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Power HIL validation of a MW-scale grid-forming inverter's stabilization of otherwise unstable cases of the Maui transmission system

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No known power system large enough to have a transmission system has operated with 100% inverter- based resources (IBRs)

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Will likely require grid-forming (GFM) inverters

Background and Motivation

- Hawaiian Electric expects Maui to be their first large island to be capable of operating with 100% inverter-based power resources
	- 2020 peak: ~89.5% IBR (DER and wind)
	- **100% IBR operation expected to possible for certain hours by 2023**, from an energy balance perspective
- Maui would be the first interconnected power system of its size (~200 MW peak) with highly distributed utility-scale generation and 69 kV voltage levels to reach this milestone

- NREL **EMT study** (PSCAD): System can be stable from an oscillation damping perspective (generic IBR models)
- Electranix [PSCAD study:](https://dms.puc.hawaii.gov/dms/DocumentViewer?pid=A1001001A21F14B62327F00172) GFM inverters can operate stably with rest of system (actual IBR plant models)
- **In this presentation: Power hardware-in-the-loop tests linking real hardware GFM inverter to real-time EMT model of Maui (RSCAD)**
- These are just steps in a complex due-diligence process towards operating Maui in an unprecedented way

2023 Maui Power System

Reduced 2023 Maui Transmission Map East Central West 112 206 405 404 201 Maalaea West 602 **K1** \bigcup **K2** South 501 Legend 304 **Maalaea** $\circled{1}$: Transformer \downarrow : Wind; Type 3 or 4 \bigvee : Load (\sim) : Synchronous Hydro : Inverter; Large PV, Battery, or Hybrid Plant (\sim) : Synchronous Condenser • Aggregated from full 230-bus system for illustrative purposes and security reasons. \sim) : Synchronous Generator : Inverter; Distributed Generation • Colored regions/hundredth bus number are indicative of PSCAD parallelization basis.

- No grid-forming inverters in base case
- Significant [system strength from synchronous condensers](https://ieeexplore.ieee.org/abstract/document/9131310/)
- Electromagnetic transient [\(EMT\) model validated](https://www.nrel.gov/docs/fy21osti/76808.pdf) against field data
- K1 and K2 are two 30 MW segments of planned 60 MW PV-BESS plant

Configuration shown here reflects a planning case from 2020. Current plan differs.

Power Hardware-in-the-loop Test Setup

- 30 MVA K1 PV-BESS plant replaced by real 2.2 MVA inverter with 1 MVA BESS
	- Instantaneous inverter output scaled 30x and injected into real-time model in PHIL
	- Inverter able to operate in GFM or GFL mode
- Rest of system represented in RTDS/RSCAD model
	- Includes 30 MVA K2 plant, also able to be GFL or GFM
	- All other IBRs always GFL

Zero synchronous generation: Scenario 6 Event E1 (fault at low-SCR bus)

- Zero sync generation system is robust to severe fault with or without gridforming
	- System has 317 MVA-s of sync condensers; $H = 0.89$ s
	- Frequency measurement during fault is unreliable due to severe voltage distortion
	- Potential DER momentary cessation not modeled; GFM (or other fast active power source) may be needed to mitigate
- Scenarios S1 and S2 are very similar, with and without GFM

Stability boundary: Scenario 3 to 3a transition (loss of 2nd-to-last sync. condenser)

- Without GFM, severe voltage and frequency oscillations; would have resulted in DER tripping and system crash
	- Note oscillations already present before disturbance
- With 30 MVA of GFM, system recovers quickly and is stable

The resulting one-GFM, one-condenser system (S3a) is also robust to fault and generation loss (not shown)

Zero inertia system: Scenario 7 Fault event

- Without GFM, scenario cannot be reached
	- Voltage instability occurs as soon as last condenser is removed (not shown)
- With 30 MVA of GFM (hardware), system crashes post-fault
- With 30 MVA of GFM (simulated), system has severe voltage and frequency deviations; would have tripped DERs and crashed
- With 60 MVA of GFM capacity, system is stable and recovers quickly

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Zero inertia system: Scenario 7 N-1 generation trip event

- All events potentially survivable
- 60 MVA GFM case has best damping

- Note difference in hardware inverter response speed immediately after event when in GFM mode (blue) vs GFL mode (red)
	- Illustrates a fundamental difference between GFL (reacts via droop) and GFM (inherently does what's needed to stabilize terminal voltage angle)

Conclusions and questions:

- **A real hardware GFM inverter can stabilize otherwise unstable cases of a transmission electric power system, including zero-inertia cases**
	- Stabilizes faster modes
	- Mitigates instability of remaining GFLs
	- MW-scale test validates detailed PSCAD simulations
- Modeling inverter control loops (power and current) of GFL devices (including small DERs if their aggregate capacity is large!) is required to detect faster modes in the system response under very weak grid conditions
- Amount of GFM capacity needed (observations):
	- *Does not* necessarily depend on percentage generation from IBRs
	- *Does* depend (inversely) on **capacity of synchronous machines** online
	- This considers oscillatory stability; major nonlinearities such as DER/IBR tripping or momentary cessation may drive higher GFM need
- Note: These simulations focus on transient stability and do not consider other topics necessary for 100% IBR operation, e.g. protection, reserves, resource adequacy…

GFM Needed for Stability at Various Inertia Levels

Could such a metric be used to **develop stability constraints for scheduling, dispatch, and capacity planning?** Can new models (e.g. NREL's [MIDAS tool\)](https://www.nrel.gov/grid/midas.html) validate the ability of this approach to ensure stability with high IBRs?

Questions welcome Andy.Hoke@NREL.gov

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