



INDUSTRIALIZED AND ROBOTIC CONSTRUCTION

ADVANCES IN TERRESTRIAL CONSTRUCTION

AND OPPORTUNITIES IN

SPACE

CONSTRUCTION



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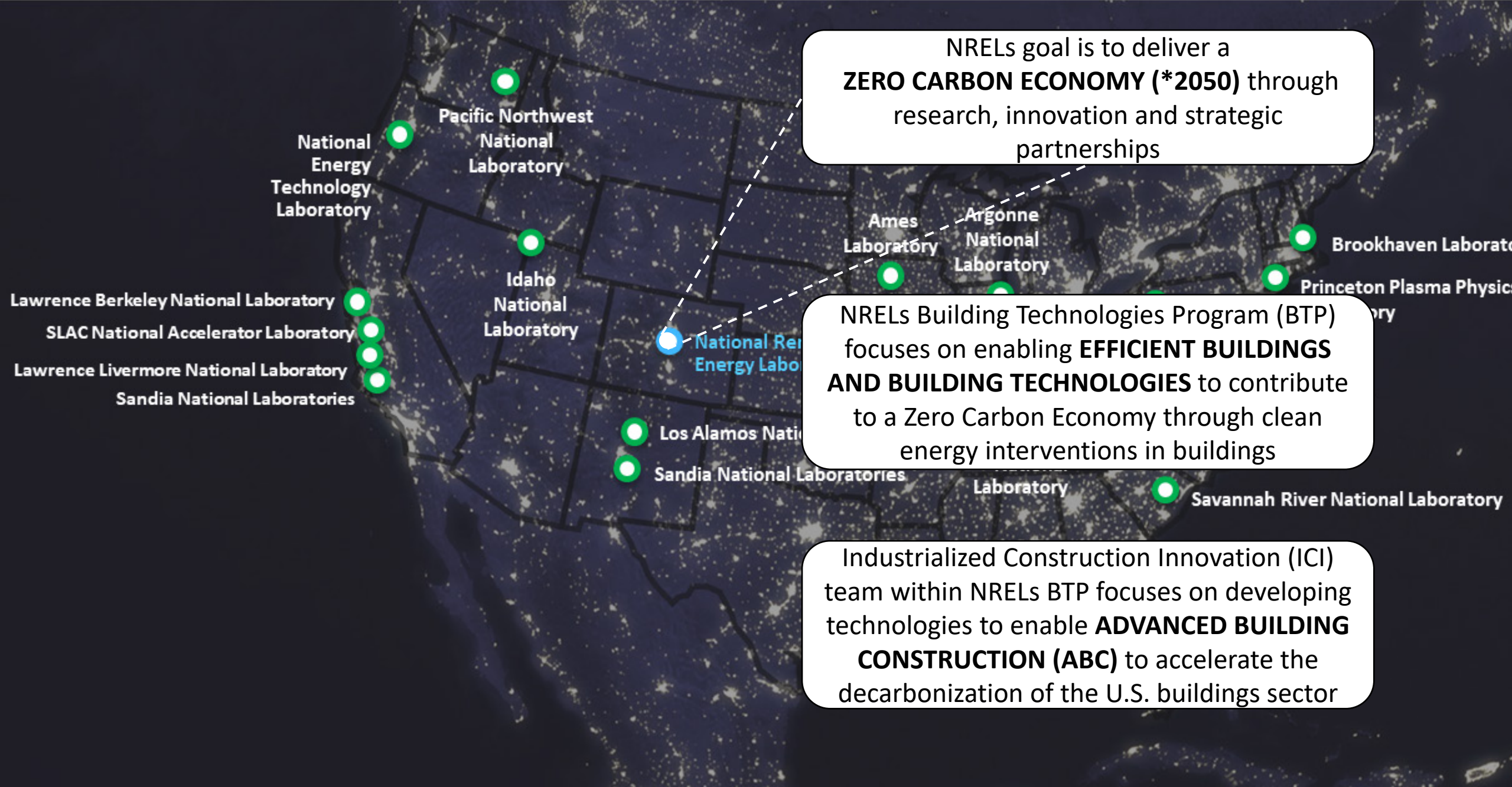


JERRY DAVIS
LAB PROGRAM MANAGER
PARTNERSHIP DEVELOPMENT
NREL

TERRESTRIAL CONSTRUCTION

- 1. Background** (NREL ICI,)
- 2. Trends & Sample** (Glimpses of past projects + Systems approach)
- 3. ICI efforts at NREL** (Modelling & Simulation, Deployment, Commercialization)
- 4. Future Avenues** (Robotics for Systems Integration/outfitting in buildings)

SPACE CONSTRUCTION



NRELs goal is to deliver a **ZERO CARBON ECONOMY (*2050)** through research, innovation and strategic partnerships

NRELs Building Technologies Program (BTP) focuses on enabling **EFFICIENT BUILDINGS AND BUILDING TECHNOLOGIES** to contribute to a Zero Carbon Economy through clean energy interventions in buildings

Industrialized Construction Innovation (ICI) team within NRELs BTP focuses on developing technologies to enable **ADVANCED BUILDING CONSTRUCTION (ABC)** to accelerate the decarbonization of the U.S. buildings sector

National Energy Technology Laboratory

Pacific Northwest National Laboratory

Idaho National Laboratory

National Renewable Energy Laboratory

Ames Laboratory

Argonne National Laboratory

Brookhaven Laboratory

Princeton Plasma Physics Laboratory

Lawrence Berkeley National Laboratory

SLAC National Accelerator Laboratory

Lawrence Livermore National Laboratory

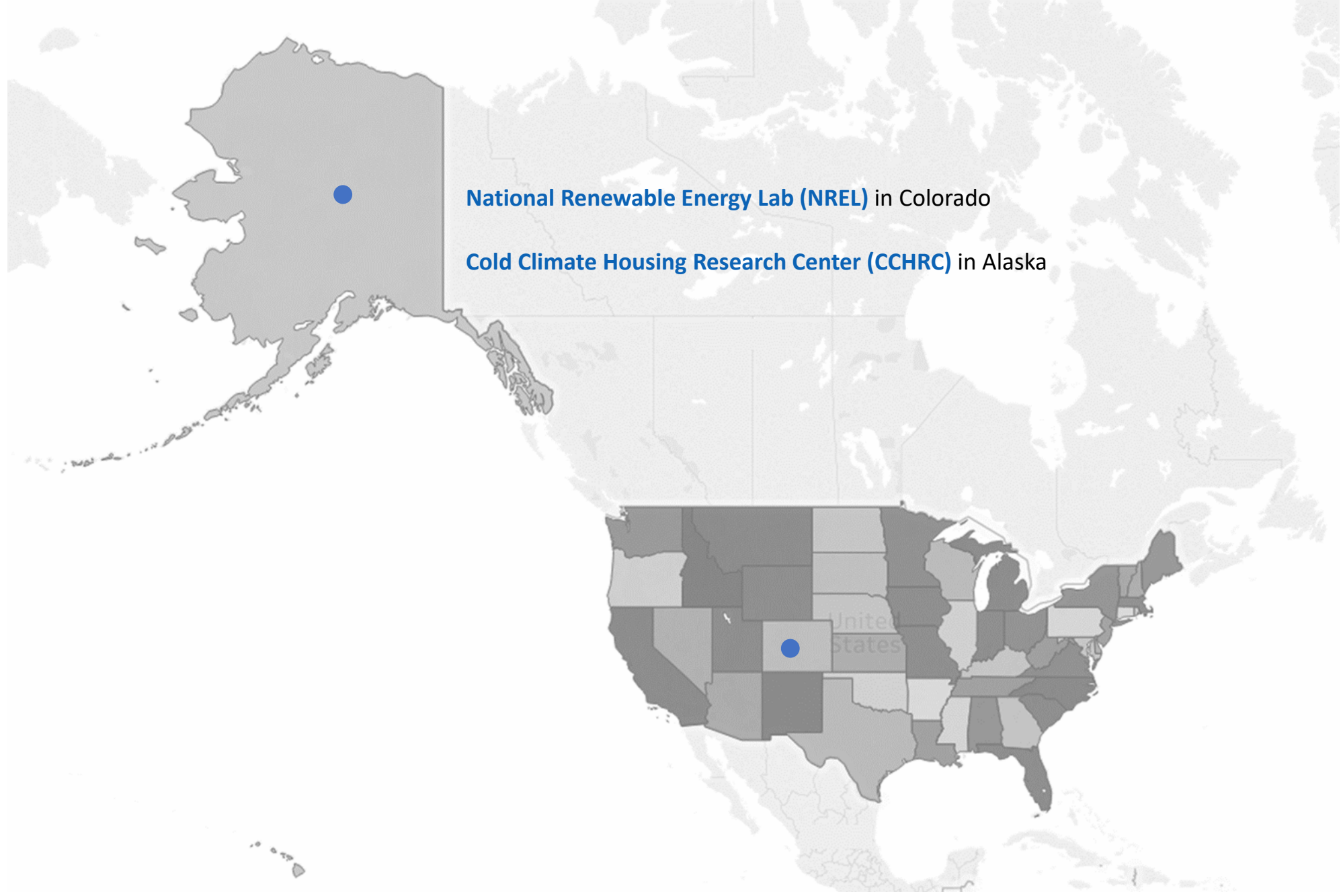
Sandia National Laboratories

Los Alamos National Laboratory

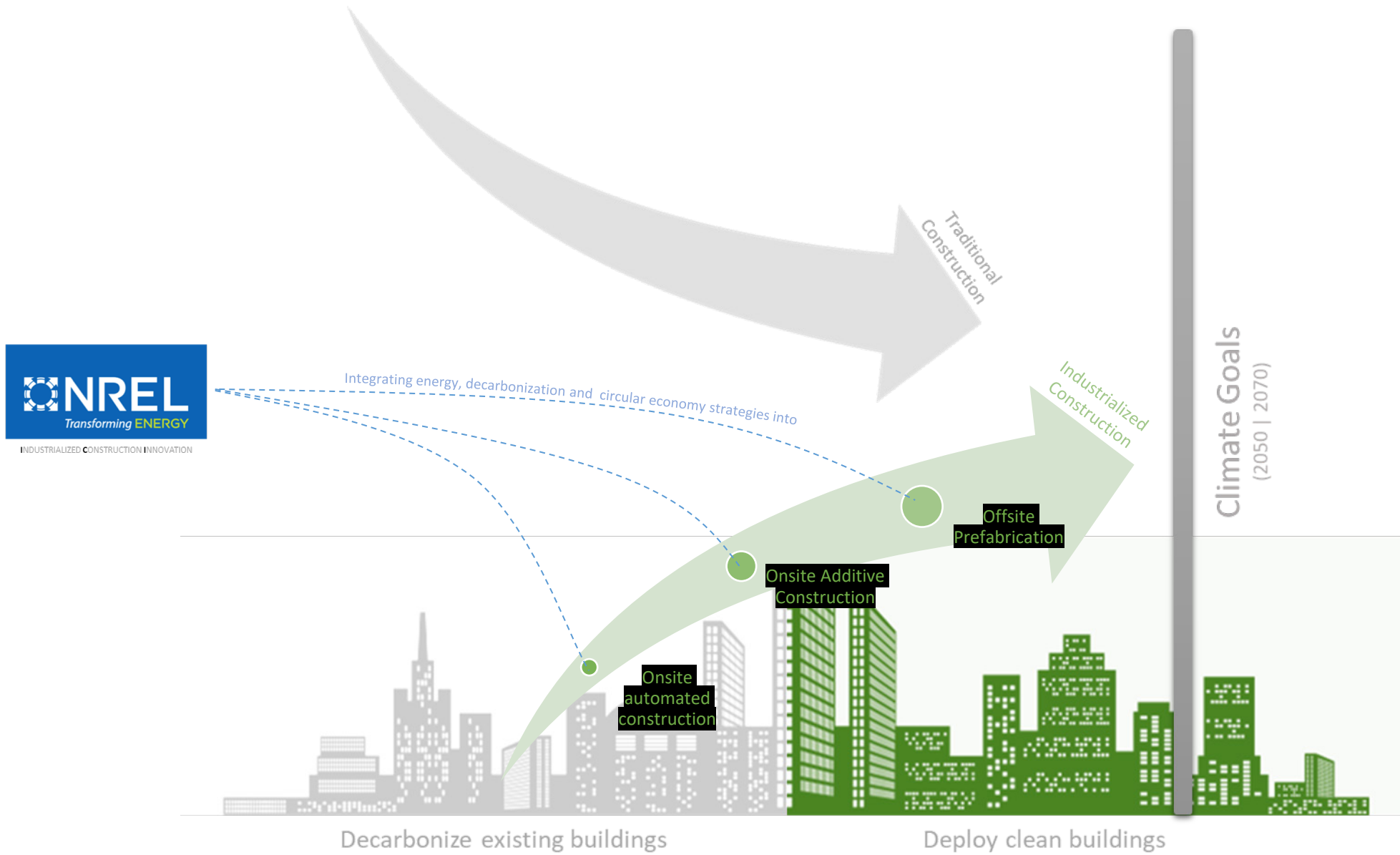
Sandia National Laboratories

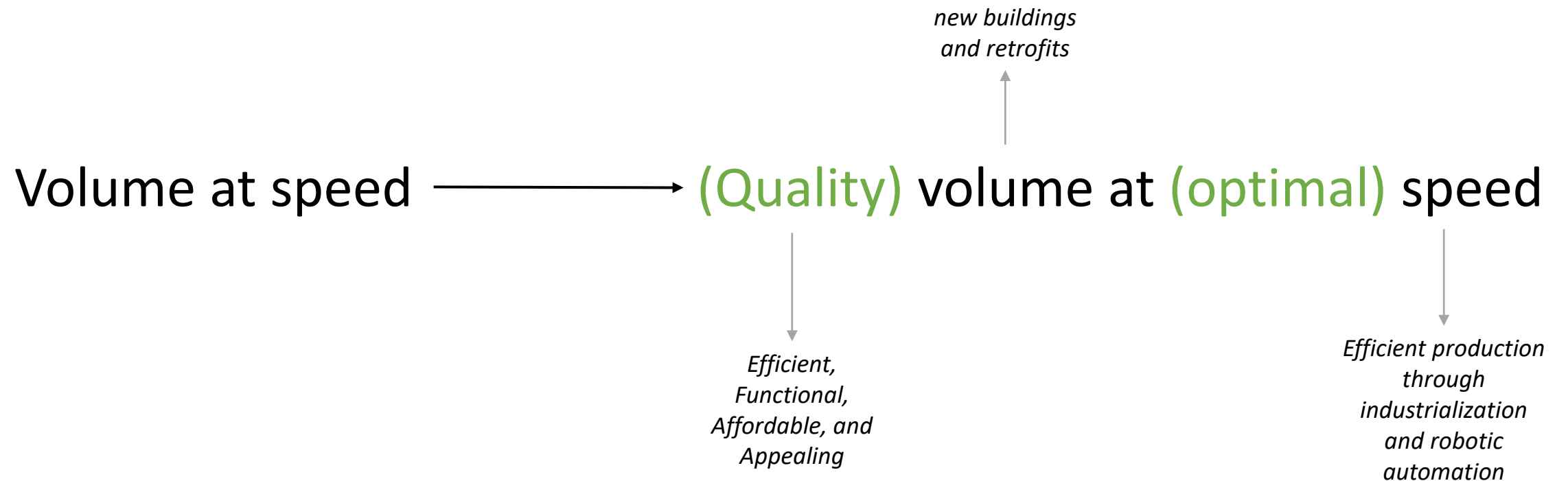
Laboratory

Savannah River National Laboratory



Background





Traditional Construction

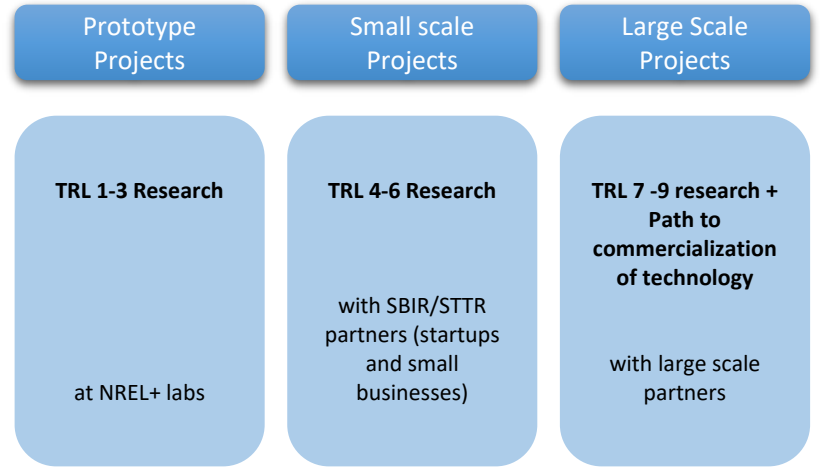
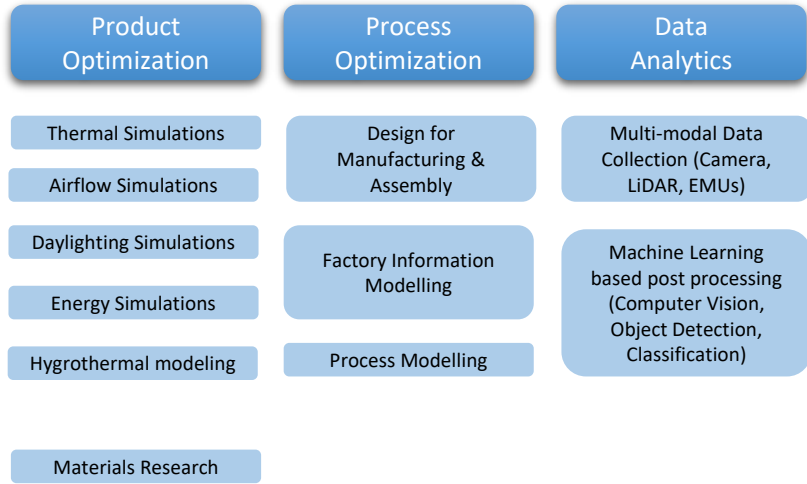
Industrialized Construction Innovation

