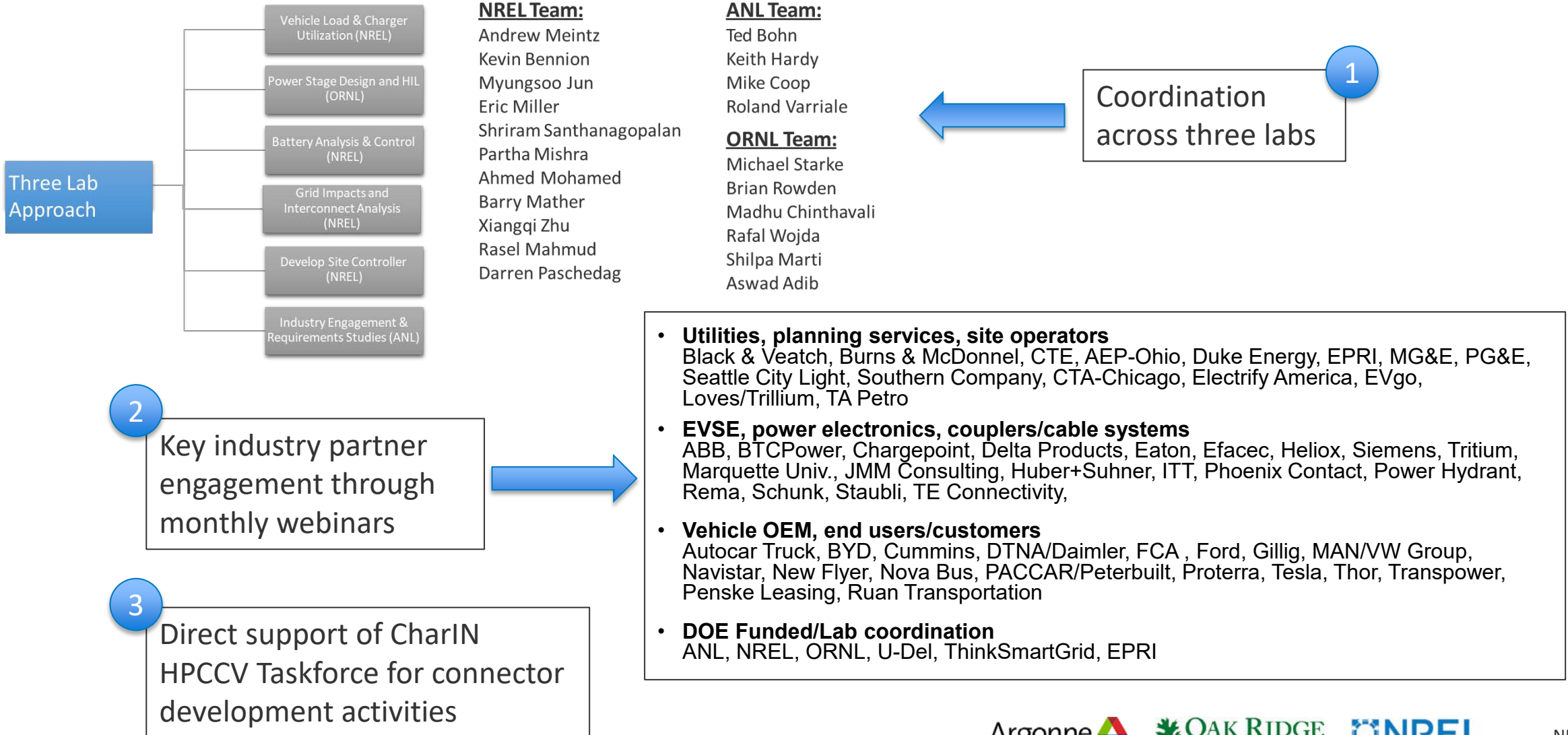
Two concerns raised at the last AMR:

