Neural Network Enhanced RKPM for Electrochemical-Mechanical Coupled Damage Modeling of Energy Storage Materials

Kristen Susuki^{1,2}, Jeffery Allen², J.S. Chen¹

¹ University of California San Diego, Department of Structural Engineering ² National Renewable Energy Laboratory, Computational Science Center







Li-ion Battery Electrode Microstructures and Chemo-Mechanical Cracking

Electrode Microstructure and Chemo-mechanical Cracking

Cathode Composition:

- Randomly-oriented grains
- Anisotropic grain material properties



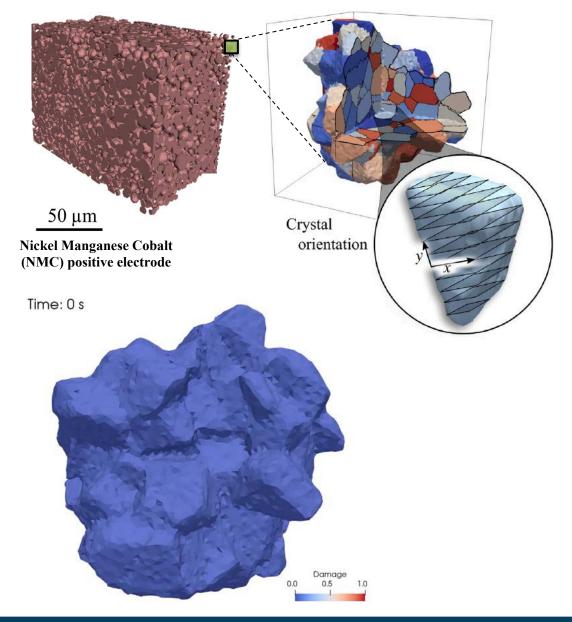
Charge Cycling:

• Li movement between electrodes causes nonuniform grain expansion and contraction



Chemo-mechanical cracking:

- Inhibited Li flow via tortuous diffusion path
- Reduced battery life





1. NREL. "Battery Microstructures Library." https://www.nrel.gov/transportation/microstructure.html.

2. Allen, J., P. Weddle, A. Verma, et al. 2021. "Quantifying the influence of charge rate and cathode-particle architectures on degradation of Li-ion cells through 3D continuum-level damage models." *J. Power Sources*. doi.org/10.1016/j.jpowsour.2021.230415.

Coupled Electrochemical-Mechanical Formulation



Governing Equations

Electrochemistry Model

[Li]

Lithium transport \rightarrow lithium concentration [Li]

 $[\dot{L}i] + J_{j,j} = 0$ in Ω (Similar to a transient heat equation) Fickian diffusion: $J_j = -D_{jk}[Li]_{,k}$

 Φ_{NMC}

• Solid-phase electrostatic potential $\Rightarrow \Phi_{NMC}$

$$\left(\kappa\Phi_{NMC_{,j}}\right)_{,j}=0$$
 in Ω (Poisson equation)

Mechanics Model

 \boldsymbol{u}

Mechanics $\rightarrow u$

$$\sigma_{ij,j} = 0$$
 in Ω (Balance of linear momentum)
$$\text{Stress: } \sigma_{ij} = C_{ijkl} \epsilon_{kl}^e$$

$$\epsilon_{kl}^e = \epsilon_{kl} - \epsilon_{kl}^{[Li]}$$

Electrochemistry Boundary Condition (BC): Butler-Volmer Relation

• Lithium transport \rightarrow intercalated lithium concentration [Li]

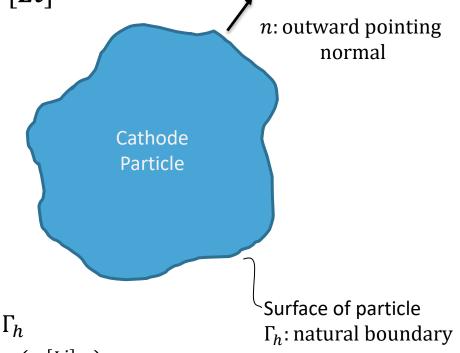
$$\frac{i}{F} = J_k n_k \qquad on \ \Gamma_h$$

• Solid-phase electrostatic potential $\rightarrow \Phi_{NMC}$

$$i = -\kappa \frac{\partial \Phi_{NMC}}{\partial x_k} n_k$$
 on Γ_h

Butler-Volmer coupling

BC:
$$i = i_0 \left[\exp\left(\frac{\alpha_a \eta F}{RT}\right) - \exp\left(-\frac{\alpha_c \eta F}{RT}\right) \right] \quad on \ \Gamma_h$$
$$\eta([Li], \Phi_{NMC}) = \Phi_{NMC} - \Phi_{el} - E^{eq}\left(\frac{[Li]}{[Li]_{max}}\right)$$