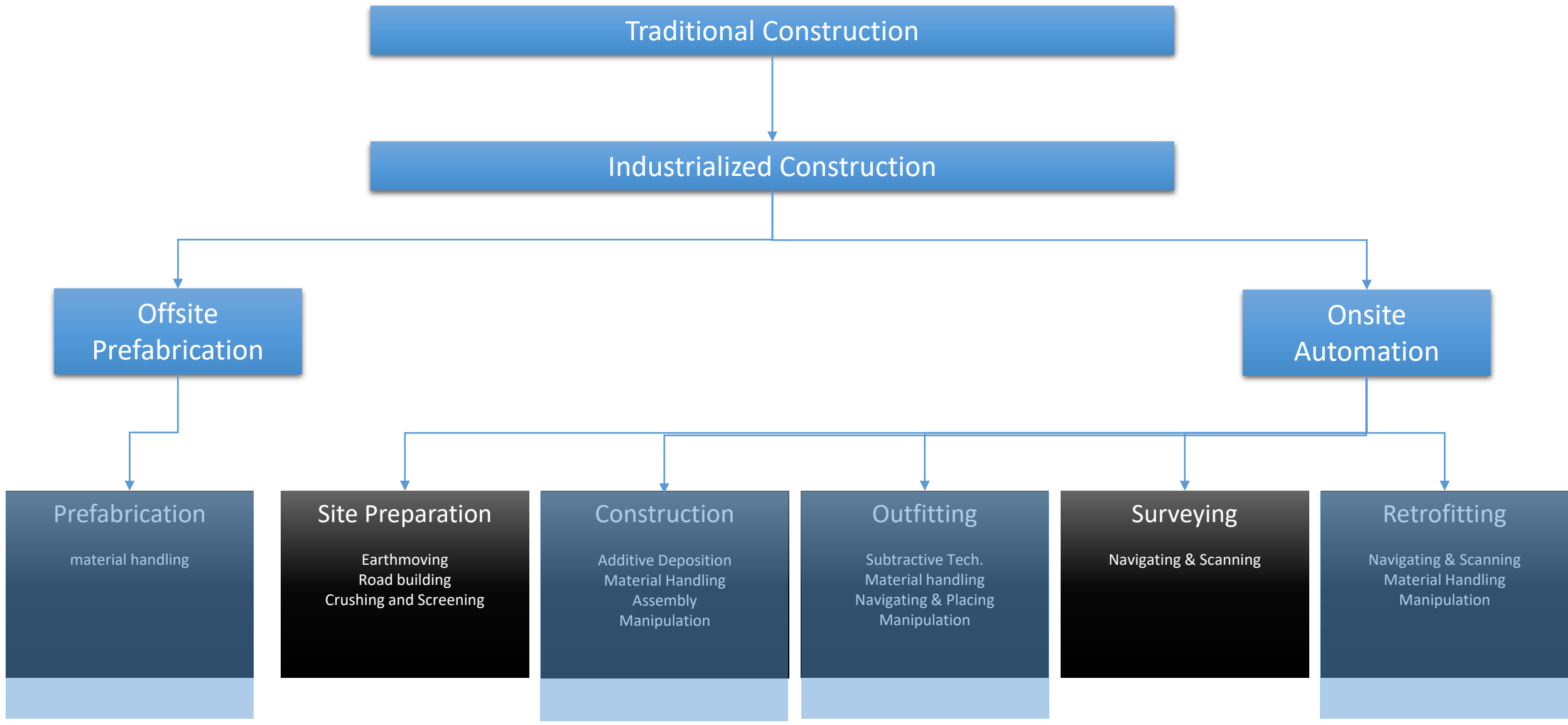
Computational Capabilities

Demonstration Capabilities

Modelling and simulation capabilities to support

Testing and demonstration capabilities to support





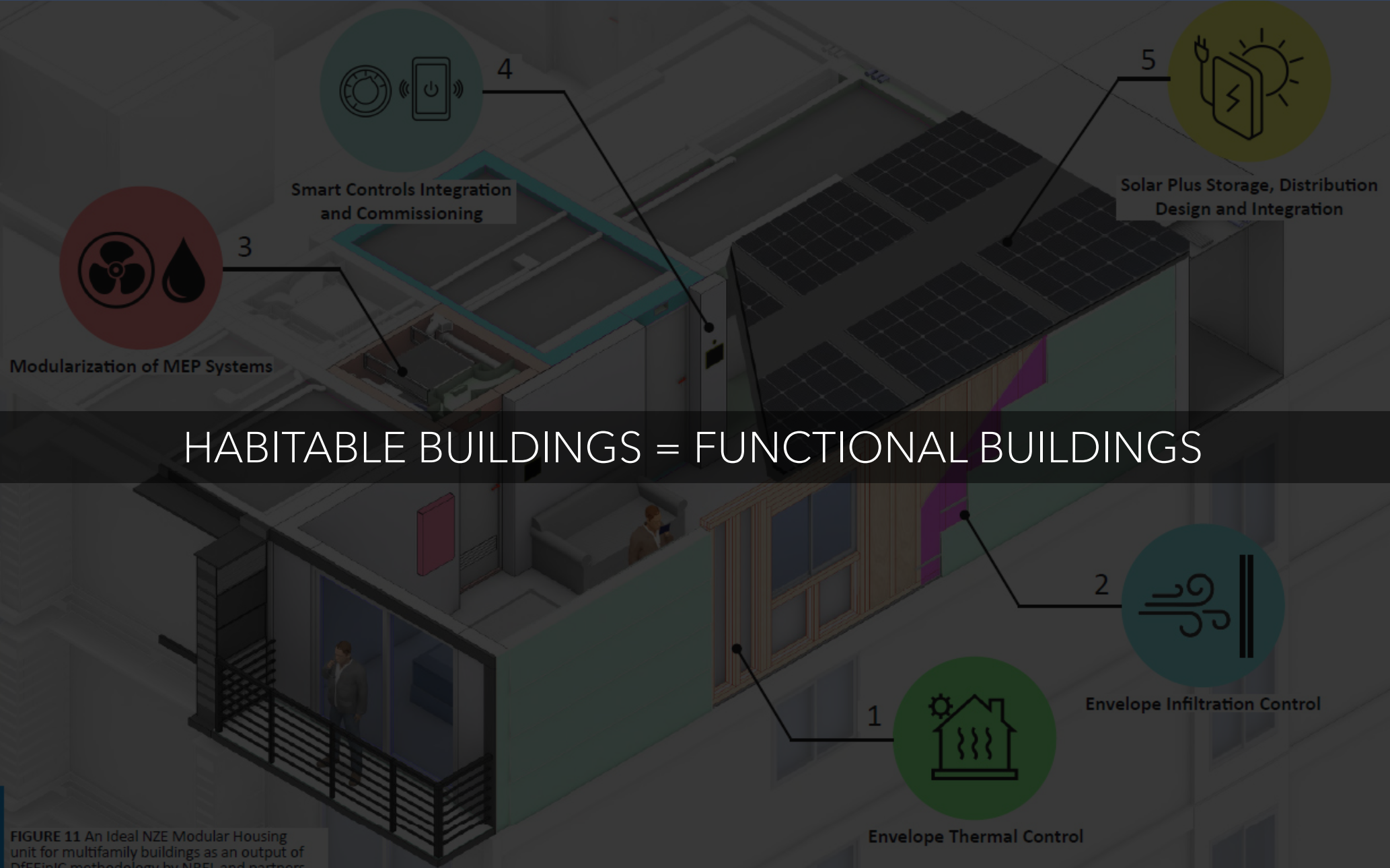
MODES OF ROBOTIC CONSTRUCTION

Industrial Robotic Arms

Rovers

Quadrupedals

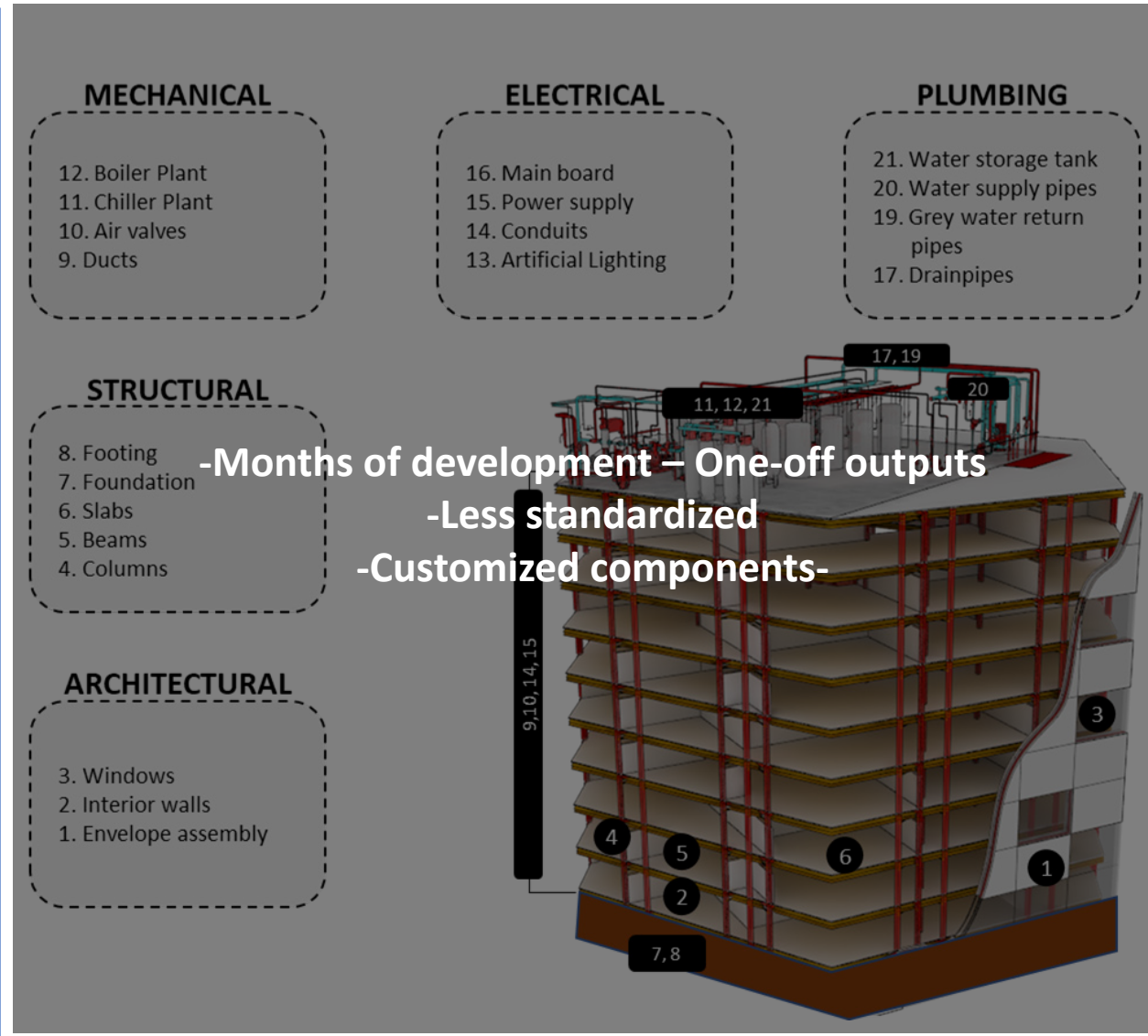
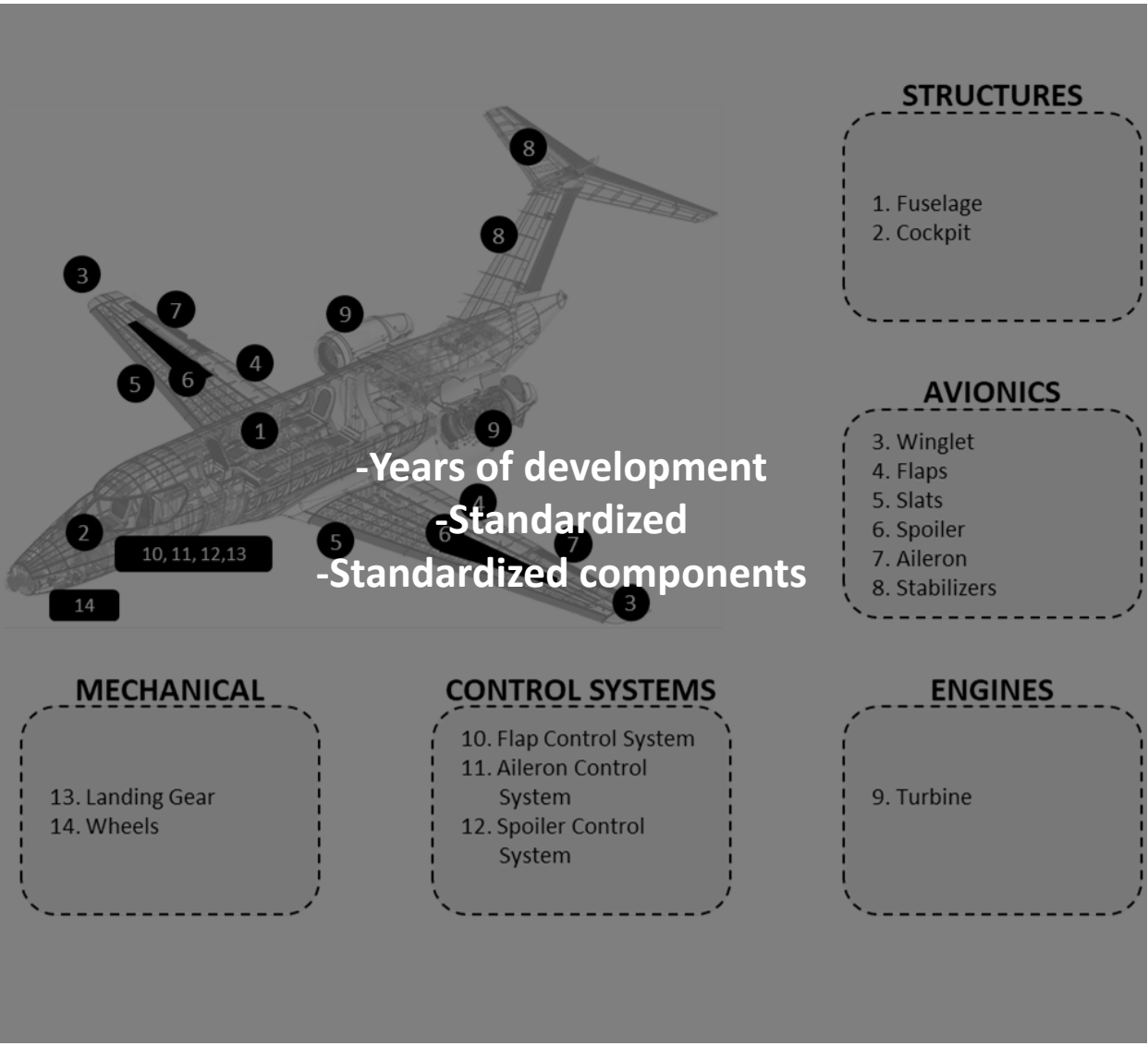
Drones



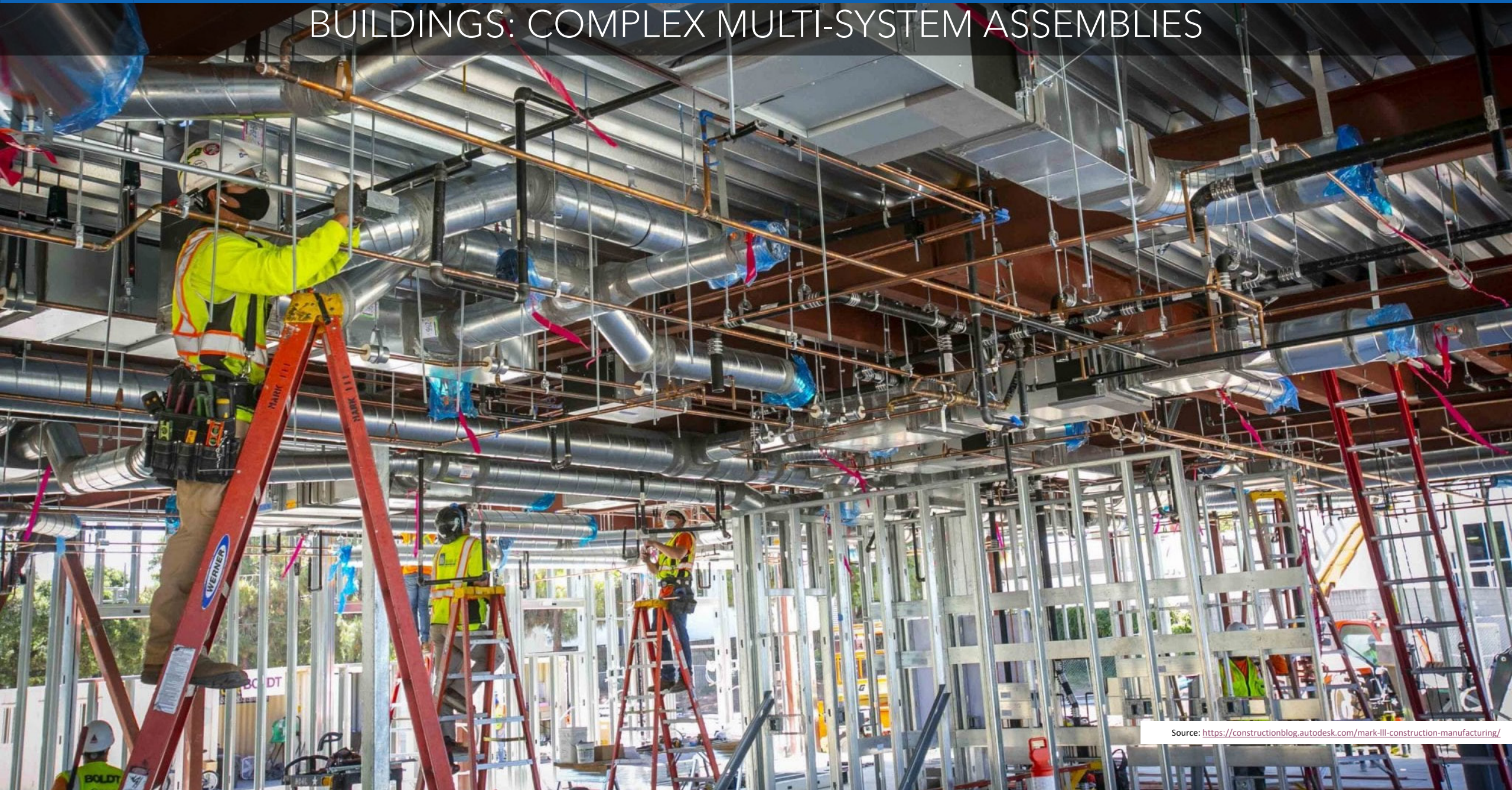
HABITABLE BUILDINGS = FUNCTIONAL BUILDINGS

FIGURE 11 An Ideal NZE Modular Housing unit for multifamily buildings as an output of DfEEinIC methodology by NREL and partners.

Building as a system of systems



BUILDINGS: COMPLEX MULTI-SYSTEM ASSEMBLIES



INDUSTRIALIZED CONSTRUCTION: BUILDING COMPONENT PRODUCTION



INDUSTRIALIZED CONSTRUCTION: BUILDING ASSEMBLIES



INDUSTRIALIZED CONSTRUCTION: ONSITE ASSEMBLIES



INDUSTRIALIZED CONSTRUCTION: OFFSITE MULTI-SYSTEM ASSEMBLIES



INDUSTRIALIZED CONSTRUCTION: IN-SITU CONSTRUCTION



INDUSTRIALIZED CONSTRUCTION: ONSITE AUTOMATION

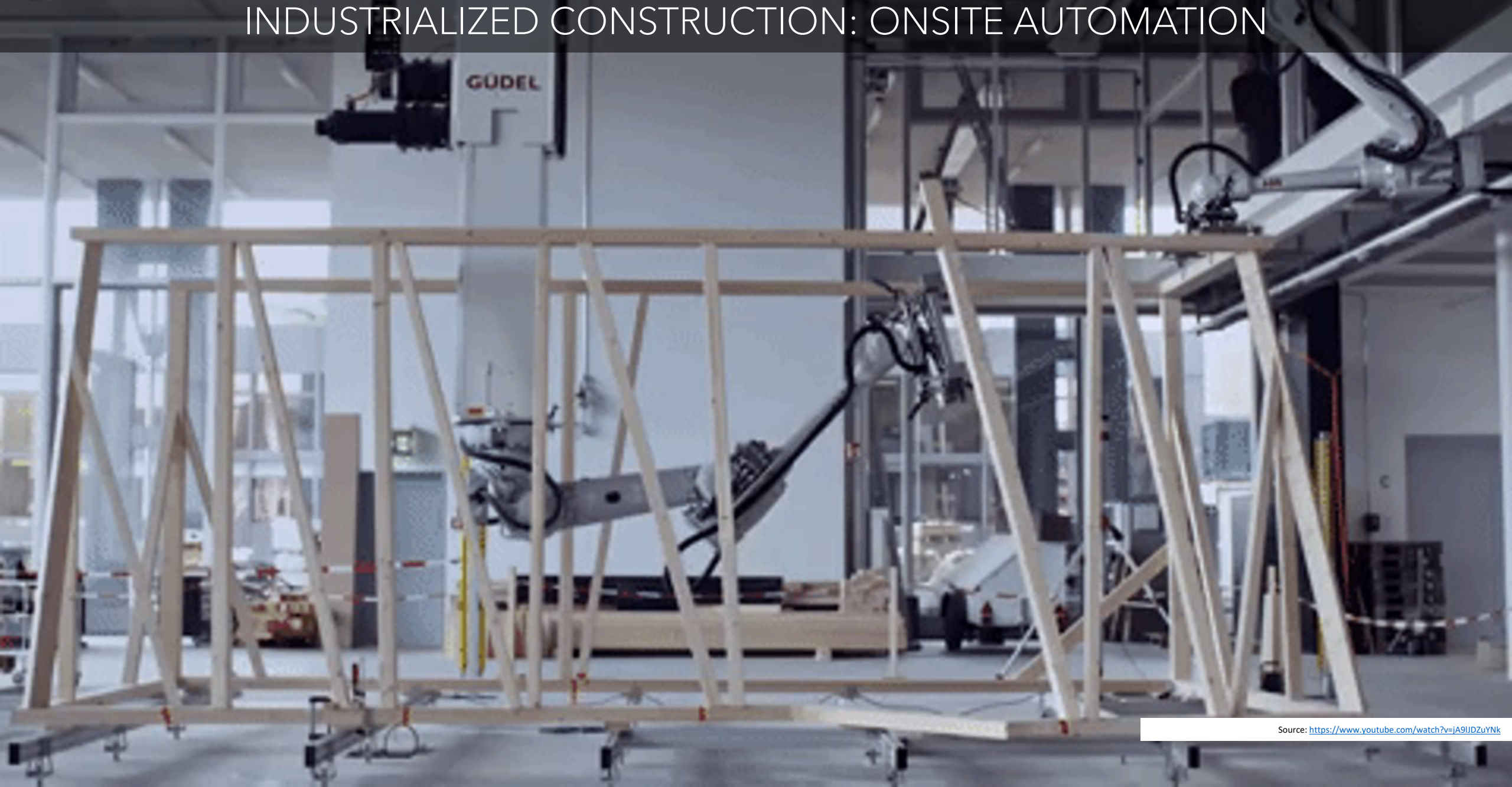


Source: <https://www.archdaily.com/779906/new-construction-robot-lays-bricks-3-times-as-fast-as-human-workers>