- *... how much scale can actually be achieved in what is being proposed... [as] scaling up to accommodate several vehicles at one time would need to be accounted for while attempting to dispense that much energy. How resilient would that be in the middle of the summer, especially for an air-cooled converter?*
 - Response: We are analyzing a 3-port system to show power balance; however, the grid analysis has shown locations on our feeders with up to 5-ports though this is location dependent. The thermal analysis for the analyzed system is capable up to a 50C environment
- *There should be more discussion regarding which parts of the project will be demonstrated in hardware and how the PI plans to execute the demonstration and evaluate and benchmark the results*
 - Response: The teams evaluation work will be in the controller hardware space with detailed models of the power electronics and the grid. Hardware evaluation of the charging connector is part of the CharIN MCS work.



Collaboration and Coordination

Multi-Lab Approach with Multiple Industry Partners



Remaining Challenges and Barriers

- Definition and refinement of 1+MW charging site scenario (distribution feeder and charger utilization) that will drive understanding and R&D
- 1+MW Charging System Emulation Platform
 - Availability and additional characterization of wide-bandgap medium-voltage industrial modules
 - Deployment of site controller optimization algorithm that balances grid interface requirements, onsite energy resources, and battery charging while maintaining real-time performance.

Proposed Future Research

- FY21:
 - Integration of the overall control and virtual 1+ MW multi-port charging system evaluation platform;
 - Verify through control HIL simulation the charging system response to grid disturbances, effectiveness of site control, and grid interface control capability to mitigating grid impact
 - Evaluation of power transfer mechanism using prototype hardware

	Description
Task 10	Evaluate smart control for overall site management in controller HIL environment using plant models for system components to include appropriate response and control
Task 11	Function validation of single multiport MW charging system through controller HIL simulation
Task 12	Perform analysis and modeling to evaluate power transfer mechanisms and develop prototype design for technology validation
Task 13 - 15	Identify standards gaps, perform interoperability testing; collect data for standards

Any proposed future work is subject to change based on funding levels

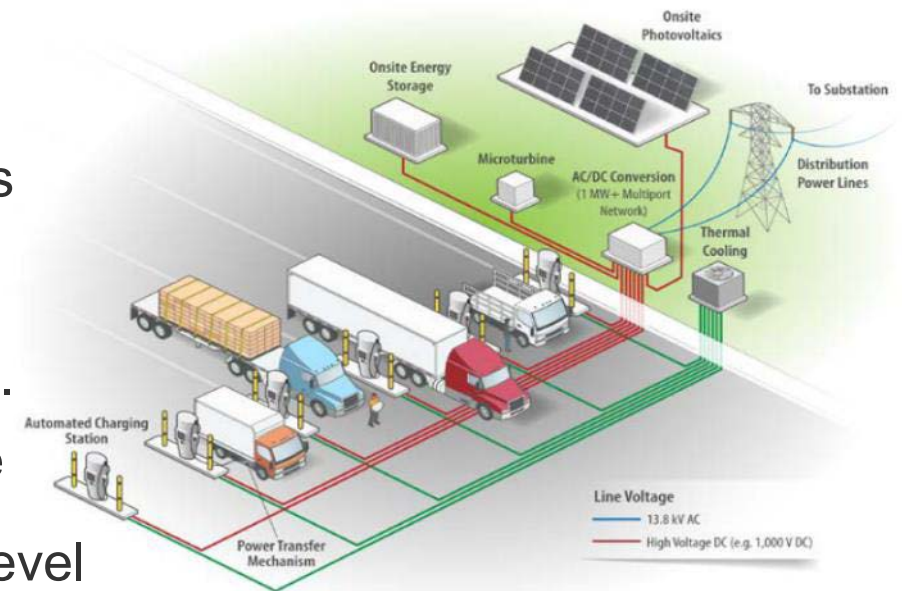
Challenges for Future Research

- Challenges to scaling-up for MW charging
 - Availability of high-voltage, high-current devices for power electronics
 - Switchgear, grid interface devices, interconnection requirements are needed for these multi-MW charging sites to support commonality
 - Circuit protection devices for very fast devices at high current DC for charging system fault protection.
 - There is a need to understand modularity across sites to support the correct balance
 - A common standard for MW charging connectors
- Standards for grid integration for charging systems to address the reactive power support and ramping requirements for non-export.
- Transitioning to the power-hardware-in-the-loop environment for validation of control approaches
- Charging profiles and battery design to support greater than 3-C charging rates for en-route charging

