

### Predicting wind loading and instability in solar tracking PV arrays

Ethan Young, NREL

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### Motivation

Wind loads are an increasingly important design consideration for solar tracking PV arrays:

- Higher wind speeds can initiate unsteady aerodynamic instabilities (galloping) which can initialize cracks and/or destroy sections of the array.
- Moderate wind loads create unsteady, reversing that lead to the worsening of existing cell cracks over time.

1. E. Wesoff, "Trackers in wind and the terror of torsional galloping", PV Magazine, Jan 2020 2. T. Sylvia, "Trackers vs. the elements, part one: tackling uneven terrain", PV Magazine, May 2022















# Motivation

Complicating factors:

- Varying wind speeds/conditions
- Terrain and site layout
- Non-universal stow strategies



**Goal:** Understanding the **fluid-structure interaction (FSI)** driving this instability can improve panel stow guidelines and inform stabilizing layout and hardware design.











# Previous Work on Aerodynamic Stability









### Modeling Approach

- Solving the incompressible Navier-Stokes equations yields a torque at each node on the panel surface.
- Panels are treated as rigid masses linked with rotational springs.
- This mass-spring approximation is used to model the FSI problem.

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# Modeling Approach

• Fluid solution updates the position of the panel, new panel position (updated mesh) is used to solve the fluid.



Constant diffusivity:  $\nabla^2 \hat{x} = 0$ 





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### Results



#### Tracking angle: $\theta = +7.5^{\circ}$ Constant 40.5 m/s wind





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E. Young, X. He, R. King, and D. Corbus, "A Fluid-Structure Interaction Solver for Investigating Torsional Galloping in Solar-Tracking Photovoltaic Panel Arrays", Journal of Renewable and Sustainable Energy, Nov 2020

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Previous Work on Fixed-Angle Pressure Loading









# Modeling Approach



- Solution of Navier-Stokes equations using FEniCS
- Traction is measured along the surface of a downstream panel
- Wind speed at panel height and (fixed) panel angle are easily adjustable inputs



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### Results

- Without the complication of mesh motion, we can run these cases at a much higher fidelity.
- Inputs are simplified to enable large parameter sweeps.



 $\theta = 0^{\circ}$ 



$$\theta = -20^{\circ}$$



$$\theta = -40^{\circ}$$



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### Results









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### New Project: PVade

Awarded FY22 Core Modelling Call









### New Project: PVade

		~ <u>.</u>				PVade
3D Simulation			$\checkmark$		$\checkmark$	$\checkmark$
Large Rigid Body Motion		$\checkmark$	$\checkmark$			$\checkmark$
Structural Deformation	$\checkmark$					$\checkmark$
HPC Scalable				$\checkmark$	$\checkmark$	$\checkmark$
Accelerated Test Outputs				$\checkmark$		$\checkmark$
Optimization						$\checkmark$
Terrain						$\checkmark$











### PVade Overview

Developed using elements of DOLFINX, an open-source software for solving partial differential equations. Currently implemented features include:

- Ability to easily specify different panel geometries and layouts via input file
- Automatic generation of high-fidelity computational meshes
- Validated solution of Navier-Stokes using a fractional step method

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 High-performance computing (HPC) ready implementation of all methods

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$$\frac{\boldsymbol{u}^* - \boldsymbol{u}^k}{\Delta t} = \nu \nabla^2 \boldsymbol{u}^k - \boldsymbol{u}^k \cdot \nabla \boldsymbol{u}^k - \frac{1}{\rho} \nabla P^k \qquad (1)$$

$$\nabla \cdot \boldsymbol{u}^* = \Delta t \nabla^2 \phi \tag{2}$$

$$\boldsymbol{u}^{k+1} = \boldsymbol{u}^* - \Delta t \nabla \phi \tag{3}$$

$$P^{k+1} = P^k + \phi$$

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### Performance

• Each new method is written and tested to ensure scalable performance

Number of Threads	Process Binding	Solver for Eq. (1, 2, 3)	Precond. for Eq. (1, 2, 3)	Time per Iteration (s)	Speedup
18	Bind by board	(GMRES, GMRES, CG)	(HYPRE, HYPRE, Jacobi)	16.8	1x
9	No binding	(GMRES, GMRES, CG)	(HYPRE, HYPRE, Jacobi)	9.53	1.76 x
1	Bind by L2 Cache	(GMRES, GMRES, CG)	(HYPRE, HYPRE, Jacobi)	1.45	11.58 x

Number of Threads	Process Binding	Solver for Eq. (1, 2, 3) Precond. for Eq. (1, 2, 3)		Time per Iteration (s)	Speedup
1	Bind by L2 Cache	(GMRES, GMRES, CG)	(None, None, HYPRE)	8.74	1.92 x
1	Bind by L2 Cache	(GMRES, GMRES, GMRES)	(Jacobi, None, Jacobi)	4	4.2 x
1	Bind by L2 Cache	(GMRES, CG, CG)	(Jacobi, Jacobi, Jacobi)	0.910	18.46 x











# 7-Panel Case Study

- 8 m/s constant wind speed
- 7 m spacing between rows
  - n rows

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• Tracking angle is *prescribed*  $\theta(t) = -30^{\circ} + 15^{\circ} \sin(2\pi f t)$ 



Comparison to previous FSI study: 95K vs 22M fluid cells (230x larger problem)





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### 7-Panel Case Study

Pressure profiles and inertial load time series can be used as inputs into mechanical module models to study cracking of cells, weathering of cracked cells, and glass breakage









### 7-Panel Case Study

Pressure profiles and inertial load time series can be used as inputs into mechanical module models to study cracking of cells, weathering of cracked cells, and glass breakage











## Future Work

- Public release of PVade
- Add solution of **structural problem**
- Couple fluid and structural solver at panel interface
- Add effects of complex terrain and enable optimization problem definitions
- Validation campaign















#### Contributing Researchers

- Walid Arsalane
- Xin He
- Scott Dana
- Chris Ivanov
- Ryan King
- Mike Deceglie
- Tim Silverman
- David Corbus

# Thank You

Questions? ethan.young@nrel.gov

#### www.duramat.org

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