INDUSTRIALIZED CONSTRUCTION: ONSITE AUTOMATION



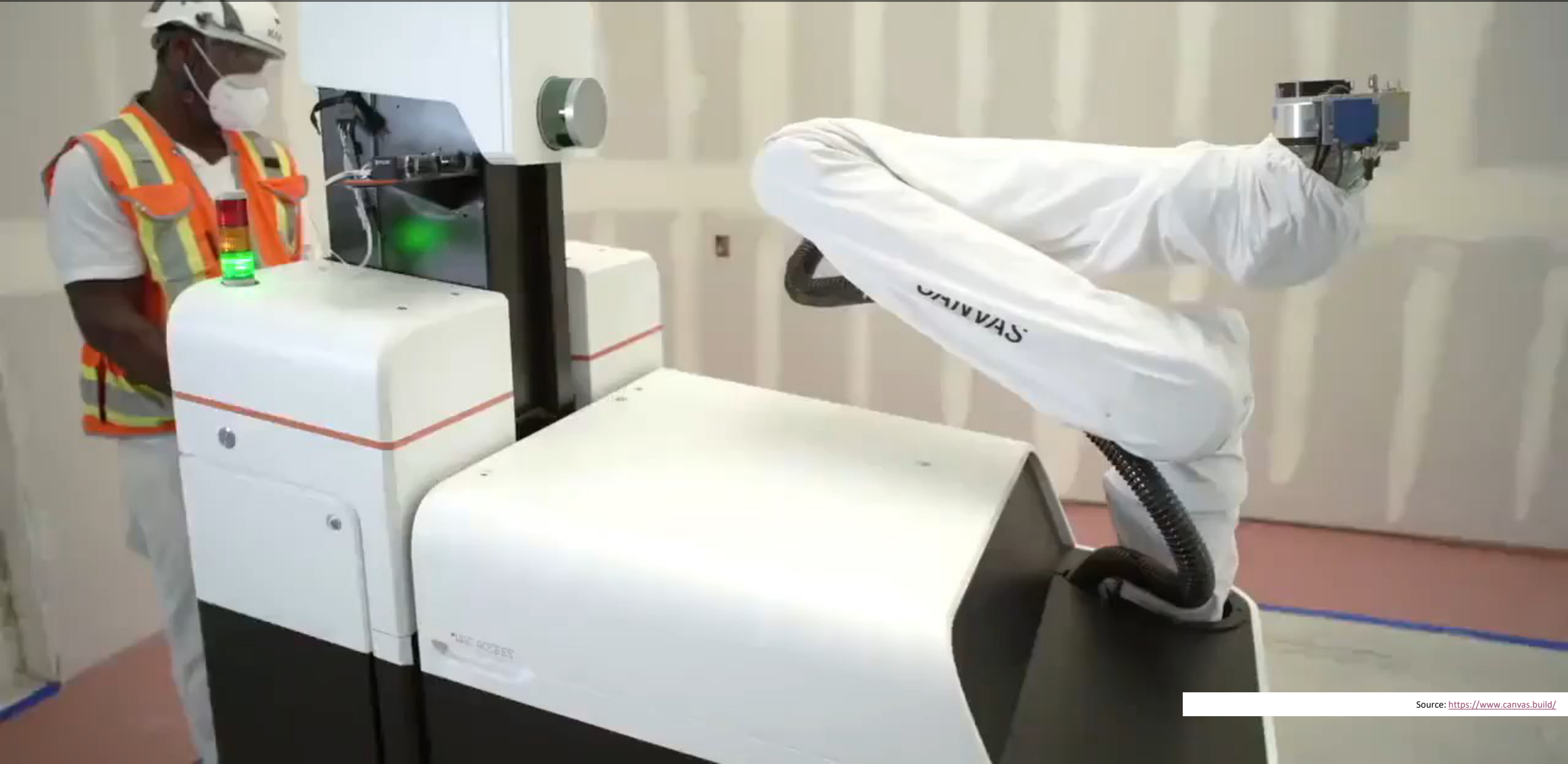
INDUSTRIALIZED CONSTRUCTION: ONSITE AUTOMATION



INDUSTRIALIZED CONSTRUCTION: ONSITE AUTOMATION



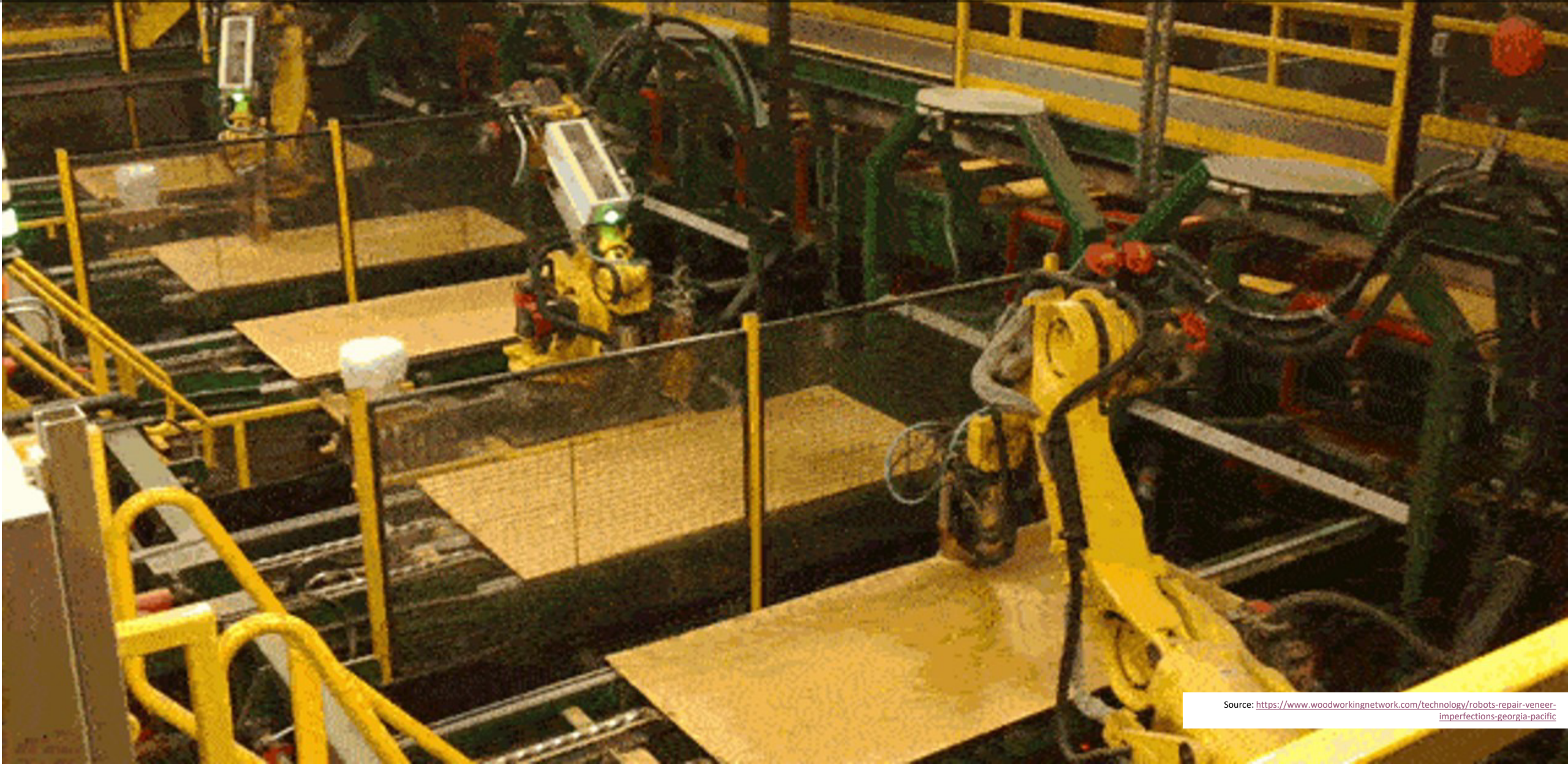
INDUSTRIALIZED CONSTRUCTION: ONSITE AUTOMATION



INDUSTRIALIZED CONSTRUCTION: REMOTE ACCESS



INDUSTRIALIZED CONSTRUCTION: RETROFIT AND RENOVATION



INDUSTRIALIZED CONSTRUCTION: FAULT DETECTION

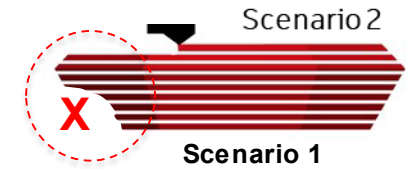
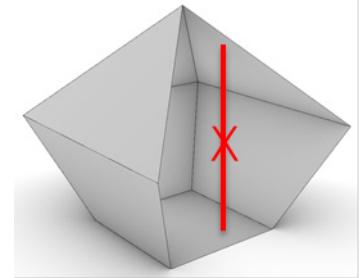
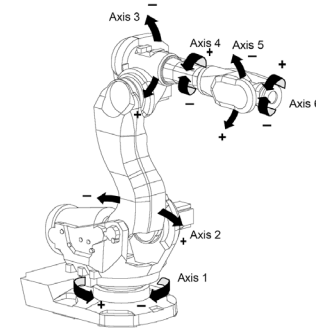
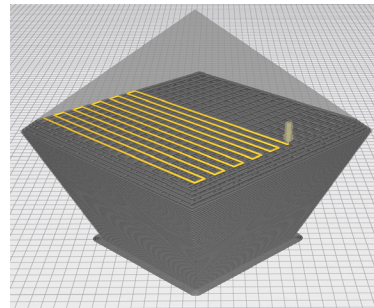
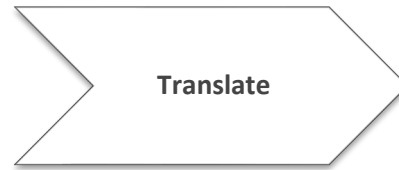
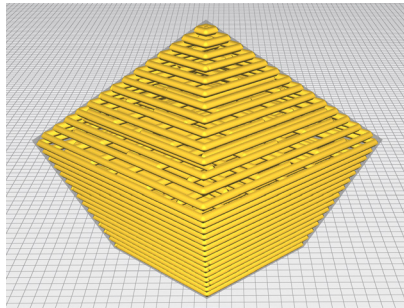
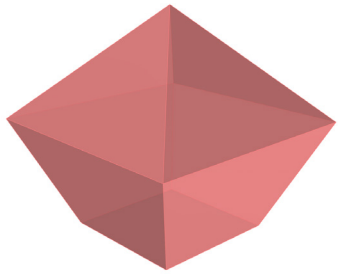
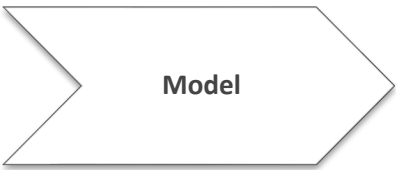


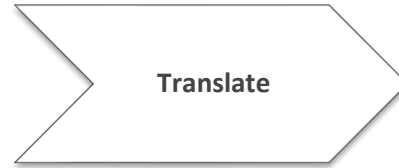
Virtual Construction Level
Mars



Actual Construction Level
Earth







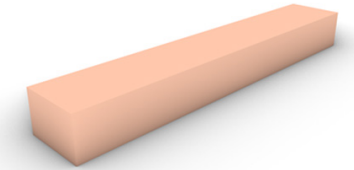
Model

Slice

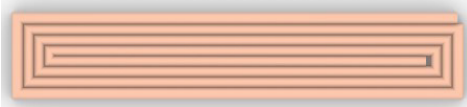
Translate

Simulate

Manufacture



Toolpath A



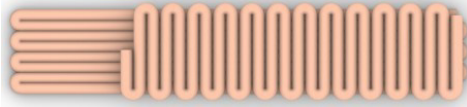
Toolpath A

```

1 ; Default start code
2 G28 ; Home extruder
3 G1 Z15 F1000
4 M107 ; Turn off fan
5 G90 ; Absolute positioning
6 M82 ; Extruder in absolute mode
7 M150 S50
8 ; Motivate all used extruder
9 M104 T0 S210
10 G92 E0 ; Reset extruder position
11 ; Wait for all used extruders to reach temper
12 M109 T0 S210
13 Layer Count: 996
14 LAYER:0
15 M107
16 G0 F9000 X108.295 Y88.100 Z0.300
17 TTPF:SWIRT
18 G1 F1800 X108.816 Y87.460 E0.04117
19 ;
20 ;

```

Toolpath B

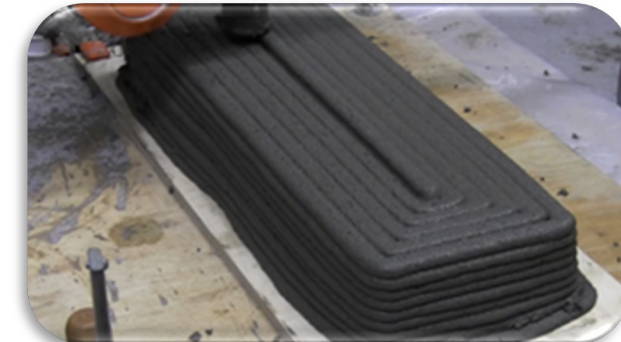
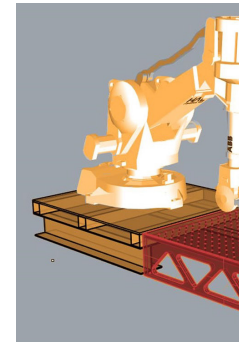


Toolpath B

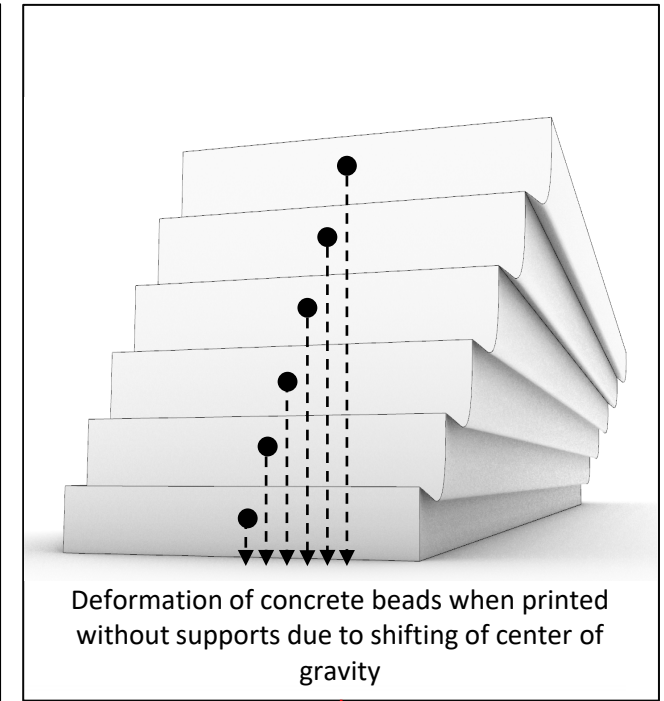
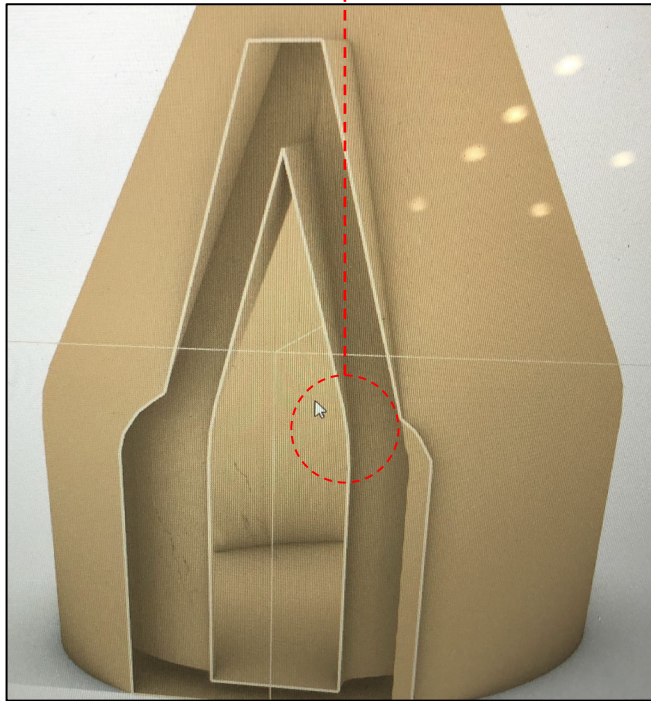
```

1 ; Default start code
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13 Layer Count: 996
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16 G0 F9000 X108.295 Y88.100 Z0.300
17 TTPF:SWIRT
18 G1 F1800 X108.816 Y87.460 E0.04117
19 ;
20 ;

```

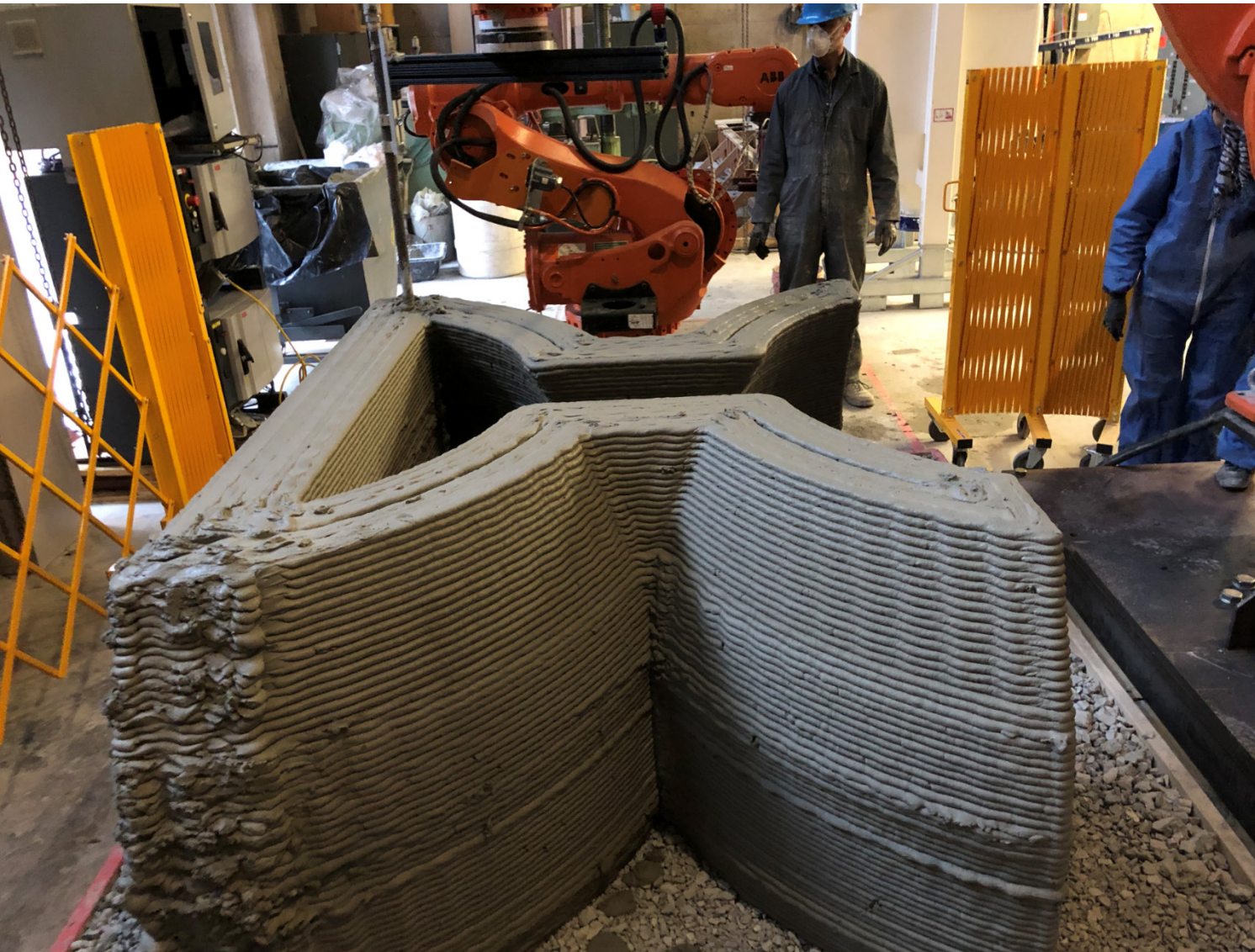


- ↑Structural performance
- ↑Complex Robotic Maneuvers
- ↑Robotic vibrations at turns
- ↑Concrete deformation (Less shape accuracy)



Design Variables:

- Angle of taper
- Material consistency (Concrete mixing ratio)