Summary

This project will:

- 1) Address challenges and develop solutions for **1+ MW systems through a national laboratory and industry collaboration**
- 2) Overcome barriers to deployment of a 1+ MW-scale integrated charging station and provide answers to fundamental questions associated with the feasibility of the system
 - Identify hardware component needs
 - **Develop and test hardware and system designs**
 - Develop design guidelines and performance metrics
 - Assess potential **grid impacts and grid services**
- 3) Develop safe systems and smart energy management techniques, including on-site resource sizing and control.
- 4) Demonstrate through controller hardware-in-the-loop the **real-time operation of a 1+MW charging system** to analyze grid integration, power electronics control, site-level energy control, and system communication requirements.



NREL Team:

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Shriram Santhanagopalan
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Ahmed Mohamed
Barry Mather
Xiangqi Zhu
Rasel Mahmud
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ANL Team:

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Keith Hardy
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Michael Starke
Brian Rowden
Madhu Chinthavali
Rafal Wojda
Shilpa Marti
Aswad Adib

Thank You !
The 1+MW Team

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Technical Back-Up Slides

Technical Back-Up Slides:

Task 1 / 2 / 3 – PE Topology Review, Simulation, and Selection

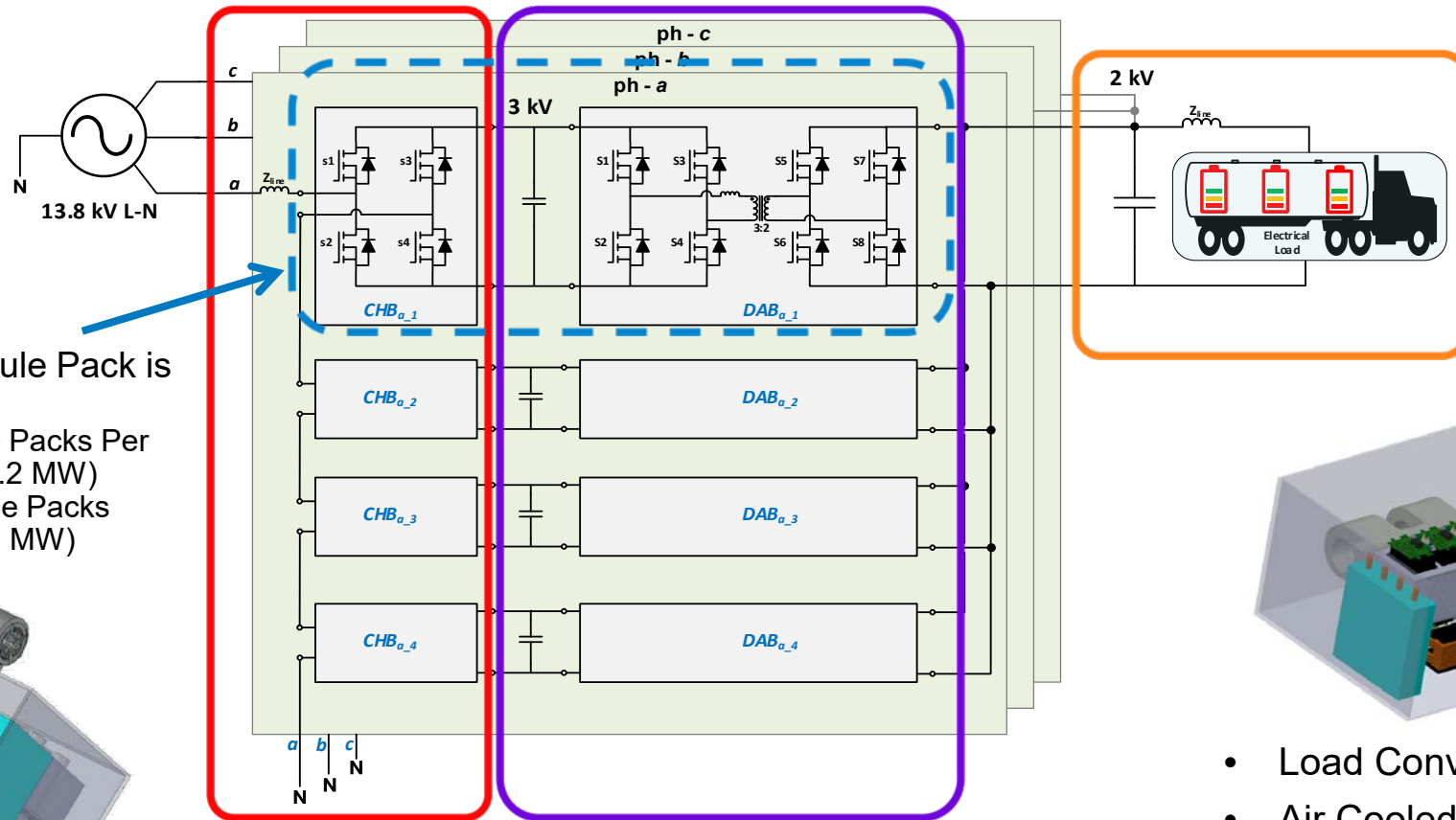
Attribute	Metric	Architecture		
		DC Coupled Arch.	AC Coupled Arch.	MV-CHB Arch.
Efficiency	Semiconductor Losses	Lowest in pure-DER mode	Lowest during pure-grid mode	Balanced
	Overall System Efficiency	94-98%	92-95%	95-98% Minimize number of parallel stages
	Standby Efficiency	Good	Good	Good
Performance	Transient DC Voltage Stability	Better	Good	Best
	Grid-side voltage stability	Best	Poor	Good
	Advanced Grid Support	Comparable	Comparable	Comparable
	Output current ripple control	Good	Good	Best
System Ratings	Active device ratings	Good	Good	Best, Low due to Modular converter structure
	Low Frequency Stepdown Transformer	Required	Required	Not Required
	AC-side breaker and switchgear requirements	High-current AC interface	High-current AC interface	Low-current AC interface
Scalability	Modularity	Good	Good	Best
	System Scalability	Good – Parallel systems required in BOS	Poor – Parallel systems required in BOS, stages for DER inclusion	Best – minimum BOS for multi-MW installation

Best Overall Performance and Balance of System Utilization

1. Efficiency: initial evaluation based on semiconductor losses and refined with passive element losses
2. AC and DC Coupled based on 480V class which limits switch utilization
 - Optimization for wide-bandgap (WBG) introduction for increased switching frequency and higher voltage consideration
3. Complexity of adding DER to system

Technical Back-Up Slides:

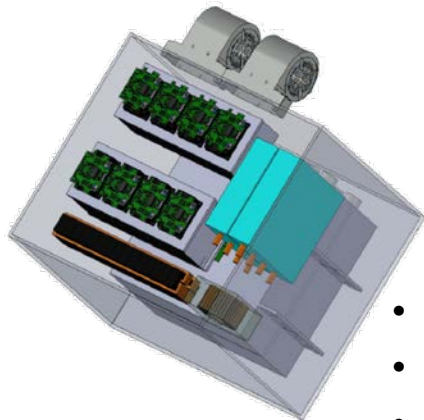
Task 1 / 2 / 3 – PE Topology Review, Simulation, and Selection