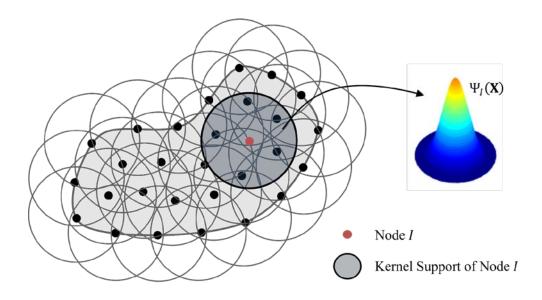


Reproducing Kernel Particle Method (RKPM)

Reproducing Kernel (RK) Approximation

RK Approximation:

$$u(\mathbf{x}) \approx u^h(\mathbf{x}) = \sum_{I=1}^{NP} \Psi_I(\mathbf{x}) d_I$$



Shape Function Construction: $\Psi_I(x)$

Strategic Correction of Kernel Functions, ϕ_a :

$$\Psi_I(x) = C(x; x - x_I)\phi_a(x - x_I) = \left(\sum_{|\alpha| \le n} (x - x_I)^{\alpha} b_{\alpha}(x)\right)\phi_a(x - x_I)$$

$$\Psi_I(\mathbf{x}) \equiv \mathbf{H}^T(\mathbf{x} - \mathbf{x}_I)\mathbf{b}(\mathbf{x})\phi_a(\mathbf{x} - \mathbf{x}_I)$$

$$\mathbf{H}^{T}(\mathbf{x}-\mathbf{x}_{I}) = [1, (x_{1}-x_{1I}), (x_{2}-x_{2I}), (x_{3}-x_{3I}), ..., (x_{3}-x_{3I})^{n}]$$

Reproducing Conditions:

$$\sum_{I=1}^{NP} \Psi_I(x) x_I^{\alpha} = x^{\alpha}, \qquad |\alpha| \le n \quad OR \quad \sum_{I=1}^{NP} \Psi_I(x) (x - x_I)^{\alpha} = \delta_{0\alpha}, |\alpha| \le n$$

$$b(x) = M^{-1}(x)H(0)$$
, where $M(x) = \sum_{l=1}^{NP} H(x - x_l)H^{T}(x - x_l)\phi_a(x - x_l)$

$$\Psi_I(\mathbf{x}) = \mathbf{H}^T(\mathbf{0})\mathbf{M}^{-1}(\mathbf{x})\mathbf{H}(\mathbf{x} - \mathbf{x}_I)\phi_a(\mathbf{x} - \mathbf{x}_I)$$

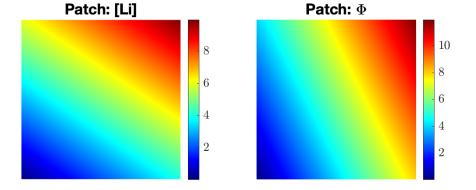
Linear Patch Test for Coupled Problem

Formulating Linear Patch Test for Coupled Problem

- Considerations:
 - Assume arbitrary linear fields:

•
$$[Li]^p = a_0 + a_1 x_1 + a_2 x_2$$

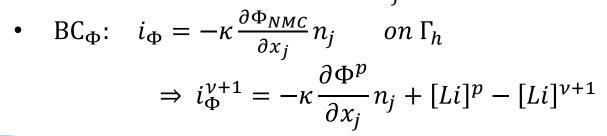
- $\Phi^p = a_4 + a_5 x_1 + a_6 x_2$
- Must design coupled BCs that satisfy governing equations.



Designing Mixed BCs (applied as Natural BCs)

• BC_[Li]:
$$i_{[Li]} = -D_{kj} \frac{\partial [Li]}{\partial x_j} n_k$$
 on Γ_h

$$\Rightarrow i_{[Li]}^{\nu+1} = -D_{kj} \frac{\partial [Li]^p}{\partial x_j} n_k + \Phi^p - \Phi^{\nu+1}$$

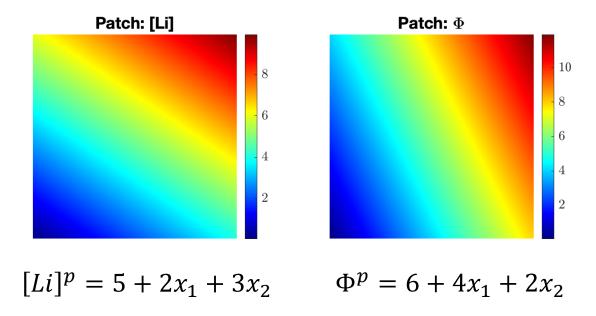


Note: We recover the original governing equations once convergence is reached (i.e. $\Phi^{(\nu+1)} = \Phi^p$, [Li] $^{(\nu+1)} = [Li]$).