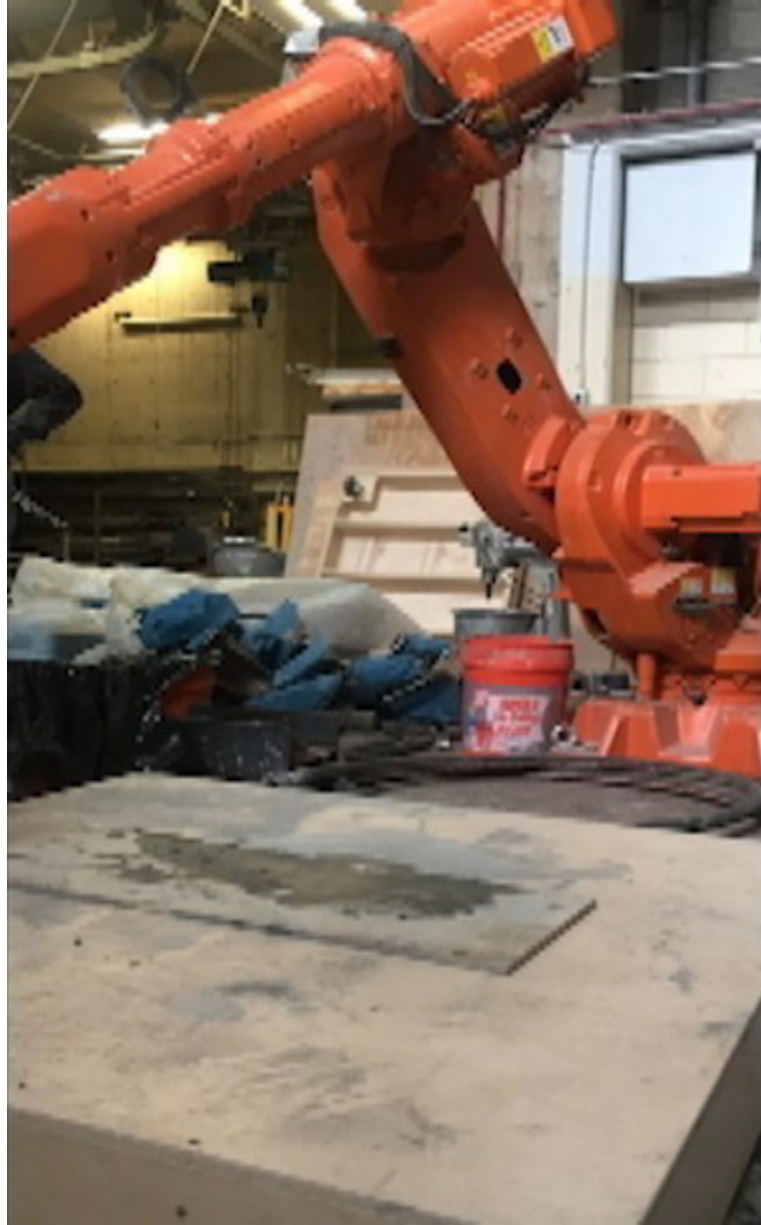
Challenges:

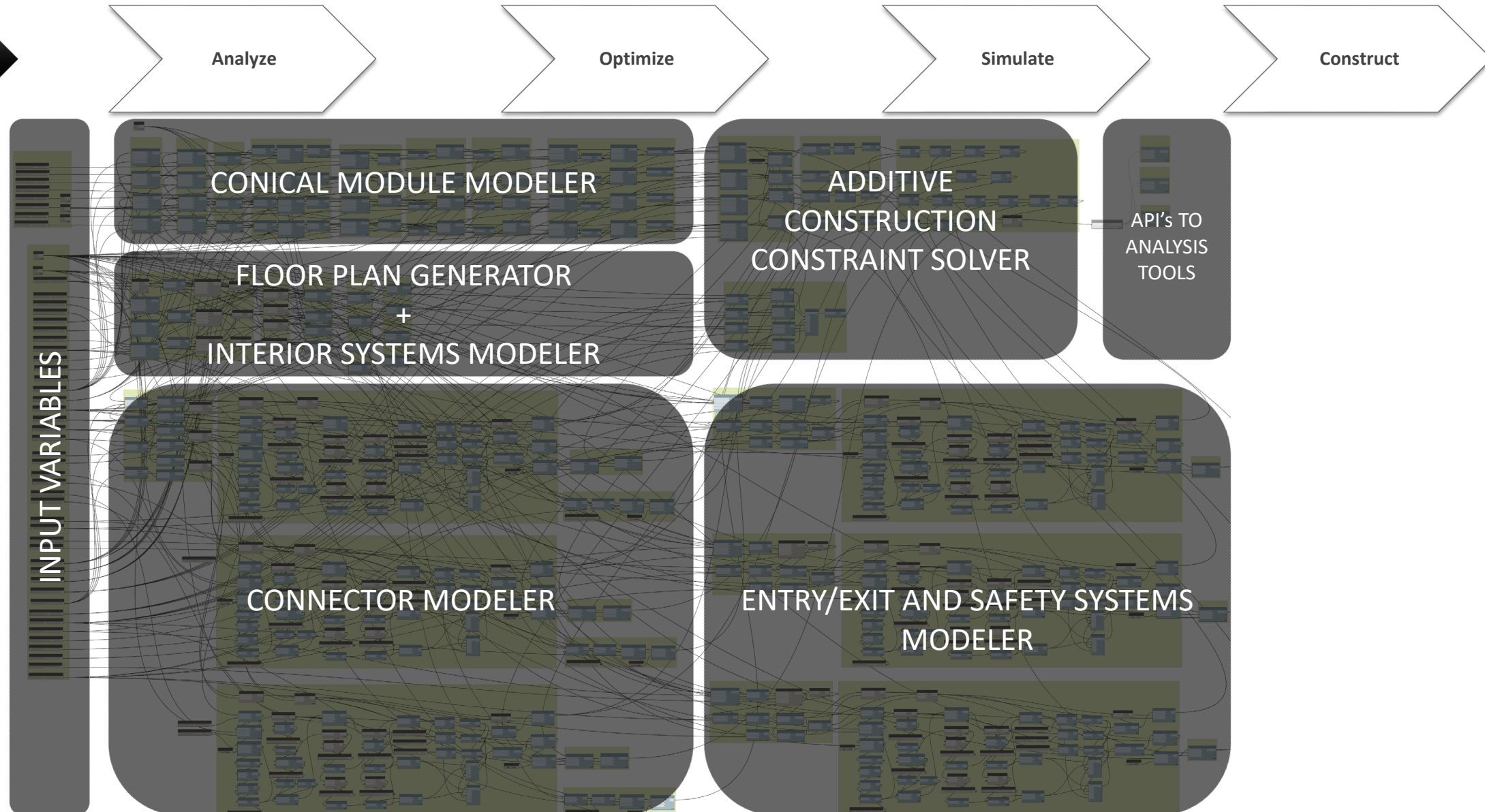
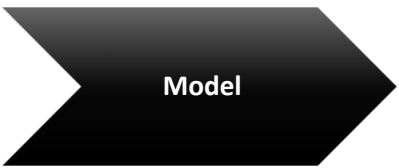
- Over-extrusion at edges/corners/ junctions

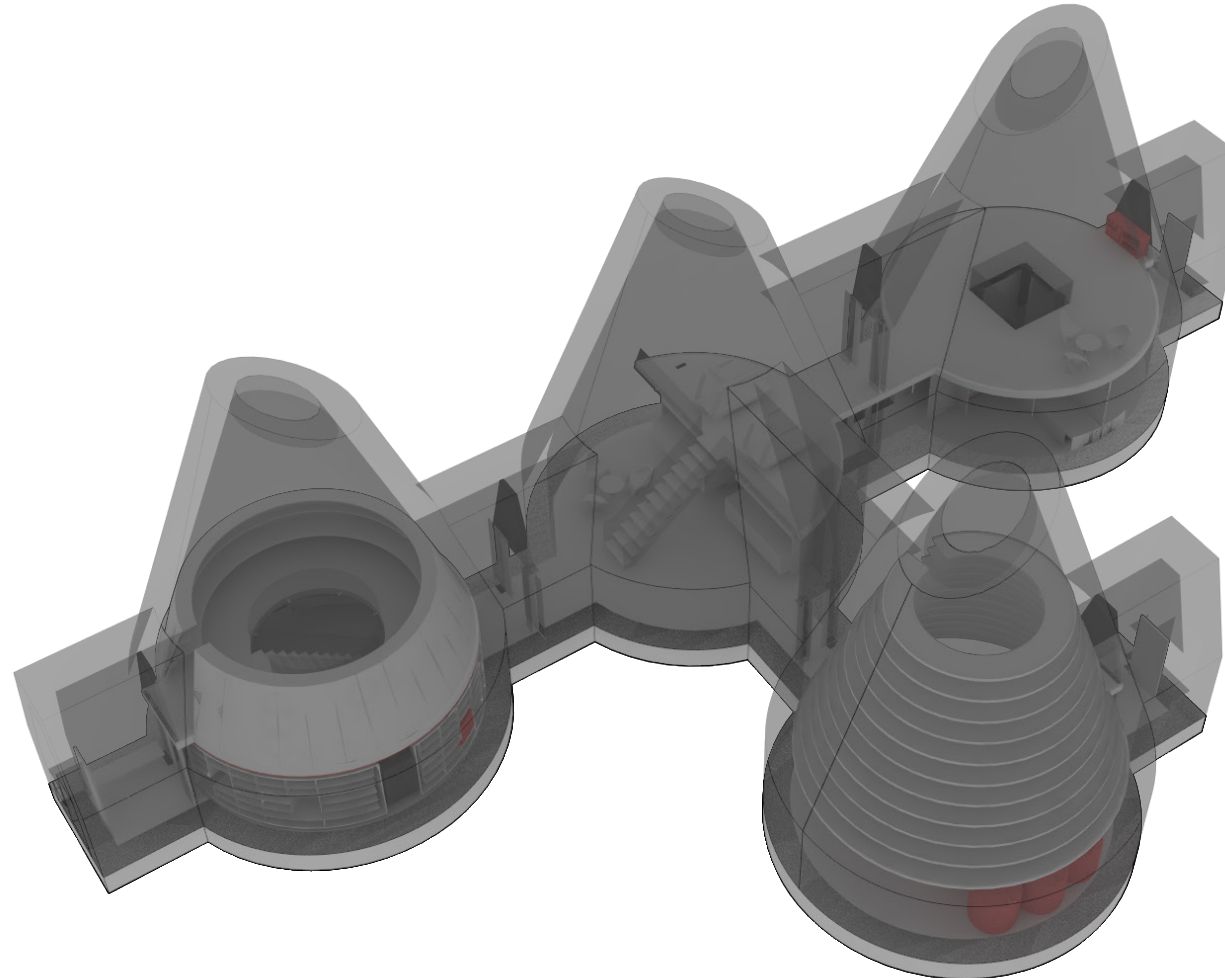
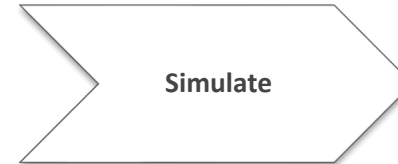
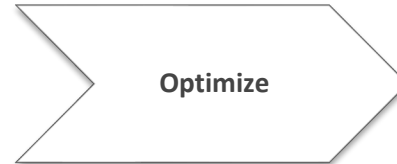
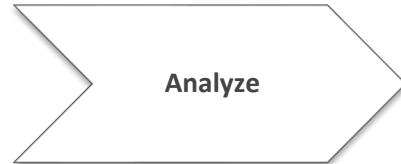
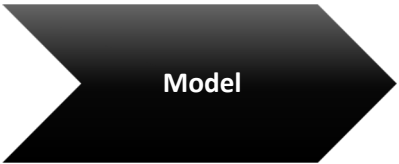
Design Variables:

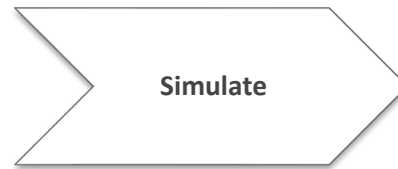
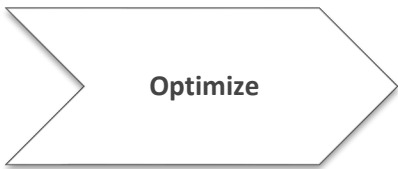
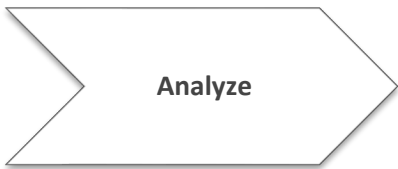
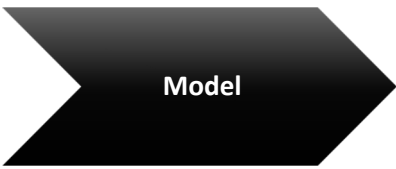
- Fillet radius at edges/corners/junctions
- Robot speed at corners



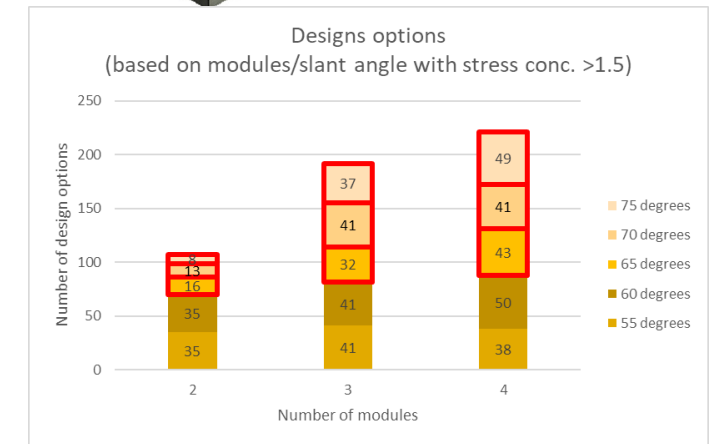
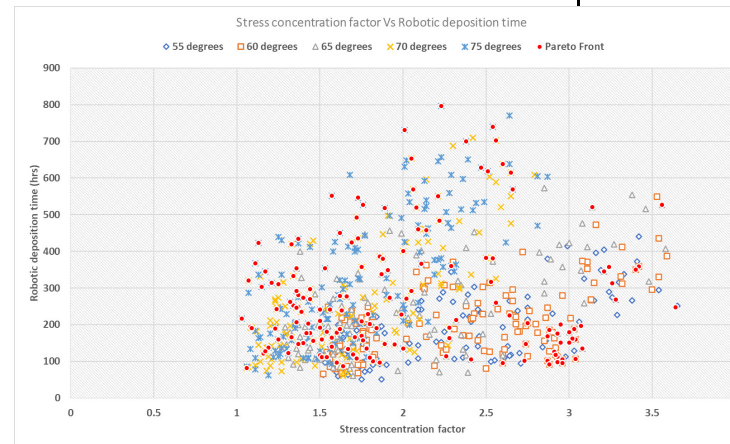
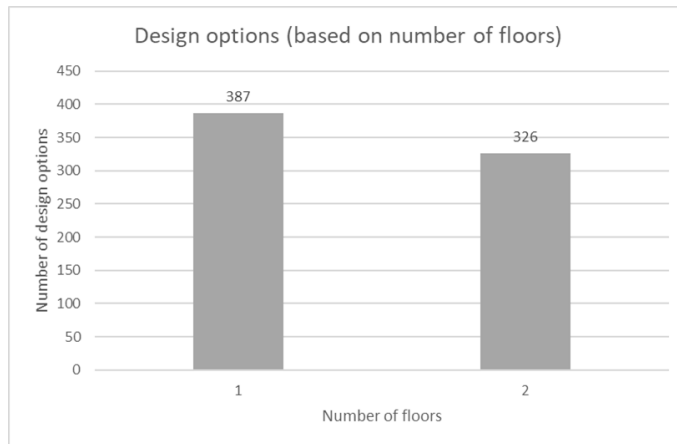
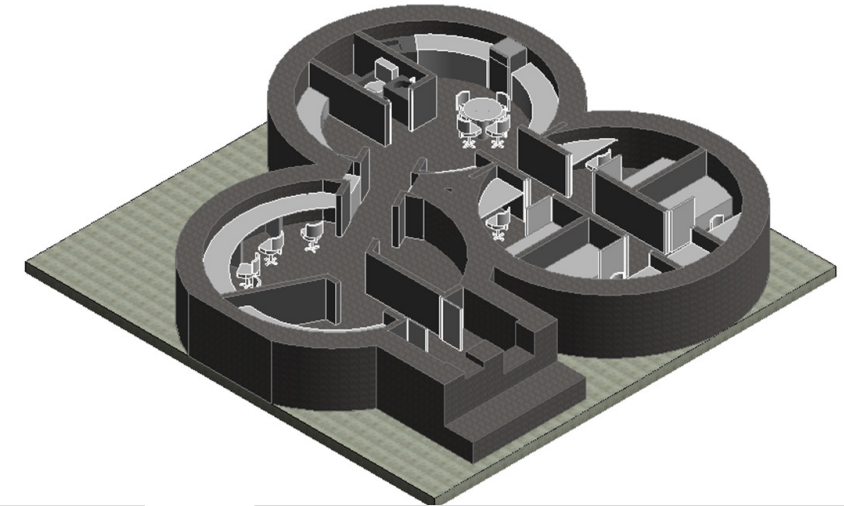
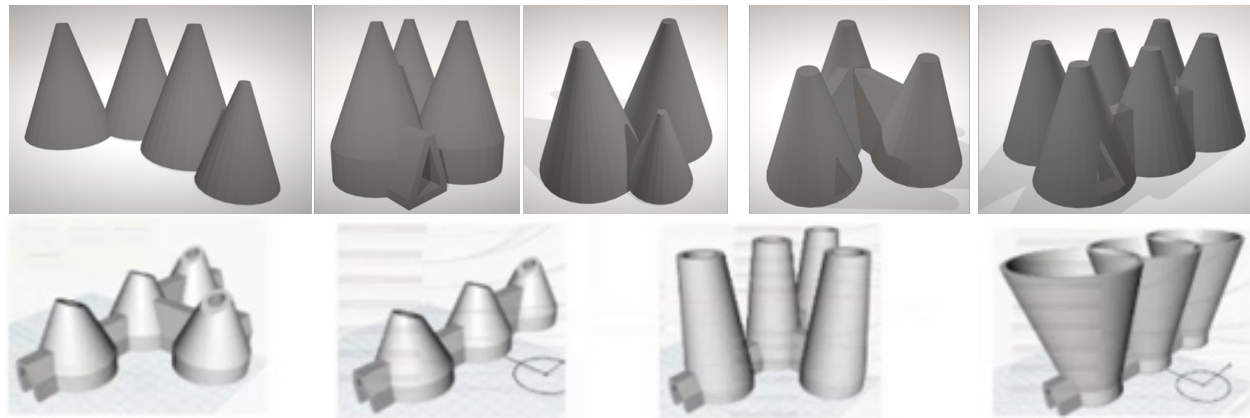
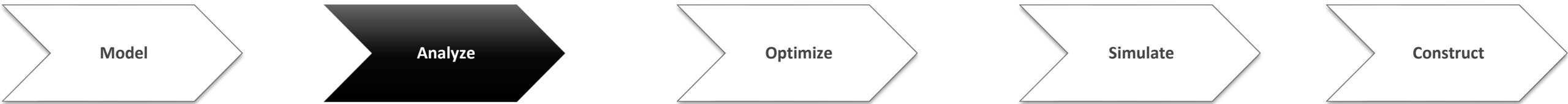