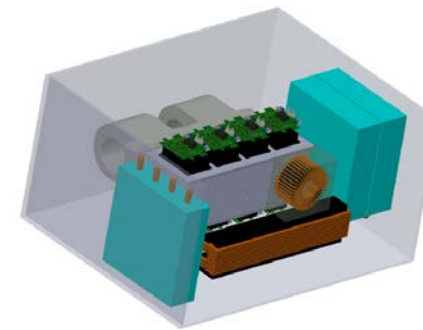
UPDATE

Each Module Pack is 300 kW

- 4 Module Packs Per Phase (1.2 MW)
- 12 Module Packs Total (3.6 MW)




- CHB-DAB 300kW Module Pack (AC-DC, DC/DC isolated)
- Air Cooled
- Max Output Power: 300 kW
- Output Voltage: 2000V DC



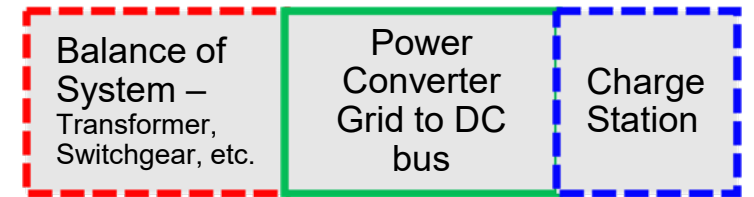
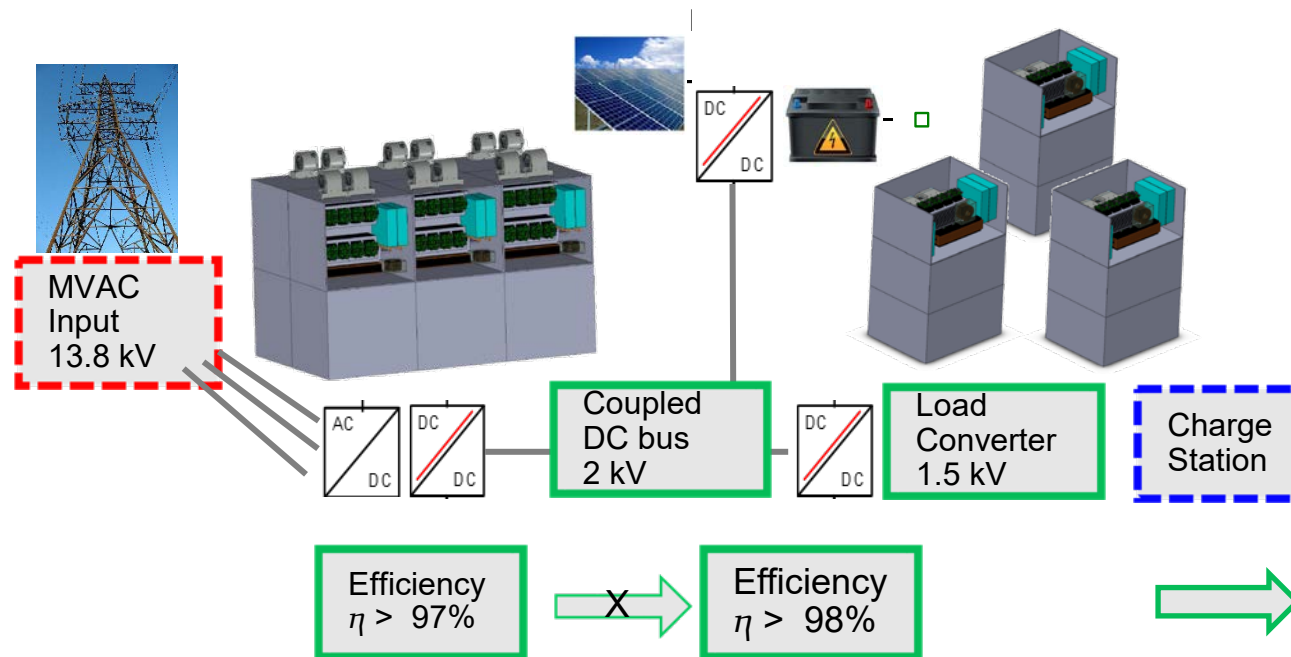
- Load Converter Module Pack (Isolated DC/DC)
- Air Cooled
- Max Output Power: 400 kW
- Output Voltage: 1500V DC