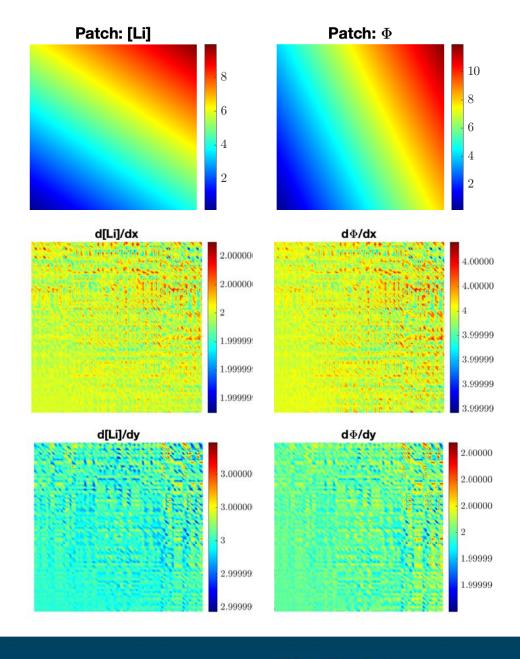
Note: A **mixed type boundary condition** is used (i.e. if solving for [Li], then $\nabla [Li]^p$ and Φ^p are used in the traction BC).

Implementing Linear Patch Test for Coupled Problem

Analytical Linear Fields:

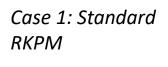


Formulation passes coupled linear patch test.



Introducing Weak and Strong Discontinuities to the **RK Approximation Space**

Kernel Function Modifications for Grain Boundaries: max[tanh(dist), 0]



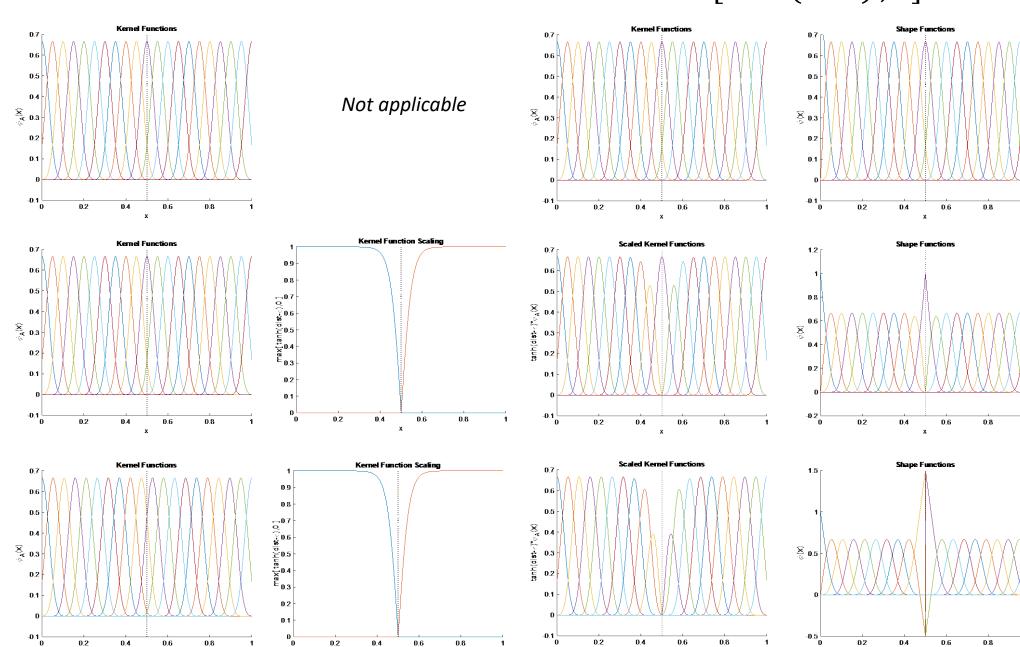
 $\begin{array}{l} \text{Smooth } \Psi \\ \text{everywhere} \end{array}$

Case 2: Scaling with node on boundary

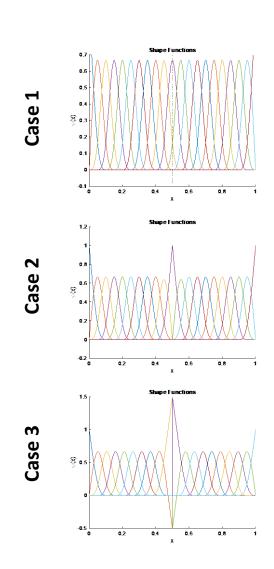
Weak discontinuity introduced only for $\Psi_{Boundary}$