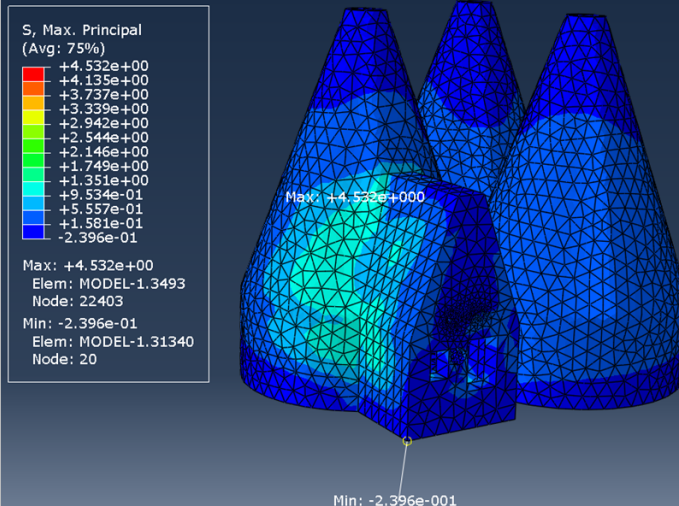
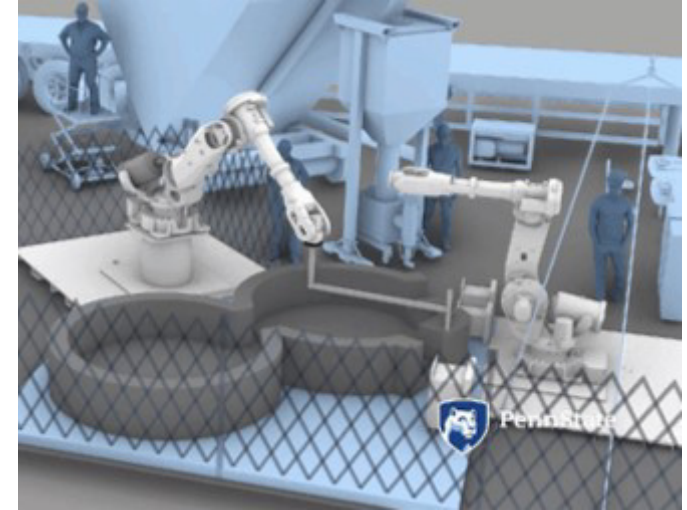
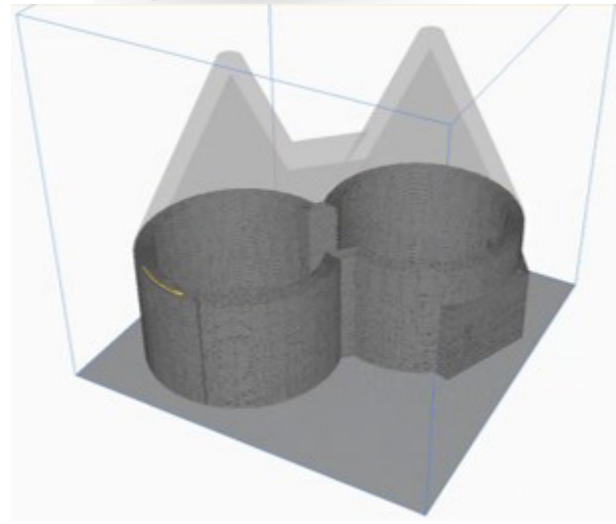
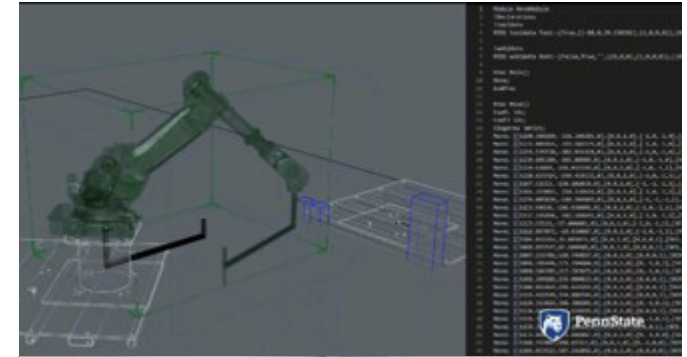
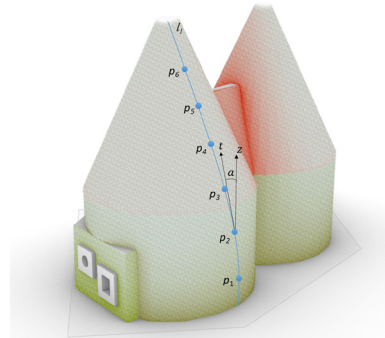
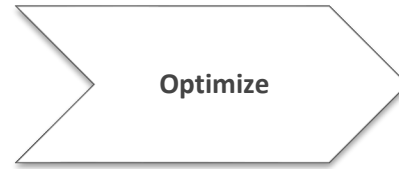
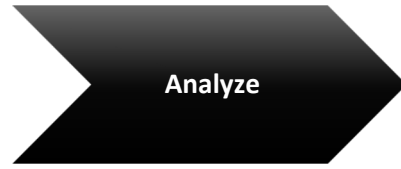
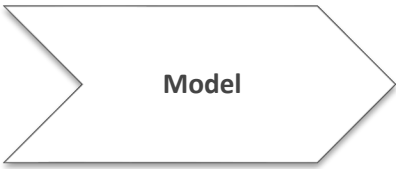






The image displays two software windows side-by-side. The left window is Autodesk Revit, showing a 3D model of a Mars habitat with a gabled roof and several circular modules. The right window is Dynamo, showing a 'STRATEGY' diagram with various parameters and connections. The text 'PARAMETRIC BIM DESIGN WITH DYNAMO' is overlaid at the bottom of the Revit window.

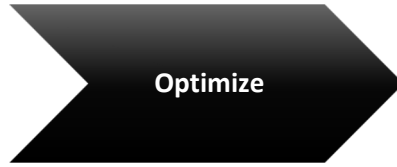
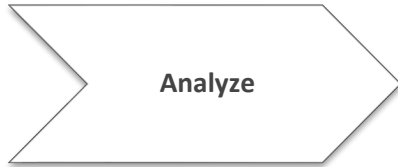
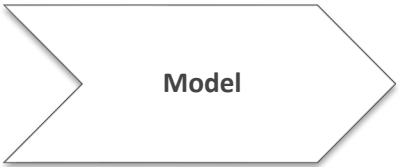




STRUCTURAL ANALYSIS

TOOLPATH FAILURE DETECTION

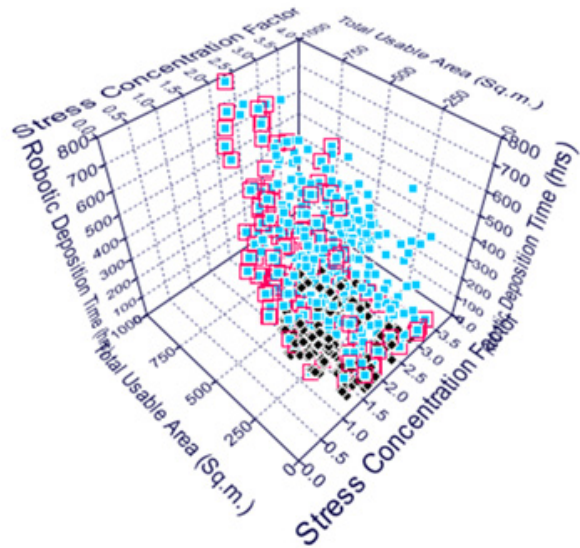
TOOLPATH CLASH DETECTION



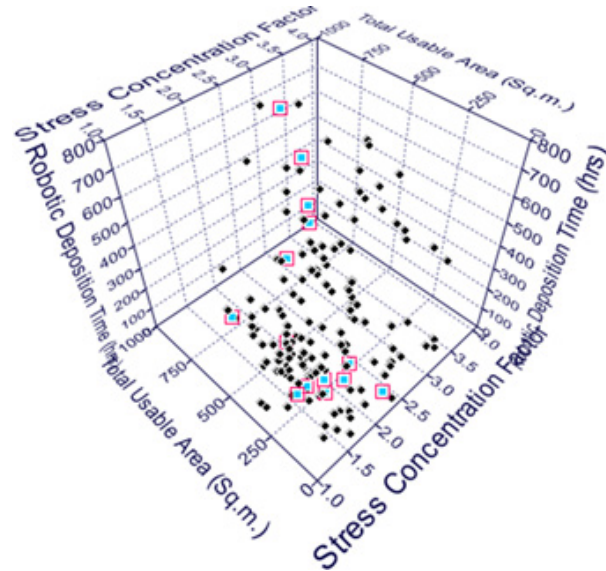
Conceptual

Preliminary

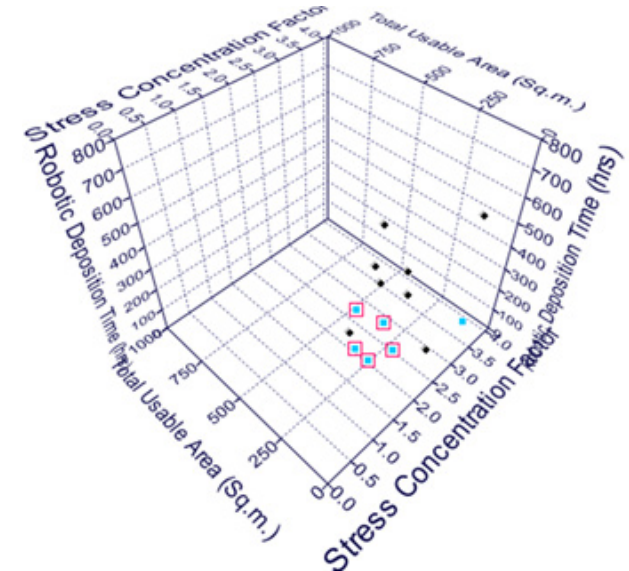
Detailed



Total = 713
 Feasible = 523
 Pareto = 158

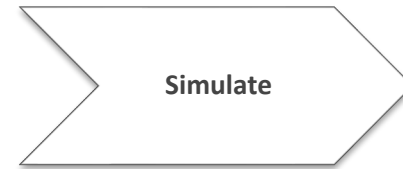
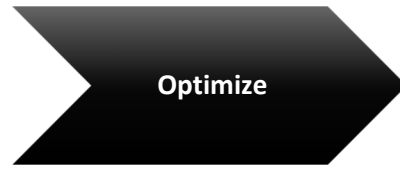
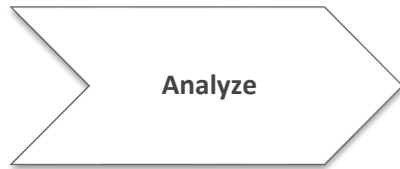
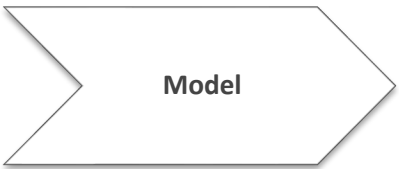


Total = 158
 Feasible = 14
 Pareto = 14



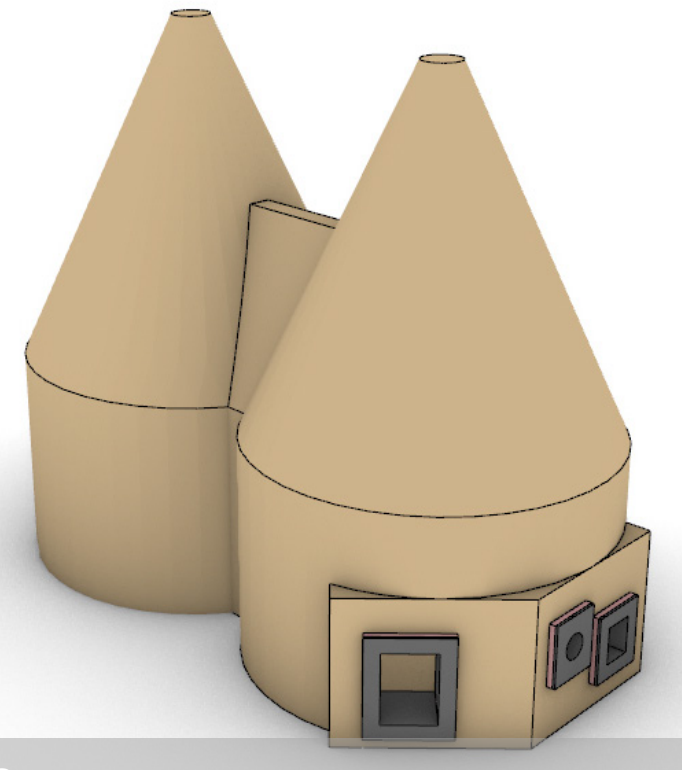
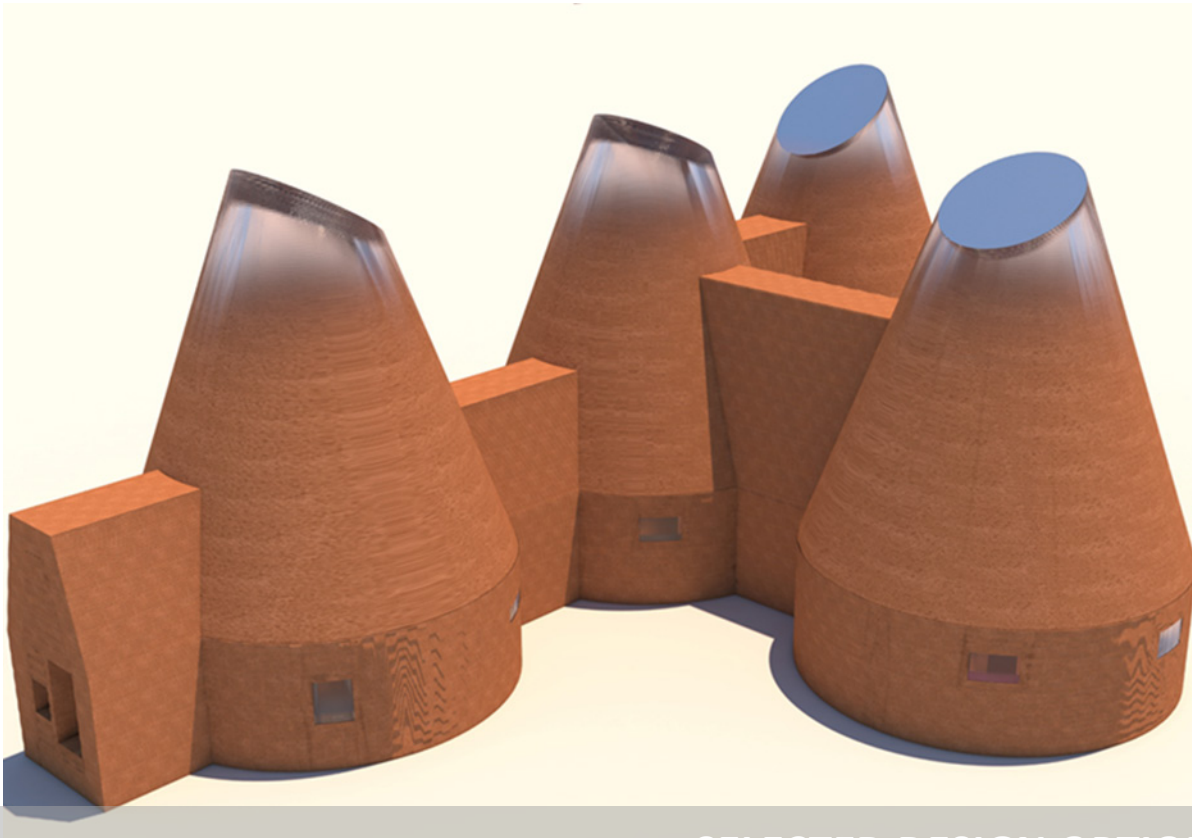
Total = 14
 Feasible = 6
 Pareto = 5

◆ Unfeasible ■ Feasible ■ Pareto

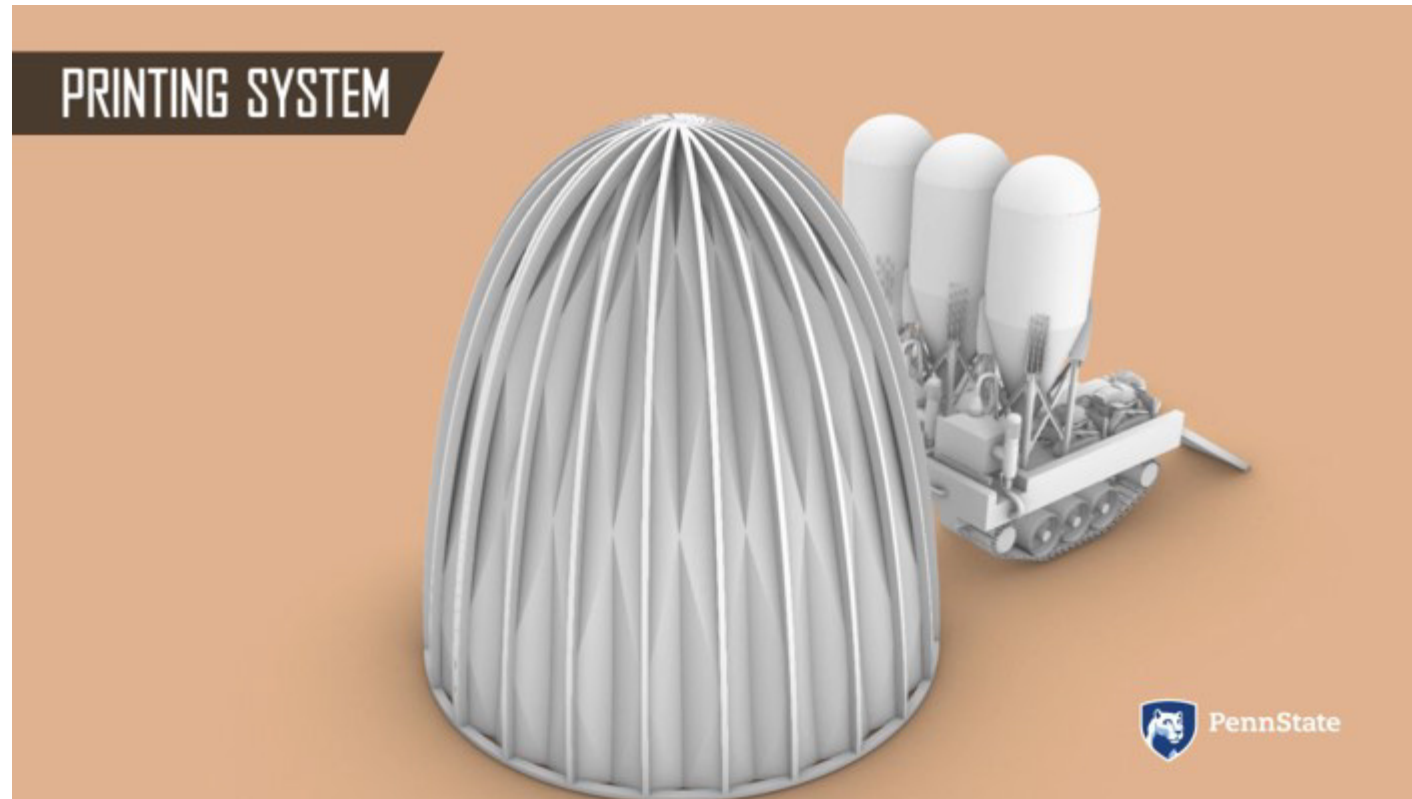
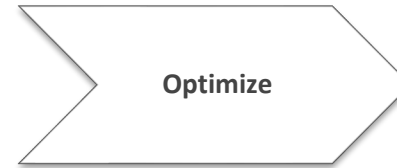
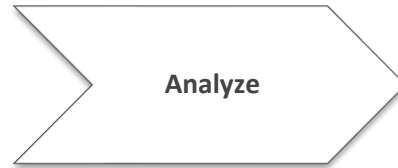
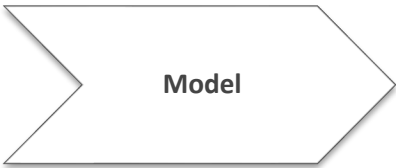


VIRTUAL CONSTRUCTION LEVEL
MARS

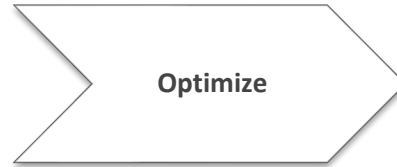
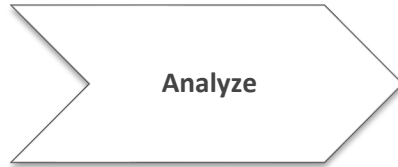
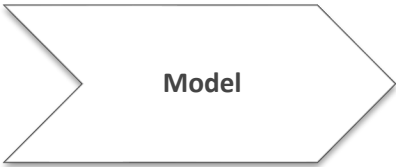
ACTUAL CONSTRUCTION LEVEL
EARTH