Technical Back-Up Slides:

Task 4 / 5 – MW+ Charging Equipment and Module Control

 CAD Models of Hardware

- Estimate 2X improvement in Power Density in MV architecture
- Expect BOS comparison to improve the Power Density further
- Potential for increased efficiency both at PE and BOS

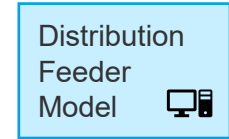


13.8 kV
3.6 MW
80-110 ft²
 $\eta > 95\%$

480 V
400 kW
25-40 ft²
 $\eta \sim 92-95\%$

Technical Back-Up Slides

Task 7 – Grid Impacts Analysis



Distribution Systems: Best Location	Feeder Requirements					Smart Charger Capacity (Reactive Power support) Requirement **	Note
		Ramp Rate		Peak Charging Load			
		Without mitigation (MW/min)	With mitigation (MW/min)	Without mitigation (MW)	With mitigation (MW)		
IEEE standardized test case: IEEE 34-bus system	Nominal	2.00	5.00	3.50	6.50	Total Capacity: 8.23 MVA Q Capacity: 5.05 MVAR	
	Maximum	2.50	5.50	4.00	7.00		
Single feeder case: California feeder	Nominal	1.80	2.50	1.80	30.00 *	Total Capacity: 33.71 MVA Q Capacity: 15.37 MVAR	Voltage goes out of upper bound if use lower PF
	Maximum	2.00	3.00	2.00	31.50 *		
Two feeder case: Hawaii feeder M1&M2	Nominal	2.16	6.50	5.50	70.00 *	Total Capacity : 78.65 MVA Q Capacity: 35.86 MVAR	Voltage goes out of upper bound if use lower PF
	Maximum	2.20	7.00	6.50	75.00 *		
Dedicated feeder case: derived from California feeder	Nominal	2.17	5.22	19.50	47.00 *	Total Capacity : 52809kVA Q Capacity: 24079kvar	
	Maximum	2.22	5.33	20.00	48.00 *		

- Analysis for four representative distribution systems.
- This **shows best location**, the max load feeders can hold will be lower at other locations.
- Considering substation cap (e.g. 10MVA), with smart charger support, max **charge load can reach 5 times of that without any mitigation strategies** (e.g., 10MW V.S. 1.8 MW for single feeder case)
- If equipped with PV and energy storage, the feeders can handle higher charging load

* Total capacity will be limited by substation transformer and sub-transmission limitations

** Smart charger capacity calculated from nominal charging load with mitigation

Technical Back-Up Slides

Task 7 – Grid Impacts Analysis

Distribution Systems: Mediocre Location	Feeder Requirements					Smart Charger Capacity (Reactive Power support) Requirement **	Note
		Ramp Rate		Peak Charging Load			
		Without mitigation (MW/min)	With mitigation (MW/min)	Without mitigation (MW)	With mitigation (MW)		
IEEE standardized test case: IEEE 34-bus system	Nominal	0.06	0.15	0.06	0.15	Total Capacity: 0.19 MVA Q Capacity: 0.12 MVAR	
	Maximum	0.08	0.20	0.08	0.20		
Single feeder case: California feeder	Nominal	0.30	2.50	0.30	2.50	Total Capacity: 3.16 MVA Q Capacity: 1.94 MVAR	
	Maximum	0.35	3.00	0.35	3.00		
Two feeder case: Hawaii feeder M1&M2	Nominal	0.40	1.50	0.40	1.50	Total Capacity: 1.90 MVA Q Capacity: 1.16 MVAR	
	Maximum	0.50	1.70	0.50	1.70		
Dedicated feeder case: derived from California feeder	Nominal	n/a	n/a	n/a	n/a	n/a	
	Maximum	n/a	n/a	n/a	n/a		