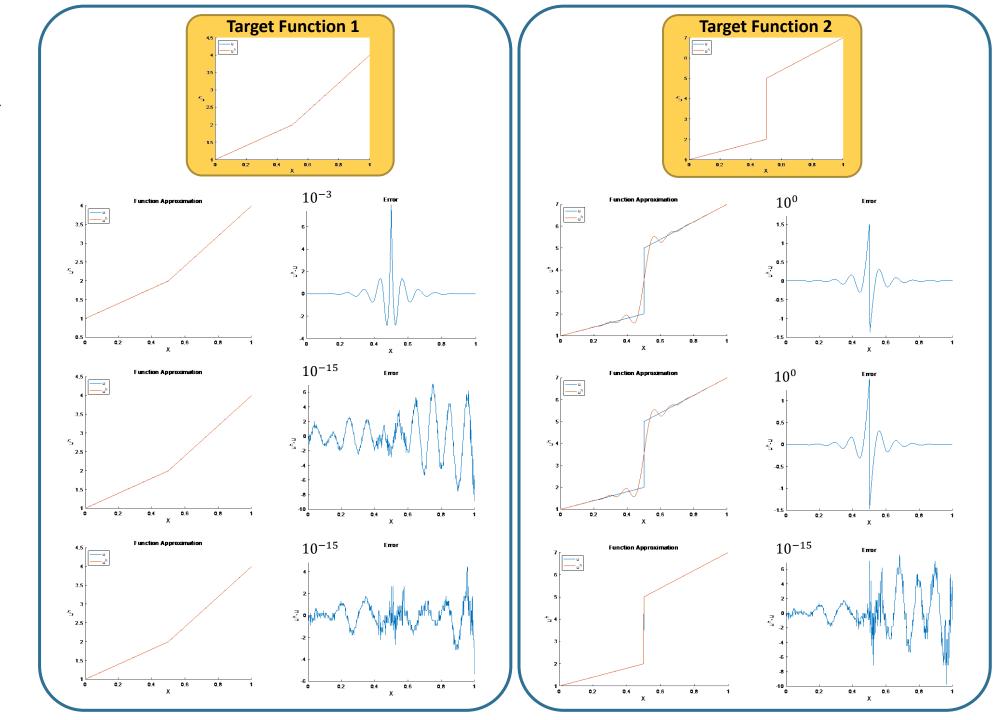
Case 3: Scaling with no node on boundary

Strong discontinuity introduced only for $\Psi_{Boundary}$



Function Approximation, u^h





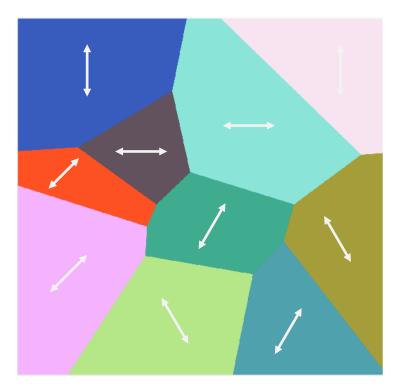
Multiple Grain Demonstration Problem

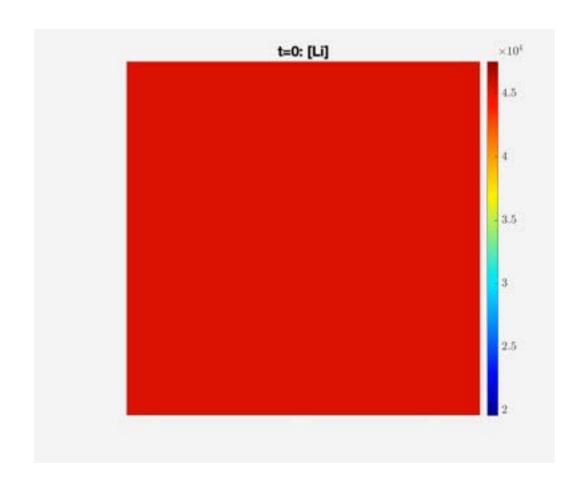




10 Voronoi Grains with Anisotropic Diffusion

Grain Orientations:





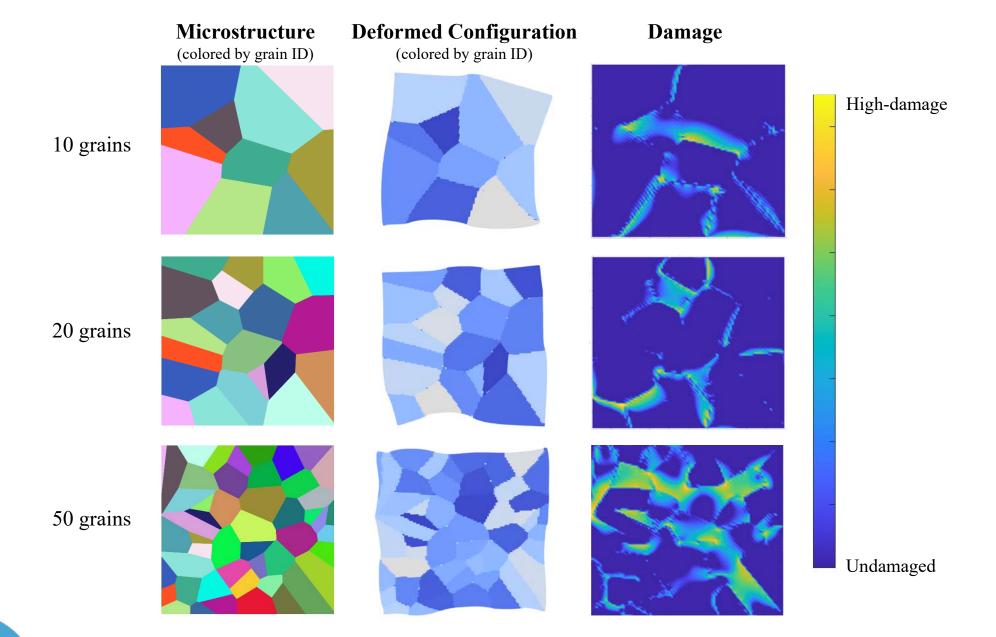
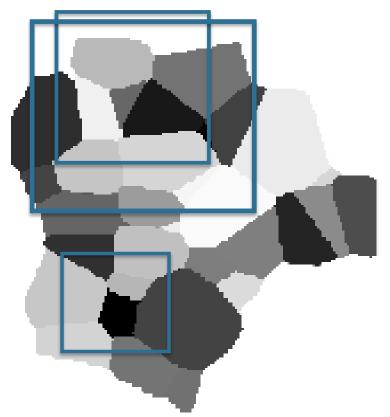
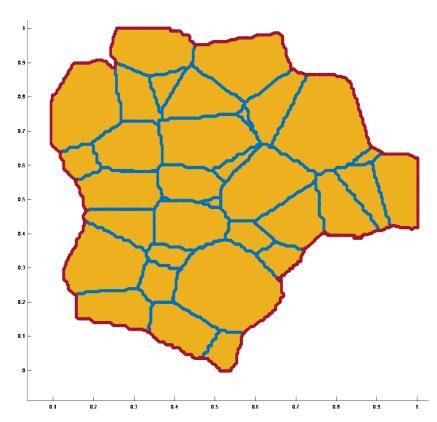
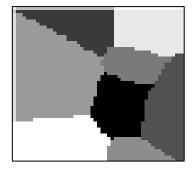


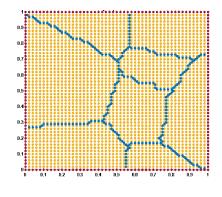
Image-based Modeling

From Pixels to Nodes

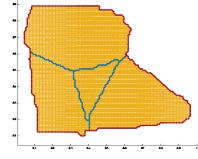


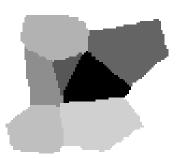


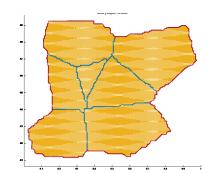


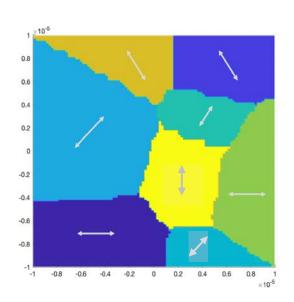






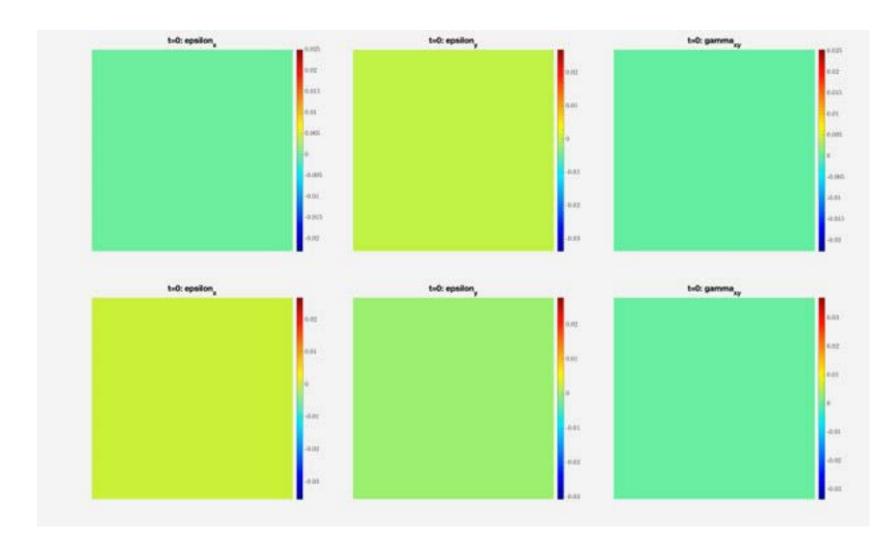






RKPM with Kernel Scaling on Grain Boundaries

Standard RKPM

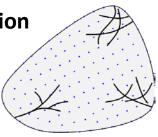


Neural Network Enhanced Reproducing Kernel Approximation

Neural Network Enhanced Reproducing Kernel (NN-RK) Approximation

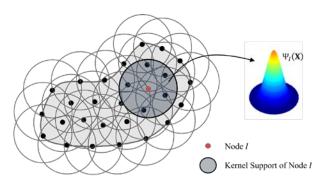
Solution decomposition

$$\mathbf{u}^h = \widetilde{\mathbf{u}}^h + \widehat{\mathbf{u}}^h$$



Smooth solution approximation

$$\widetilde{\mathbf{u}}^h(\mathbf{X}) \approx \mathbf{u}^{RK}(\mathbf{X}) = \sum_{I=1}^{NP} \Psi_I(\mathbf{X}) \mathbf{d}_I$$