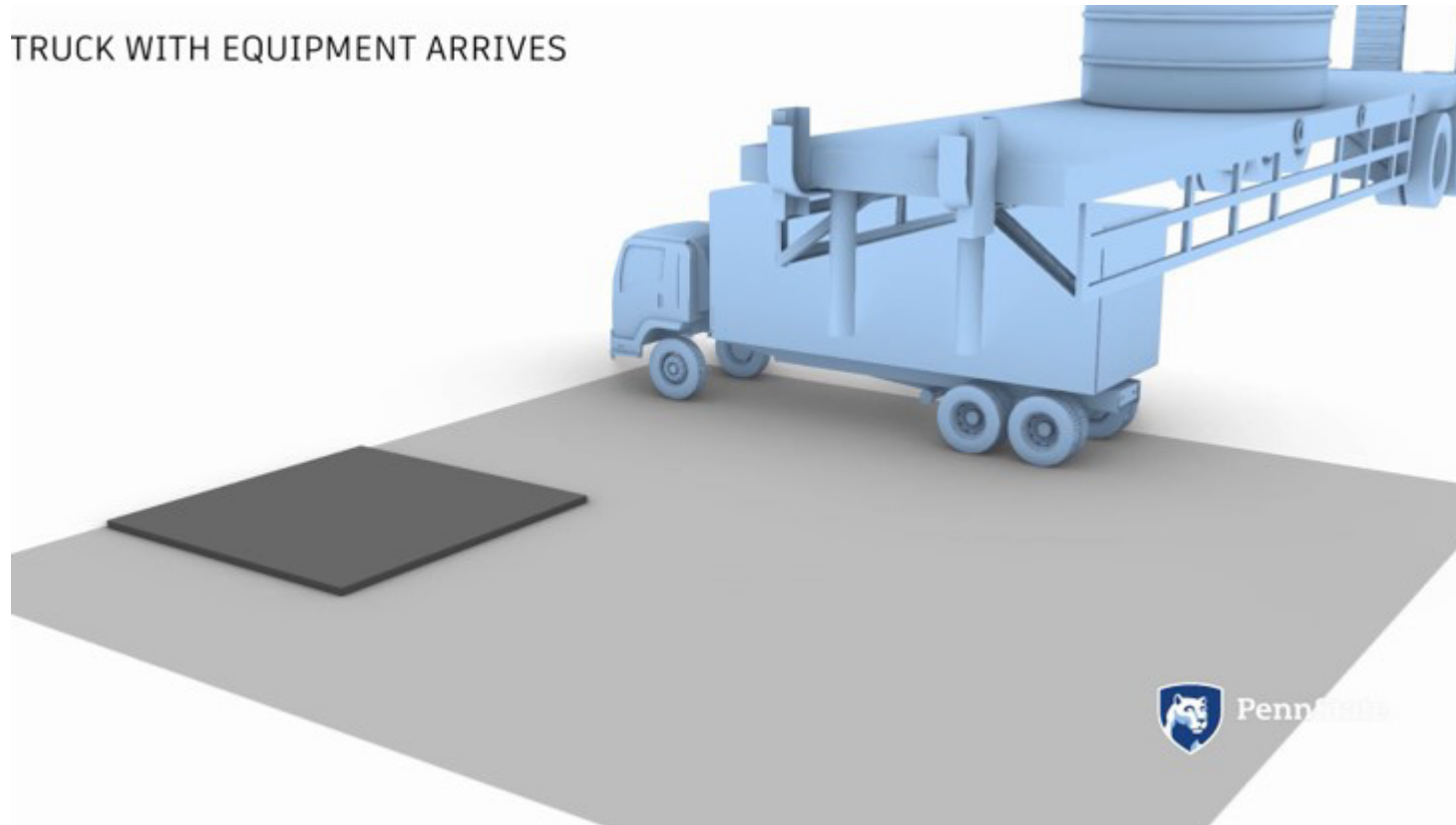
SELECTED DESIGN OPTIONS



4D SIMULATION (VIRTUAL CONSTRUCTION). CREDITS – EDUARDO COSTA + NEGAR ASHRAFI + NAVEEN



TRUCK WITH EQUIPMENT ARRIVES



4D SIMULATION (ACTUAL CONSTRUCTION). CREDITS - NAVEEN KUMAR MUTHUMANICKAM

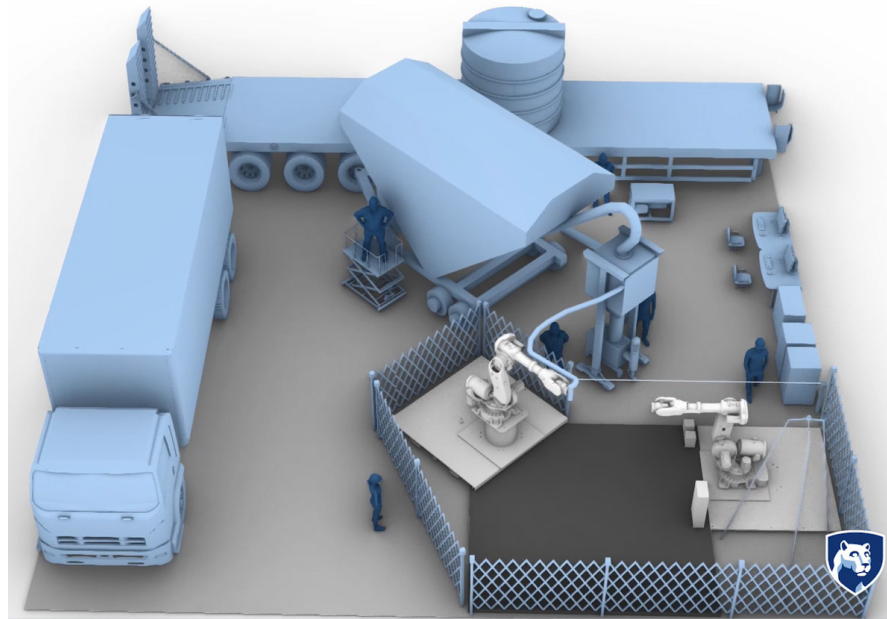
Model

Analyze

Optimize

Simulate

Construct



ACTUAL CONSTRUCTION AT FINALS IN PEORIA, ILLINOIS

Model

Analyze

Optimize

Simulate

Construct



ACTUAL CONSTRUCTION AT FINALS IN PEORIA, ILLINOIS

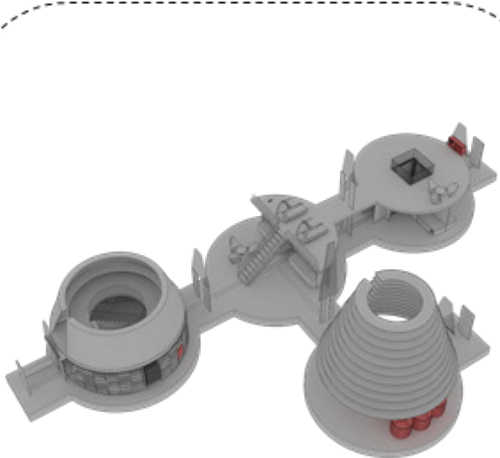


WORLD'S
FIRST
FULLY ENCLOSED TAPERED
CONCRETE STRUCTURE
3D PRINTED
WITHOUT SUPPORT STRUCTURE

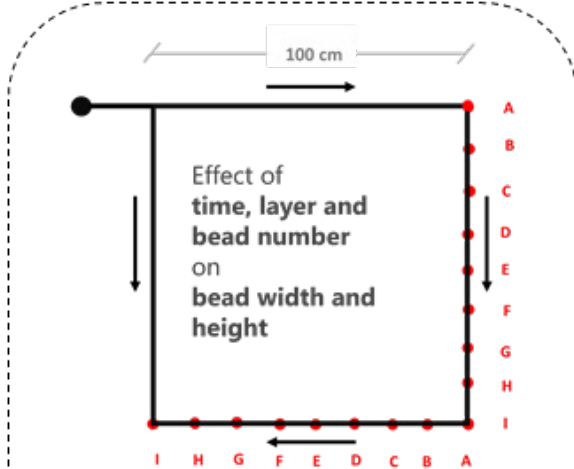
Muthumanickam, N. K., Duarte, J. P., Nazarian, S., Memari, A., & Bilén, S. G. (2021). Combining AI and BIM in the design and construction of a Mars habitat. In *The Routledge Companion to Artificial Intelligence in Architecture* (pp. 251-279). Routledge. <https://doi.org/10.4324/9780367824259-17>

Design for Industrialized & Robotic Construction

SYSTEMS DESIGN



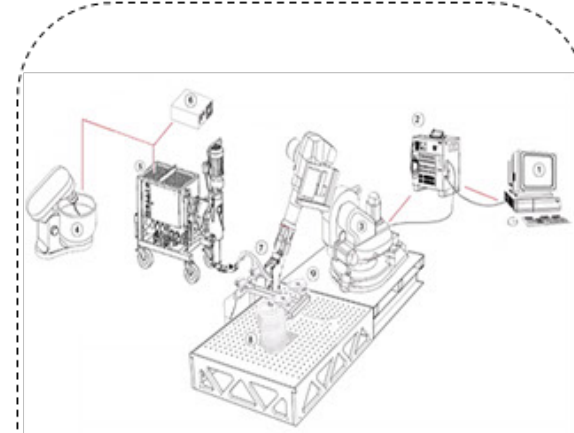
TOOLPATH DESIGN

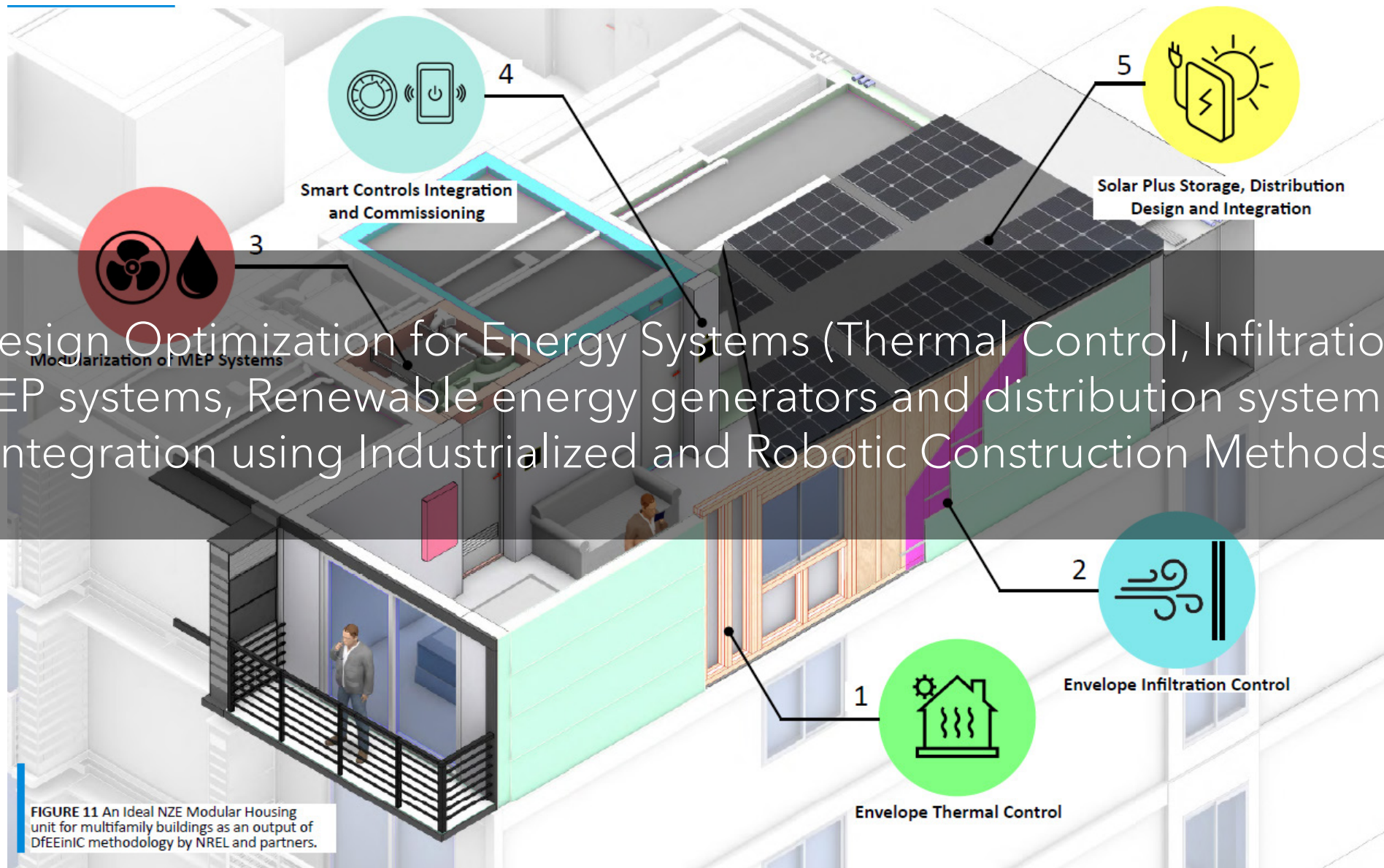


MATERIAL DESIGN

Admixtures	Water	Superplasticizer	G Powder
Binder	Cement	Silica Fume	Slag
Aggregates	River Sand	Or Basalt Sand	PP Fiber

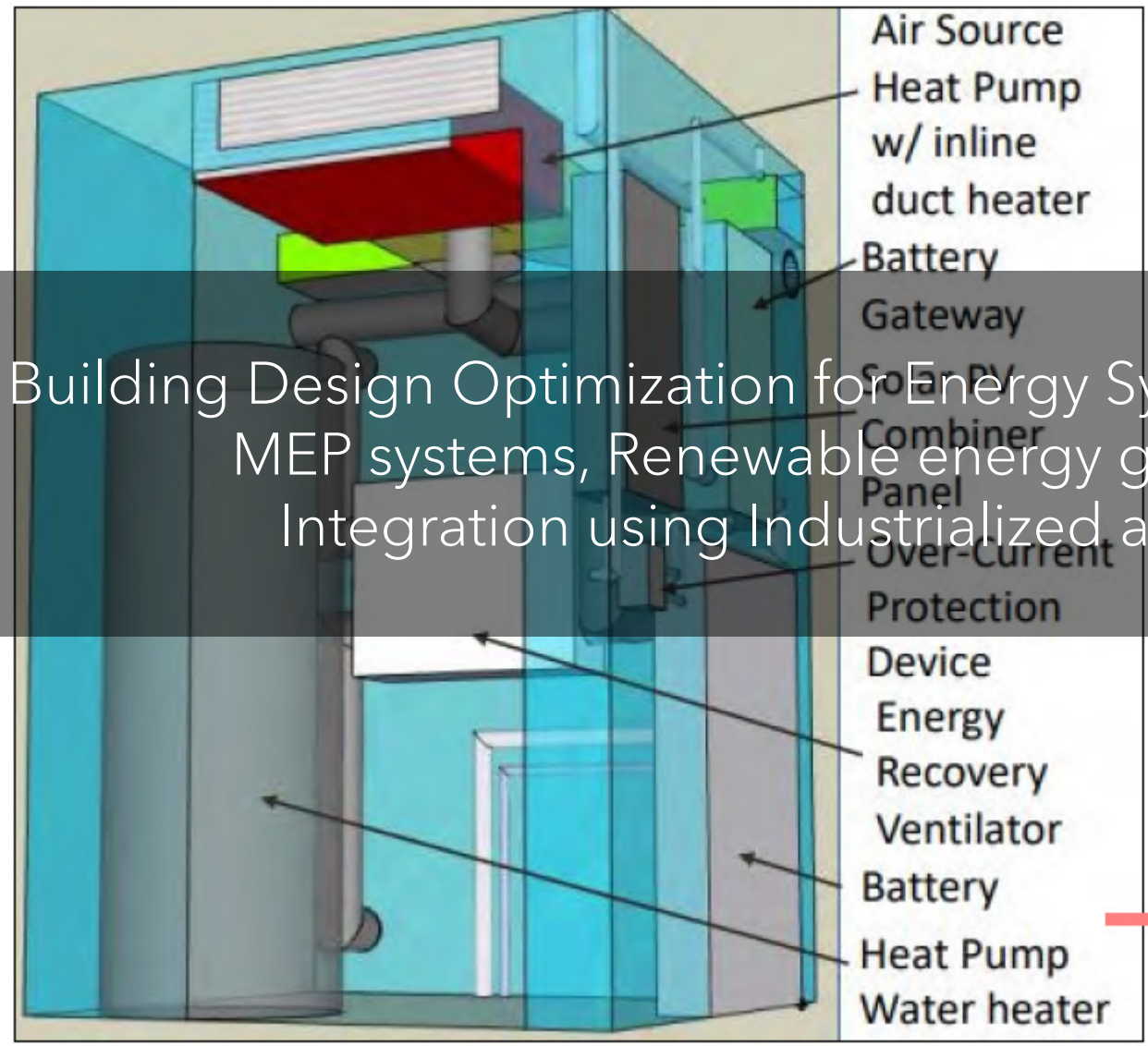
PRODUCTION DESIGN





Building Design Optimization for Energy Systems (Thermal Control, Infiltration Control, MEP systems, Renewable energy generators and distribution systems) Integration using Industrialized and Robotic Construction Methods

FIGURE 11 An Ideal NZE Modular Housing unit for multifamily buildings as an output of DfEEinIC methodology by NREL and partners.



Building Design Optimization for Energy Systems (Thermal Control, Infiltration Control, MEP systems, Renewable energy generators and distribution systems) Integration using Industrialized and Robotic Construction Methods



FIGURE 30 Illustrating 3D design of VEIC's Mechanical Pod for ZEM homes.

Modelling and Simulation Efforts – Factory Information Model Industry Partner : KBS Factory

Offsite Production Process Optimization for Energy Systems Integration





Onsite Installation Process Optimization for Energy Systems Integration

Preparing to load the model...

E-ROBOT Prize Winners

Phase 1 Winner



Apellix Aerial Robotics Spray Painting...
[Drone for Applying Multifunctional Control Lay...](#)



Avideh Zakhor's team
[Drone thermography for Building Envelope Retr...](#)



Avideh Zakhor's team
[Robotic system for air sealing /insulating attics](#)



Friendly Robots Company
[The Mayfly and the Aardvark](#)



FunForm
[Robotic Assisted Exterior Insulated Finish Syste...](#)



NU Team PARIS
[Precise Air-sealing Robot for Inaccessible Spa...](#)



NYU E-ROBOT
[EASEEbot](#)



Team F.G.S. – Revolutionizing Robotic R...
[Team F.G.S. – Revolutionizing Robotic Retrofits](#)



Team R-STRIPE
[The R-STRIPE Deep Energy Retrofit System](#)



wall-EIFS
[wall-EIFS](#)

Grand Prize Winner



Avideh Zakhor's team
[RoboAttic](#)



Friendly Robots Company
[The Mayfly and the Aardvark](#)



Team F.G.S. – Revolutionizing Robotic R...
[Unified Retrofits – Holistic Robotic Retrofits](#)

DOE E-Robot Prize TA – Robots for Energy Systems Integration In Buildings

67

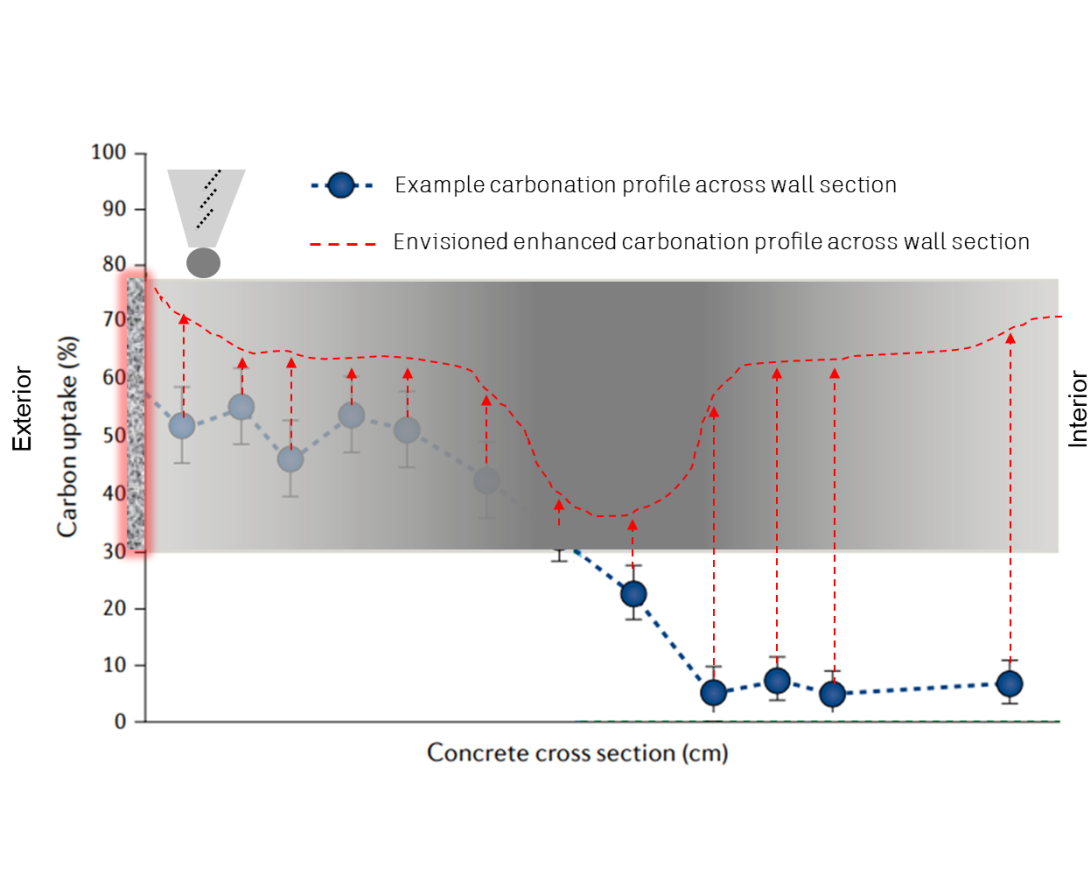
Teams

434

Innovators

Robotic Technology For Structural/Energy Systems and Service Installation in 3D Printed Buildings





Functionally graded 3D printing to increase porosity

- Increased porosity near wall surface for increased CO₂ uptake
- Gradual densification in middle for structural load bearing

Demolition waste spray

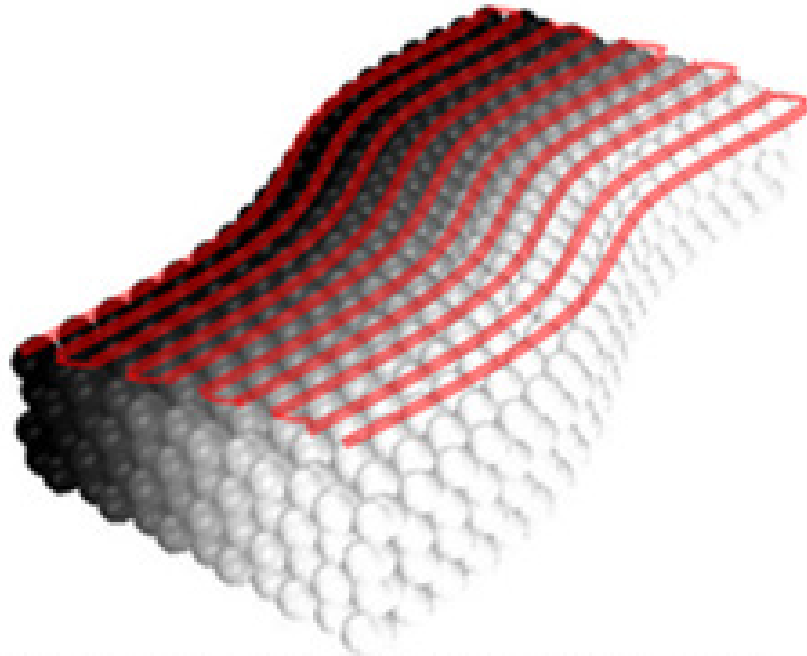
- Increased SA
- Increased Carbonation
- Increased CO₂ uptake