** Smart charger capacity calculated from nominal charging load with mitigation

Reviewer-Only Slides

Publications and Presentations

- Published
 - Xiangqi Zhu, Barry Mather and Partha Mishra, “Grid Impact Analysis of Heavy-Duty Electric Vehicle Charging Stations”, Proc. of 2020 Conference on Innovative Smart Grid Technologies (ISGT), 2020 IEEE
 - Partha Mishra, Eric Miller, Shivam Gupta, Shriram Santhanagopalan, Kevin Bennion, Andrew Meintz, Kevin Walkowicz, “A Framework to Analyze the Requirements of a Multiport Megawatt-Level”, TRB 99th Annual Meeting
 - Mingzhi Zhang, Xiangqi Zhu, Barry Mather, and Andrew Meintz, “Location Selection of Fast Charging Station for Heavy Duty EVs using GIS and Grid Analysis”, Proc. of 2021 Conference on Innovative Smart Grid Technologies (ISGT), 2021 IEEE
 - Xiangqi Zhu, Rasel Mahmud, Barry Mather, Partha Mishra, and Andrew Meintz, “Voltage Control Analysis for Heavy Duty Electric Vehicle Charging Station”, Proc. of 2021 Conference on Innovative Smart Grid Technologies (ISGT), 2021 IEEE
- Accepted
 - Ahmed A. S. Mohamed, Rasel Mahmud, Partha Mishra, Serena N. Patel, Isaac Tolbert, Shriram Santhanagopalan, and Andrew Meintz , “Hierarchical Control of Megawatt-Scale Charging Stations for Electric Trucks with Distributed Energy Resources,” 2021 IEEE Green Technology Conference (GreenTech) 2021
 - Theodore Bohn, "Industry Engagement Insights into MD/HD EV MW+ Charging systems", Argonne National Lab report # ANL/ESD-20/6
- In Progress
 - Pankaj Bhowmik, Madhu Chinthavali, and Brian Rowden, “Design of a 1.2 MW 480V-3 ϕ AC-coupled EV Extreme Fast Charging Station,” IEEE Transportation Electrification Conference and Expo (ITEC) 2020
 - Xiangqi Zhu, Partha Mishra, Barry Mather, Mingzhi Zhang, and Andrew Meintz, “Grid Impact Mitigation of Heavy-Duty Electric Vehicle En-Route Charging Stations”
 - Partha Mishra, Eric Miller, Shriram Santhanagopalan, Kevin Bennion, and Andrew Meintz, “A Framework To Analyze The Requirements Of A Multiport Megawatt-Level Charging Station For Heavy-Duty Electric Vehicles”

Critical Assumptions and Issues

- Assumption: 1+MW charging loads have been generated by modelling electric vehicles using available travel data for conventional vehicles. Travel patterns may change charging due to changes to short-distance regional freight models and due to range limitations.
 - Solution: The team is adding charging during long dwell times between shifts at depots and at rest areas to understand the impact to 1+MW charger utilization
- Issue: Physical layer communication reliability issues in the presence of (up to) 3000A charging current have not been validated. Existing powerline communication testing up to 200 A in EMC chamber in 2012, w/ANL-SAE. Other standards
 - Solution: The project is supporting the MCS effort consider alternate approaches such as differential CAN over pilot-proximity pin mockup test started. Though this needs full system testing for data in support of a reliability comparison.
- Issue: System level validation testing needed on coordination of subsystems (interoperability) including open communication protocols/standards between vehicle-EVSE (dispenser head), and DC-as-a-service communication of meters, local energy management, fleet management software.
 - Solution: The project's focus on a CHIL deployment will help identify requirements for the site control and hardware ecosystem. This effort will provide early learnings into valuable timing and information exchange to support the development of standards.