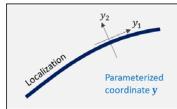


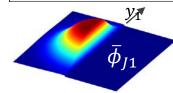
Neural Network (NN) Enrichment

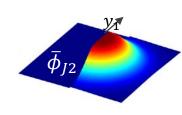
$$\widehat{\mathbf{u}}^h(\mathbf{x}) \approx \mathbf{u}^{NN}(\mathbf{X}) = \sum_{I=1}^{NB} b_I(\mathbf{X}; \mathbf{W})$$

Neural network (NN) approximation

Block-level NN approximation







$$u^{NN}(\mathbf{x}) = \sum_{B=1}^{N_B} b_B^{NN}(\mathbf{x}; \mathbf{W}_B) \quad \bullet \quad b_B^{NN}: \text{ block-level NN approximation}$$

$$b_B^{NN}(\mathbf{x}; \mathbf{W}) = \sum_{K=1}^{N_E} \hat{\phi}_{KB}(\mathbf{y}(\mathbf{x}; \mathbf{W}_B^L), \mathbf{W}_{KB}^S) p(\mathbf{x}; \mathbf{W}_{KB}^P) \quad \bullet \quad NK: \text{ the number of NN kernels per block}$$

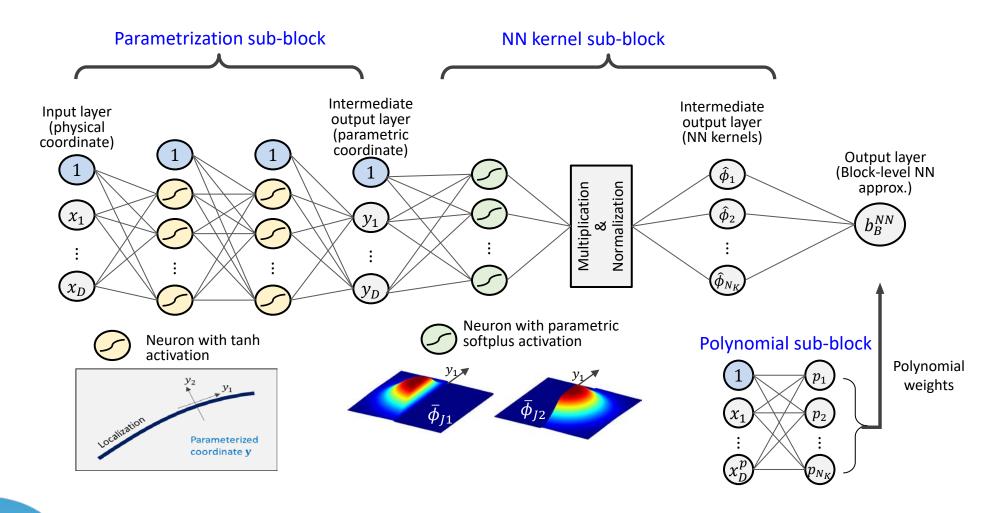
NN Kernel function captures

- Location and orientation of localization
- Shape of solution transition
- W^L: NN weight set controlling the location and orientation of the kernel.
- **W**^S: NN weight set controlling the shape of transition.

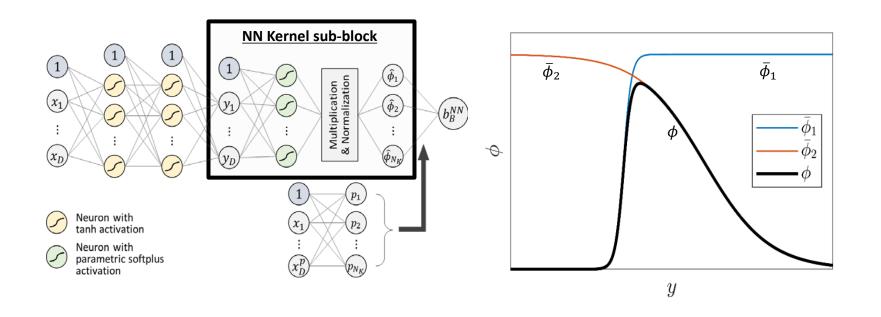
- **NN Polynomial** introduces
- Monomial completeness for further accuracy
- **W**^P: NN monomial coefficient set
- * The NN control parameters \mathbf{W}^L , \mathbf{W}^S , and \mathbf{W}^P are **automatically** determined via loss function minimization.

Block-Level Neural Network Architecture

A block-level neural network is a <u>modified deep neural network</u> with *increased interpretability*.