Short fiber reinforcement using rotational 3D printing that

- can act as chemically passive structural reinforcement
- is suitable to be infused within extrudable concrete paste

NREL ICI Proprietary Information

NREL ICI Proprietary Information



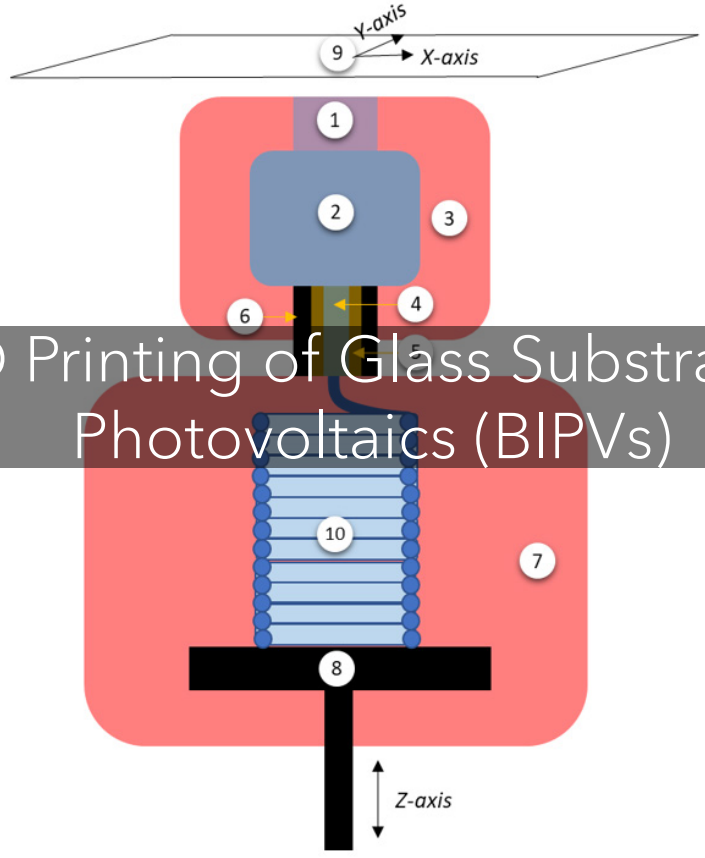
CAD model of toolpath (red) for functionally graded concrete (gradation indicated with color)



Accelerates Carbonation

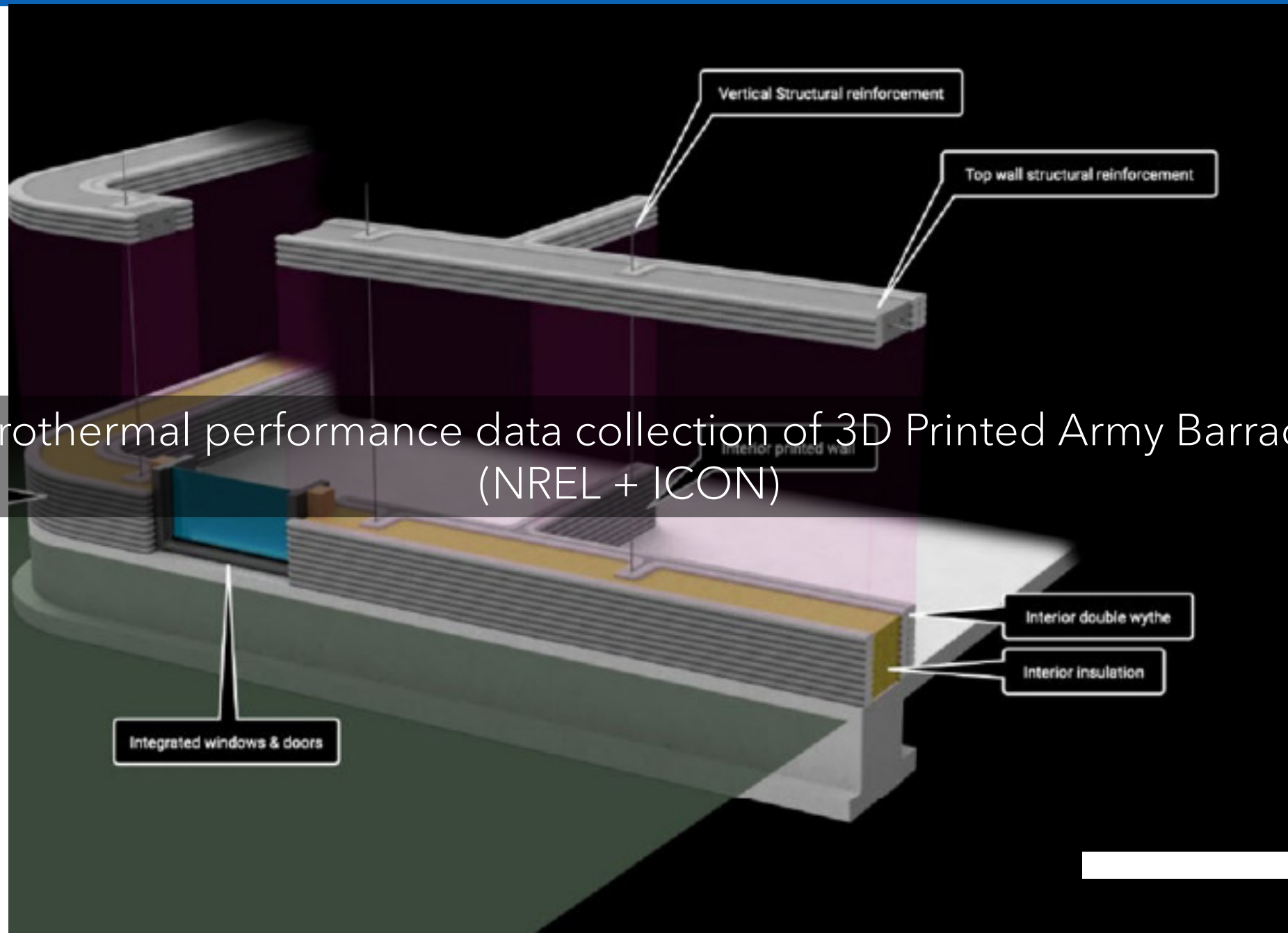
Robotic Deposition Technology To Control Microstructure of Concrete in 3D Printed Walls for Increased CO₂ Uptake

Robotically Controlled Electron Beam for Accelerated Curing Cementitious Materials in 3D Printing (Argonne + Fermi Lab + NREL)



Robotically Controlled 3D Printing of Glass Substrates for Building Integrated Photovoltaics (BIPVs)

Hygrothermal performance data collection of 3D Printed Army Barracks (NREL + ICON)



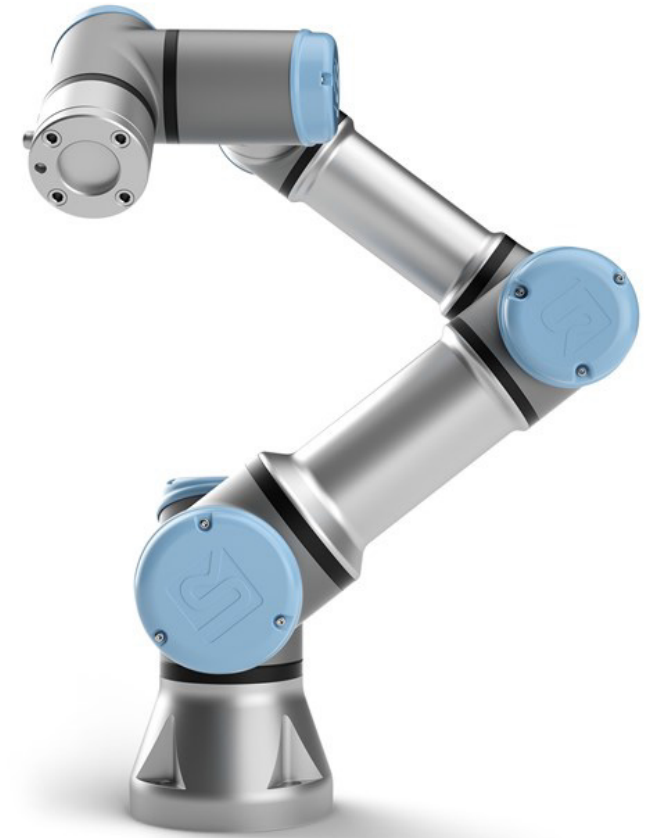
Ongoing discussions about a potential project to 3D Print test house for Nome community in Alaska with emphasis on hygrothermal aspects of 3D printed buildings in extreme climates (**permafrost conditions, extreme temperature gradients**)

NREL ICI Proprietary Information

With CCHRC - Under Discussion

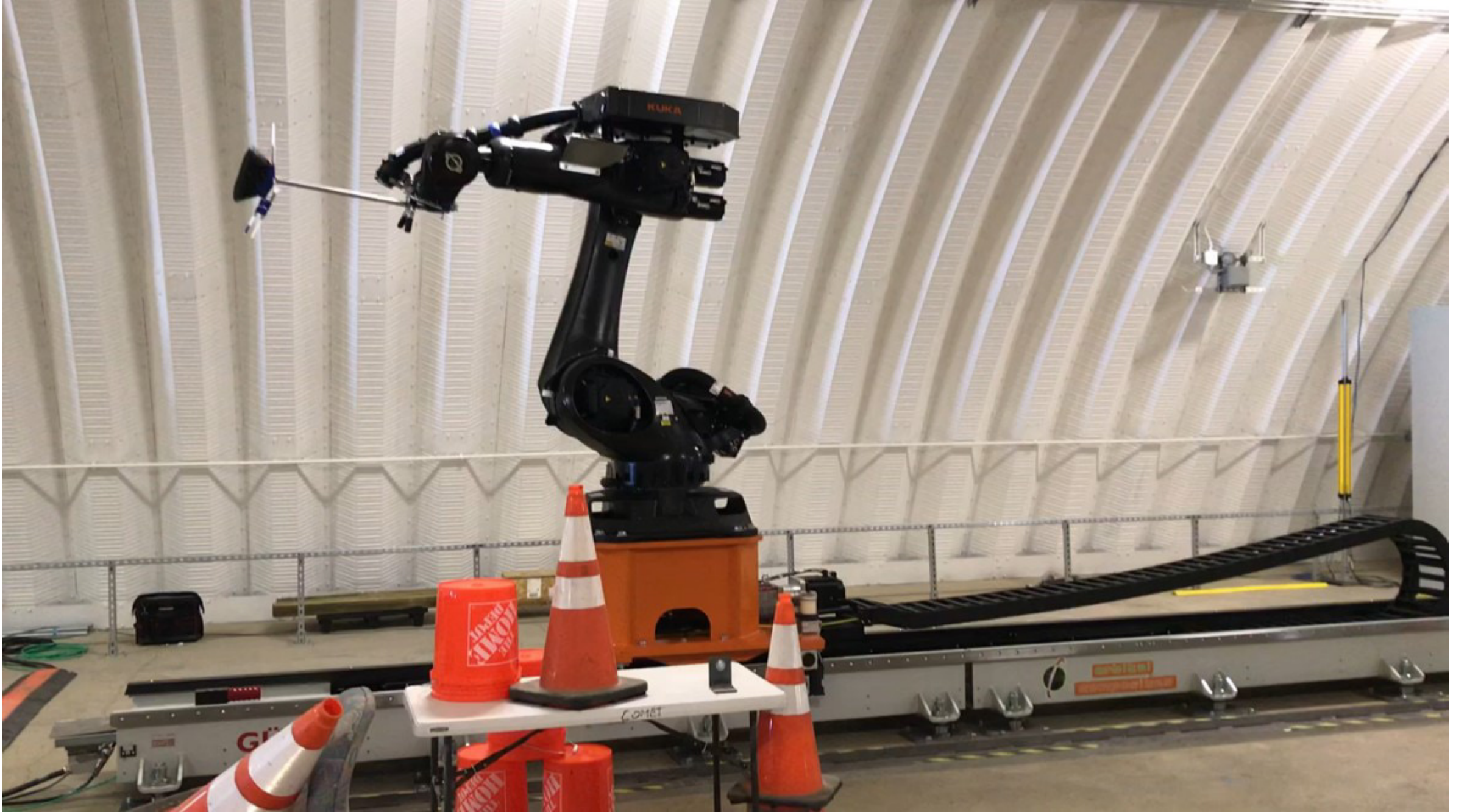


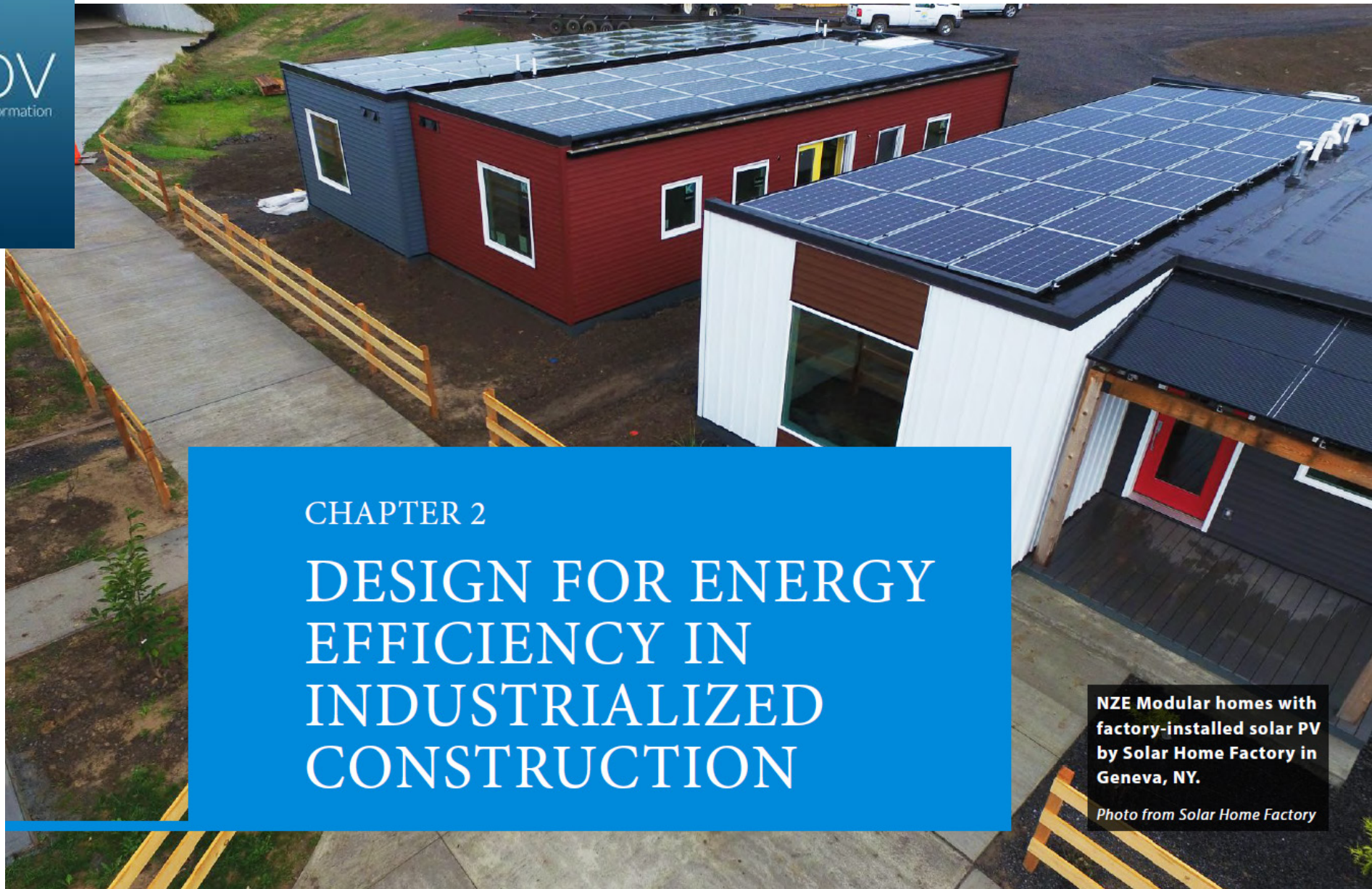
Larger industrial robot at Composite Manufacturing and Engineering Technology (CoMET) facility of NREL



Smaller industrial COBOT for small scale testing - Building Systems Outfitting - autonomous Pick and Place







CHAPTER 2

DESIGN FOR ENERGY EFFICIENCY IN INDUSTRIALIZED CONSTRUCTION

**NZE Modular homes with
factory-installed solar PV
by Solar Home Factory in
Geneva, NY.**

Photo from Solar Home Factory

THE ENERGY IN MODULAR (EMOD) BUILDINGS METHOD

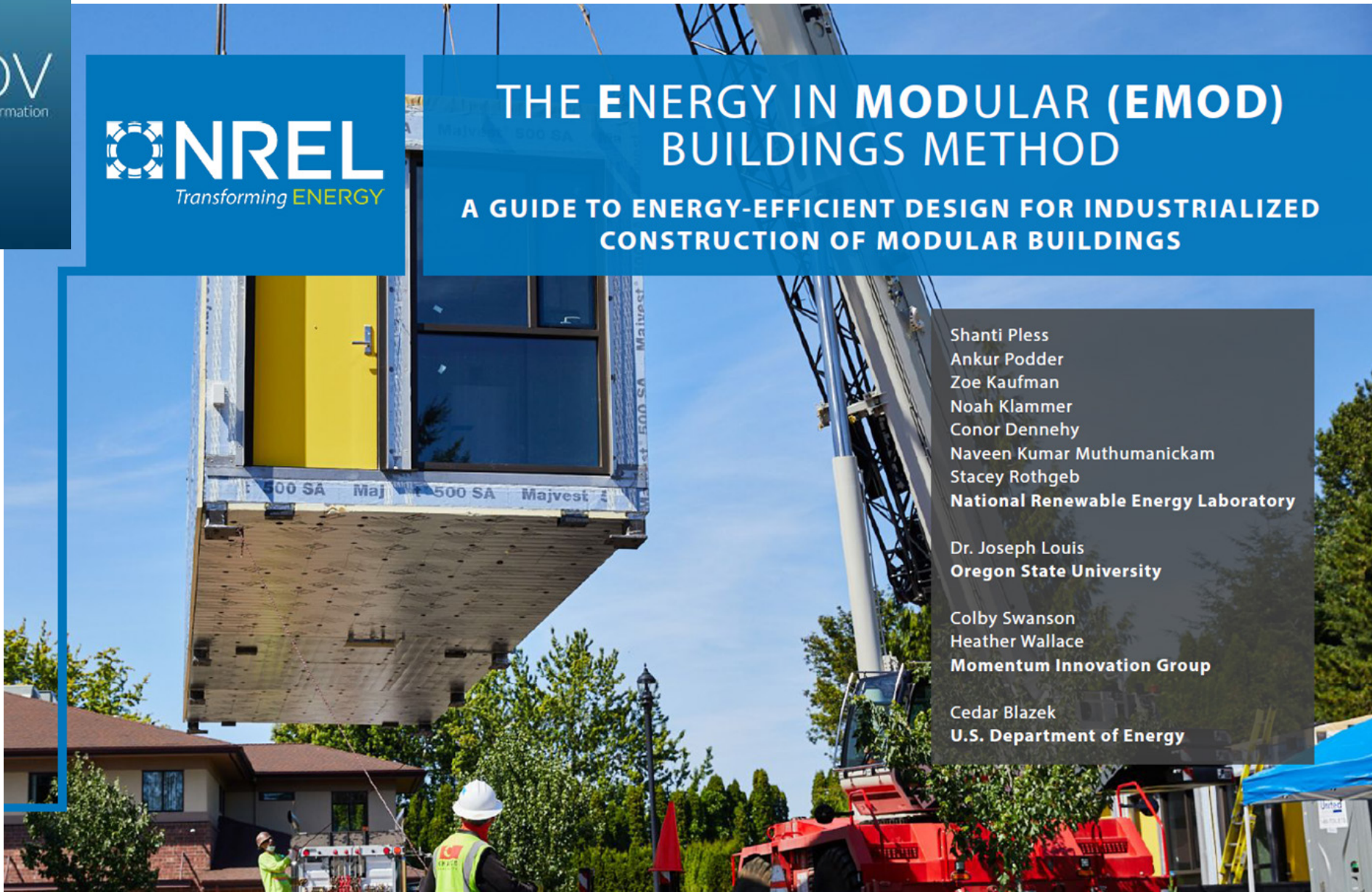
A GUIDE TO ENERGY-EFFICIENT DESIGN FOR INDUSTRIALIZED
CONSTRUCTION OF MODULAR BUILDINGS

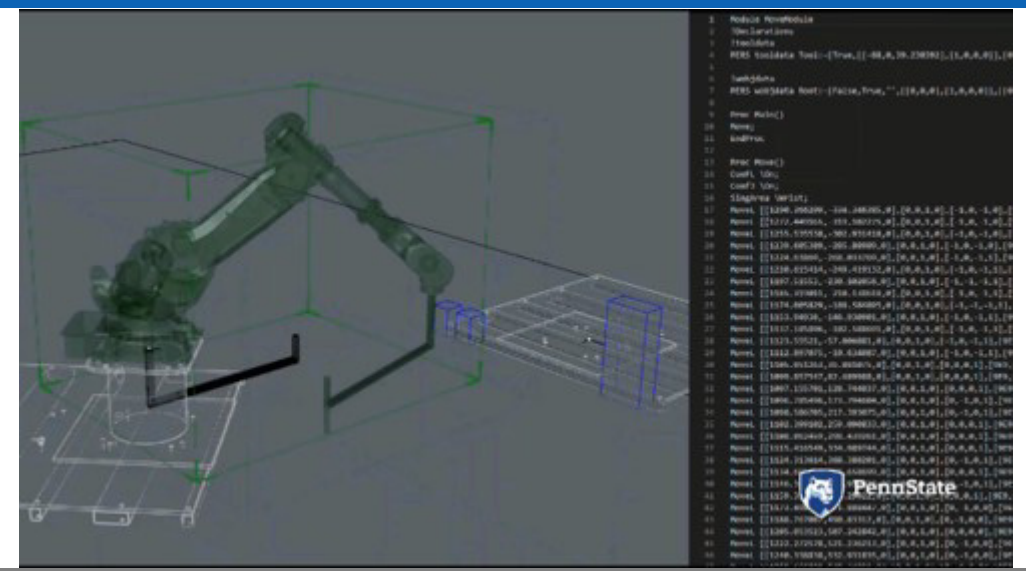
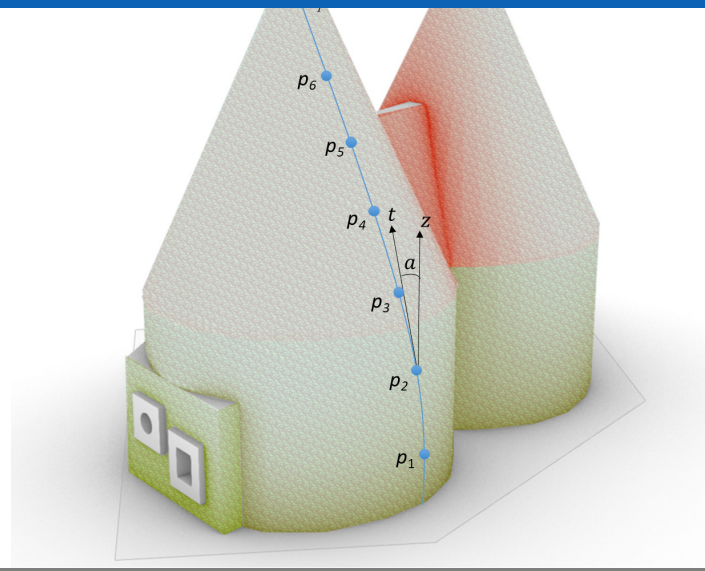
Shanti Pless
Ankur Podder
Zoe Kaufman
Noah Klammer
Conor Dennehy
Naveen Kumar Muthumanickam
Stacey Rothgeb
National Renewable Energy Laboratory

Dr. Joseph Louis
Oregon State University

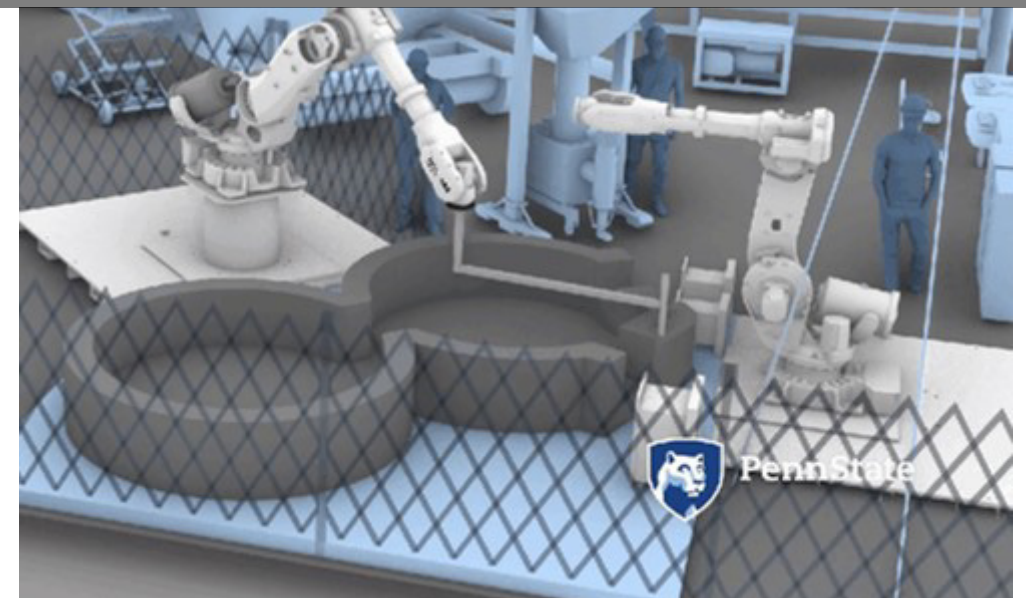
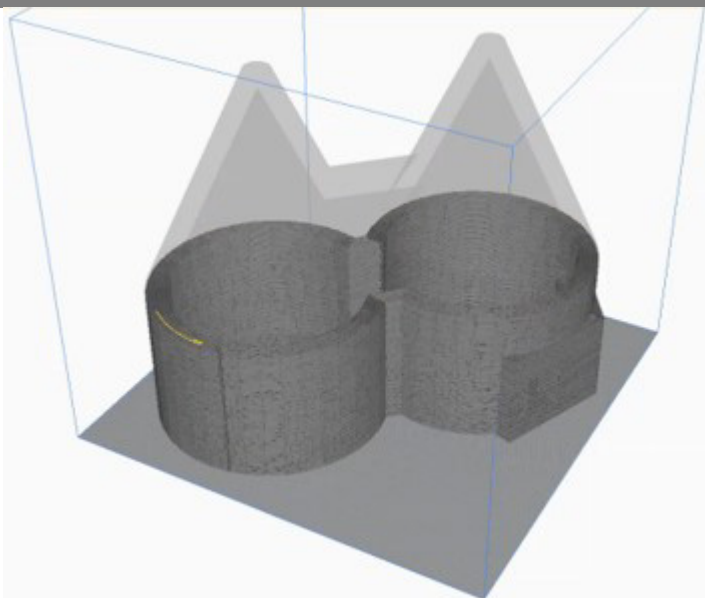
Colby Swanson
Heather Wallace
Momentum Innovation Group

Cedar Blazek
U.S. Department of Energy





Muthumanickam, N.K., Duarte, J.P., Nazarian, S., Bilén, S. G., & Memari, A. (2022). **Metamodels for rapid analysis of large sets of building designs for robotic constructability: Technology demonstration using the NASA 3D Printed Mars Habitat Challenge.** In Proceedings of the American Society of Civil Engineers Earth & Space Conference, ASCE Earth & Space 2022. April 25-28, 2022. Denver, CO. <https://learn.mines.edu/earthspace2022/>

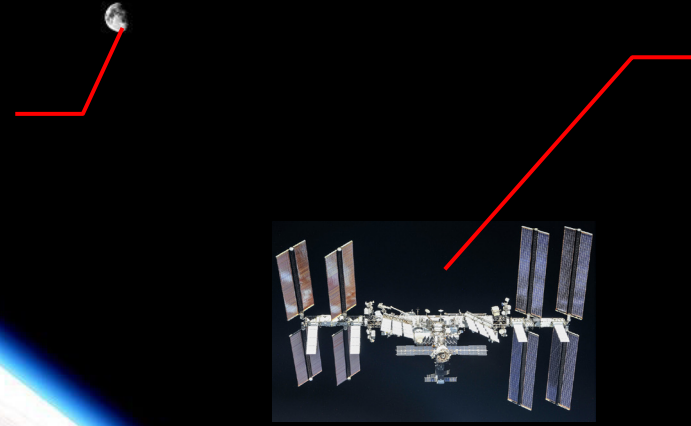


Terrestrial Vs Extra Terrestrial Construction

Building on extra-terrestrial bodies

a system of systems that are functional

- structurally stable
- energy efficient
- thermally efficient
- habitable****
- remotely constructable
- easily deployable
- remotely controllable



Building in orbital space

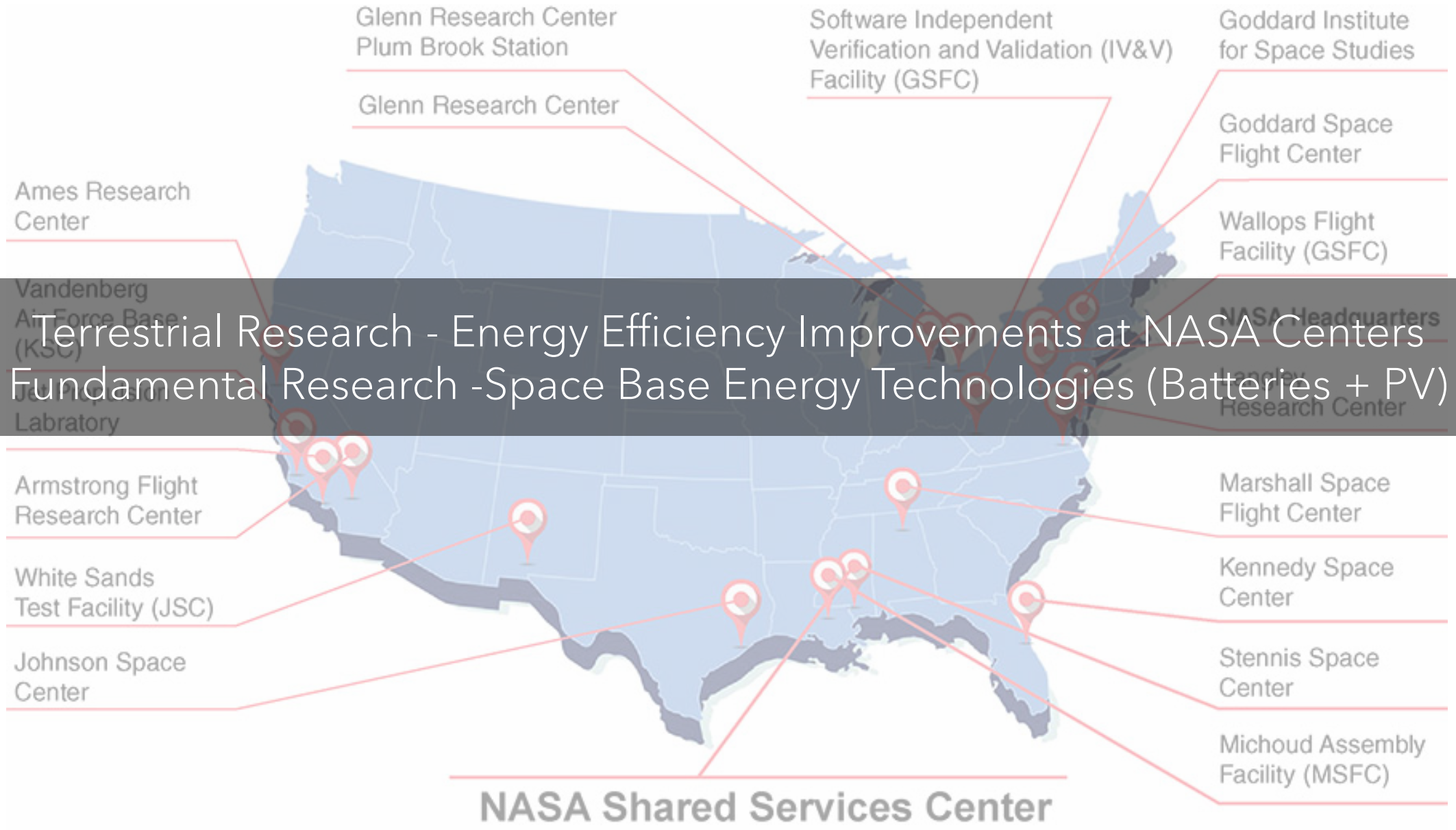
a system of systems that are functional

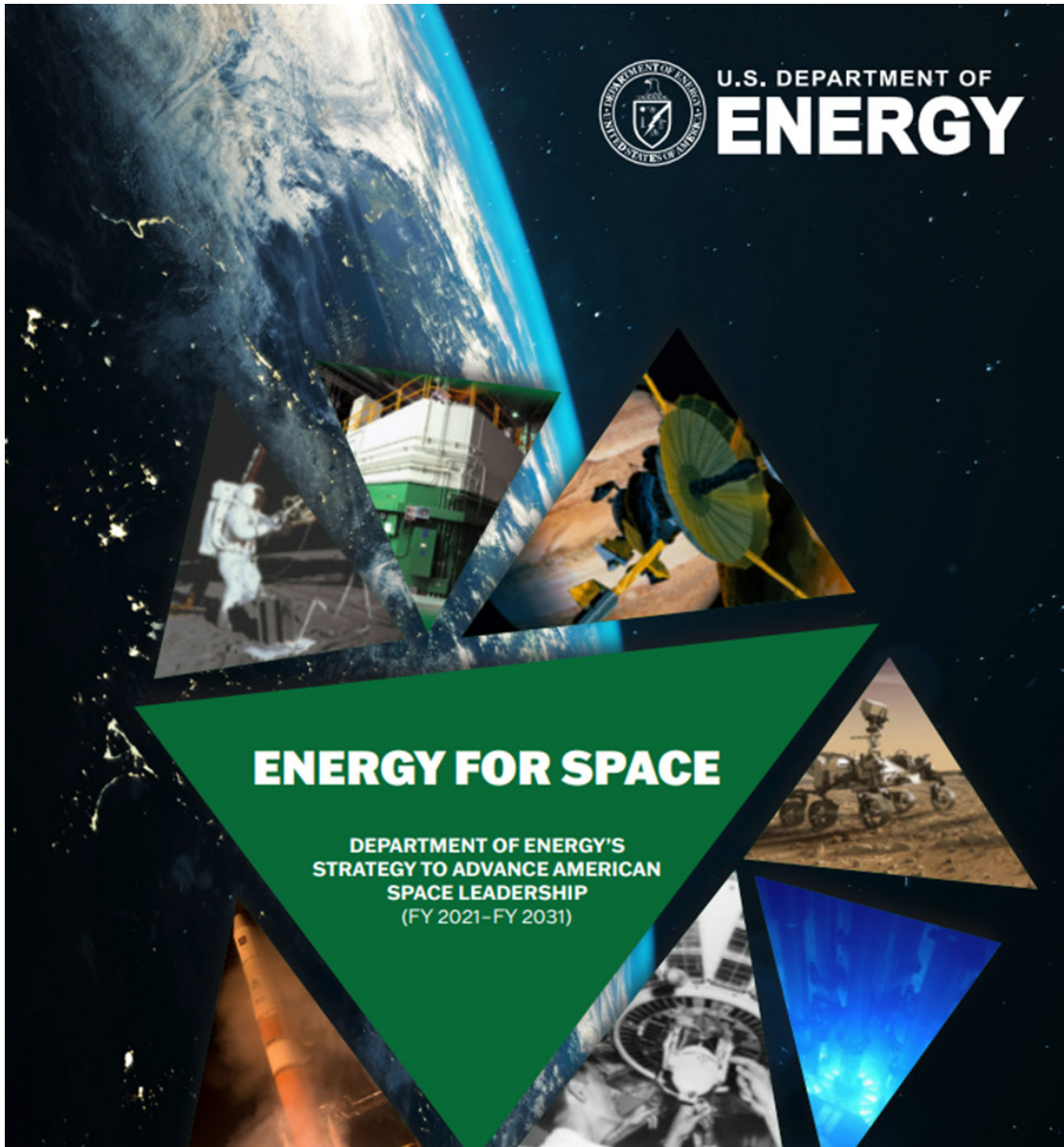
- structurally stable
- energy efficient
- thermally efficient
- habitable****
- easily deployable (or assembly)
- remotely controllable

Building on Earth

a system of systems that are functional

- structurally stable
- energy efficient
- thermally efficient
- habitable****
- rapidly constructable





S&T Capacity. As the largest sponsor of basic scientific research and development (R&D), DOE has built a diverse community of interdisciplinary S&T talent within the complex of National Laboratories and throughout U.S. colleges and universities. This world-leading S&T expertise can be brought to bear on answering the most difficult challenges facing U.S. space missions.

- **R&D Infrastructure.** DOE supports the world's most advanced and unique scientific facilities. These facilities support researchers both in the United States and abroad in advancing our understanding of the universe, from the subatomic scale to the cosmic scale. The discoveries made possible by these facilities push the boundaries of human knowledge across many scientific disciplines.

- **Emerging/Innovative Capabilities.** DOE provides expert knowledge and world-leading capabilities in nuclear and non-nuclear energy technologies, artificial intelligence (AI) and robotics, high-speed information technology, advanced manufacturing, microelectronics, materials for extreme environments, radiation science, isotope production, and a host of other areas. This engine of discovery can power crewed missions to the Moon and beyond, as well as pave the way for human habitats and a sustained presence on the surface of other planetary bodies.




- **Technology Commercialization.** DOE is one of the largest supporters of technology transfer in the federal government. Thus, DOE's R&D investments can aid in accelerating the commercialization and industrialization of space, forge new capabilities for sustainable expansion into the solar system, and provide benefits for life on Earth.

NASA's MMPACT

In Situ Fabrication and Repair



OES

<p>FABRICATION OF TOOLS AND PARTS WITH THE FOLLOWING EMPHASIS:</p> <ul style="list-style-type: none"> - Feedstock flexibility (In Situ, provisioned, recycled) - Miniaturization - Speed - Part accuracy and surface finish - Multi material  <p>First Microgravity Flight</p>	<p>REPAIR CAPABILITIES WITH THE FOLLOWING EMPHASIS:</p> <ul style="list-style-type: none"> - Unique material properties - Environmental performance - In Situ processes  <p>Welding</p>	<p>HABITAT STRUCTURES CAPABILITIES WITH THE FOLLOWING EMPHASIS:</p> <ul style="list-style-type: none"> - Radiation shielding features - Use of In Situ resources - Autonomous construction  <p>Habitable Coaxial Structure</p>	<p>NON DESTRUCTIVE EVALUATION CAPABILITIES WITH THE FOLLOWING EMPHASIS:</p> <ul style="list-style-type: none"> - Independent quality assurance of In Situ processes - Integrated closed loop control of In situ process - Failure analysis and routine inspection applicability  <p>Measuring Machine/Laser Scan</p>	<p>RECYCLING CAPABILITIES WITH THE FOLLOWING EMPHASIS:</p> <ul style="list-style-type: none"> - Reuse of failed parts & waste materials - Limitation of waste stream variety - Simplification  <p>Reactor</p>
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SYSTEM OF SYSTEMS / APPLICABILITY AND CONSIDERATION:
 - Mobile Army Parts Hospital
 - Interoperability between ISFR, FAB, REPAIR, NDE, RECYCLING, and, HAB concepts

NREL ICI Focus Areas

<p>Offsite Prefabrication of Building Systems</p> <ul style="list-style-type: none"> • Heating Systems • Cooling Systems • Energy Generators • Energy Storage • Energy Distribution 	<p>Building Retrofit automation</p> <ul style="list-style-type: none"> • Envelope • Thermal • Energy • Renewables 	<p>Robotic Automation in Construction</p> <ul style="list-style-type: none"> • Hygrothermal control layer installation • Energy Generator Installation • Energy Storage systems Installation • Energy Distribution Systems Installation 	<p>Non-destructive evaluation of Buildings</p> <ul style="list-style-type: none"> • Sensors for multi-modal data collection of hygro-thermal and energy performance of buildings. • Autonomous robots for remote monitoring of building energy systems • Digital twins 	<p>Recycling</p> <ul style="list-style-type: none"> • Circular Economy Strategies • BIM based serialization of construction assets for material tracking • Material Flow tracking using supply chain tools like CELAVI/MFI
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Process Simulation Of Robotics For Systems Integration/Outfitting In Buildings

Computational simulation of robots performing control layer, energy systems and services installation

Robotic Technologies For Outfitting Of Buildings

Robotic technology development to install hygrothermal control layers in envelopes, energy generation, distribution and storage systems

Autonomous Non-destructive Evaluation of Buildings

Autonomous robots and sensor technologies to evaluate thermal, hygrothermal and energy performance of buildings using multi-modal data collection and digital twins

Thank you!



INDUSTRIALIZED CONSTRUCTION INNOVATION

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RESEARCH ENGINEER

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NREL/PR-5500-83615