NN Kernel Function Controlled by \mathbf{W}^{S}



NN Kernel Function

$$\phi(y; \mathbf{W}_{KB}^{S}) = \prod_{i=1}^{2} \bar{\phi}(z_{i}(y, \bar{\mathbf{y}}_{i}^{KB}, c_{i}^{KB}); \beta_{i}^{KB})$$

Regularized step functions

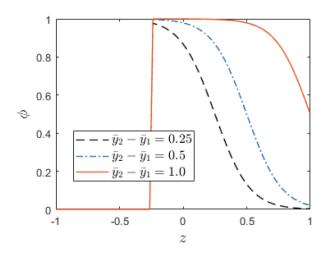
Regularized Step

Functions
$$\bar{\phi}(z_i; \beta_i) \equiv S\left(z_i + \frac{1}{2}; \beta_i\right) - S\left(z_i - \frac{1}{2}; \beta_i\right)$$

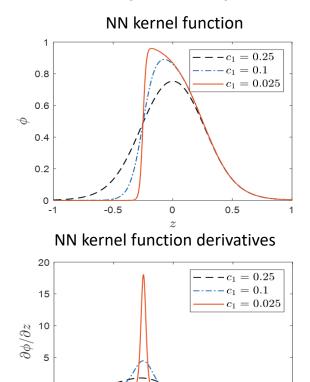
Where
$$z_i = (-1)^i (y - \overline{y}_i)/c_i$$
, $i = 1, 2$
$$S(z; \beta) = \frac{1}{\beta} \log(1 + e^{\beta z})$$
 (parametric softplus function)

Neural Network Kernel Function Controlled by $\mathbf{W}^{\mathcal{S}}$

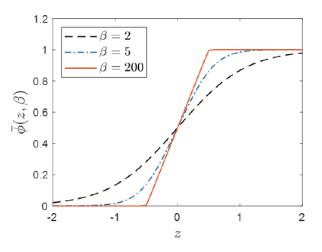
NN Control Parameter \bar{y} Domain of influence



NN Control Parameter *c*Transition of NN kernel function



NN Control Parameter β Transition of NN kernel function derivative

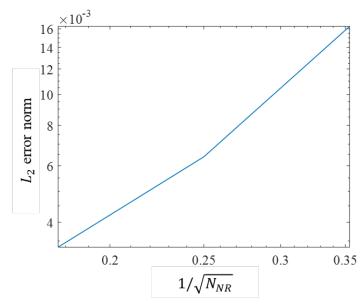


-0.5

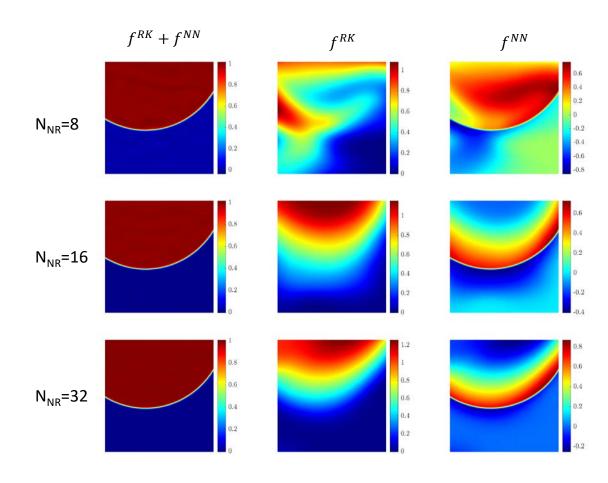
0.5

Convergence Performance for Function Evaluation: (1) Influence of the Number of Neurons (N_{NR})

Average rate of convergence: 2.282

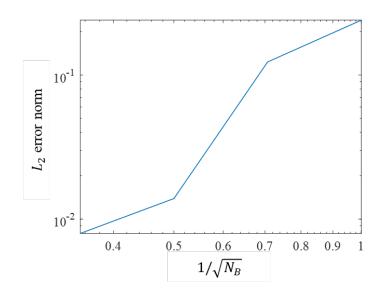


Number of block $N_B=1$ Number of NN kernel per block $N_K=4$

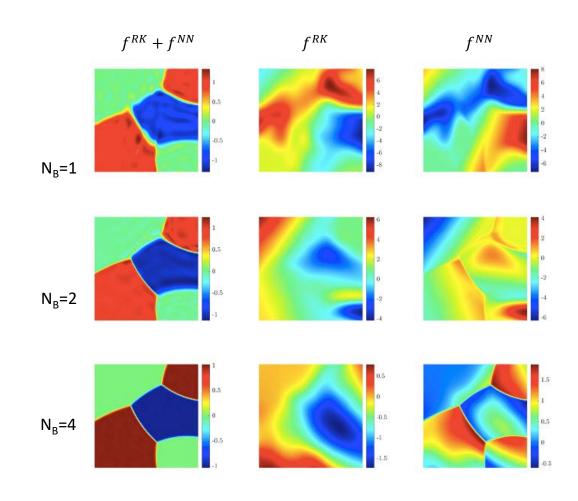


Convergence Performance for Function Evaluation: (2) Influence of the number of NN Blocks (N_B)

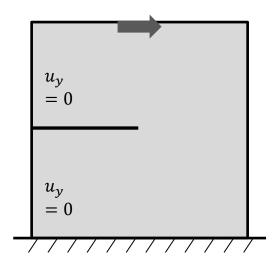
Average rate of convergence: 3.578



Number of neurons $N_{NR} = 32$ Number of NN kernel per block $N_K = 4$



Damage Evolution



$$\min \Pi = \frac{1}{2} \int_{\Omega} g(\eta) \psi^{+} + \psi^{-} d\Omega + \frac{p}{2} \int_{\Omega} \eta^{2} d\Omega + \Pi^{ebc}$$

<u>Damage</u>

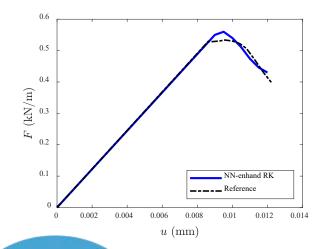
$$\eta = \frac{\kappa}{\kappa + p} \qquad \kappa = \psi^+ - \psi^c$$

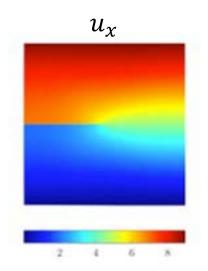
$$\psi^{+} = \frac{1}{2}\lambda \langle tr\varepsilon_{i}\rangle^{2} + \mu\varepsilon_{i}^{+}\varepsilon_{i}^{+}$$

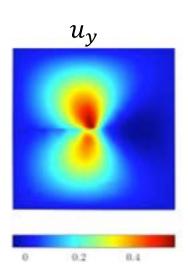
$$\psi^{-} = \frac{1}{2}\lambda ((tr\varepsilon_{i})^{2} - \langle tr\varepsilon_{i}\rangle^{2}) + \mu\varepsilon_{i}^{-}\varepsilon_{i}^{-}$$

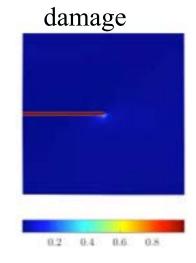
$$\langle \cdot \rangle = \max(0, \cdot)$$

- 256 RK particles (16X16) are used with 512 RK coefficients.
- 3 NN blocks are used with 540 total unknown weights and biases.
- Visibility criteria with diffraction is applied to the RK shape functions around the area of pre-existing crack.

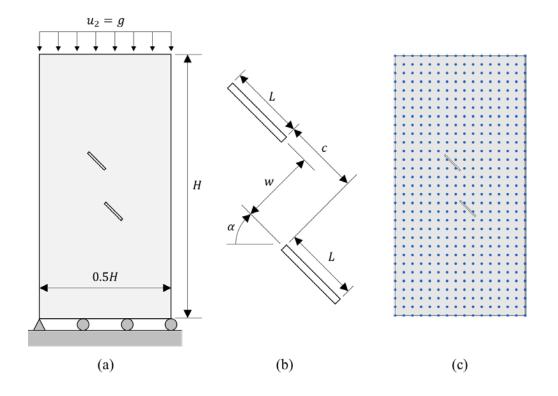


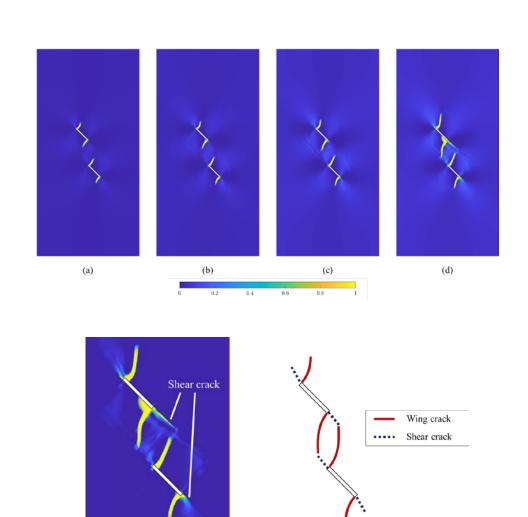






Mixed-mode Fracture of a Doubly Notched Crack Branching





NN-RKPM

(a)

Experiment (reference)

(b)

Conclusions and Future Work

Conclusions:

- A coupled linear patch test was designed and passed for the electrochemical model.
- Through kernel function scaling and strategic RK node placement, weak and strong discontinuities along grain boundaries were introduced in a flexible manner.
- Image-based modeling techniques were leveraged for realistic model construction.
- NN enhancement increased localization accuracy in homogeneous materials without extensive model refinement.

Future Work:

- Input non-rectangular exterior geometries to fully-coupled simulation.
- Extend NN-RK damage capture to heterogeneous electrode materials.

Thank you

Kristen Susuki – ksusuki@ucsd.edu

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