

Operating Conditions of a Main Bearing Contact in a Commercial Wind Turbine

Yi Guo, *Technical University of Denmark*

Allan Thomson, Olle Bankestrom, Joe Erskine, *SKF*

Jonathan Keller, Roger Bergua, *National Renewable Energy Laboratory, U.S.A.*

Outline

Motivation and Background

Instrumentations

Testing Turbine

Modelling Tools

Results: Loads, Motions, and Metal-Metal Contact

Conclusions

Motivations and Background

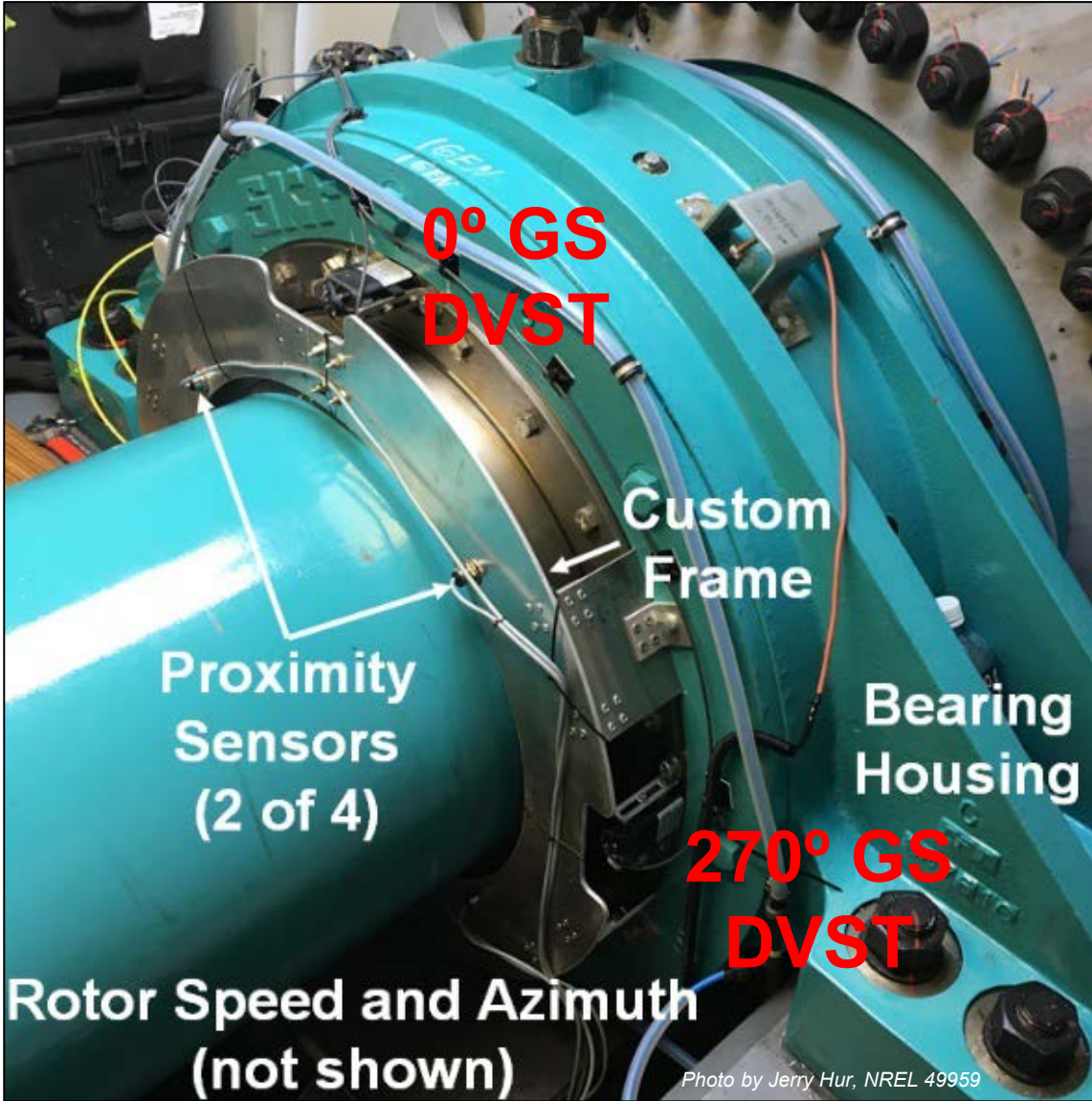
- Premature failures of main bearings observed in some populations with failure rates up to 20%–30% in 6–10 years.
- Removal and replacement of a main bearing typically requires appreciable maintenance costs and downtime.
- Key question – **Why do some main bearings fail prematurely?**
 1. *Does relative axial motion between bearing rings damage the main bearing?*
 2. *Does the bearing cage slip during operation?*
 3. *Is there metal-to-metal contact between rollers and raceways?*
- SKF provided design verification support tool (DVST) sensors, which were installed in a GE 1.5-megawatt SLE turbine at NREL.
- We examine the axial and sliding motion, loads, and lubrication of the main bearing, as correlated to turbine operating conditions.



Photo by Dennis Schroeder, NREL 21864



DVST measurements:
outer ring temperature,
axial acceleration,
tangential strain, and
acoustic emission

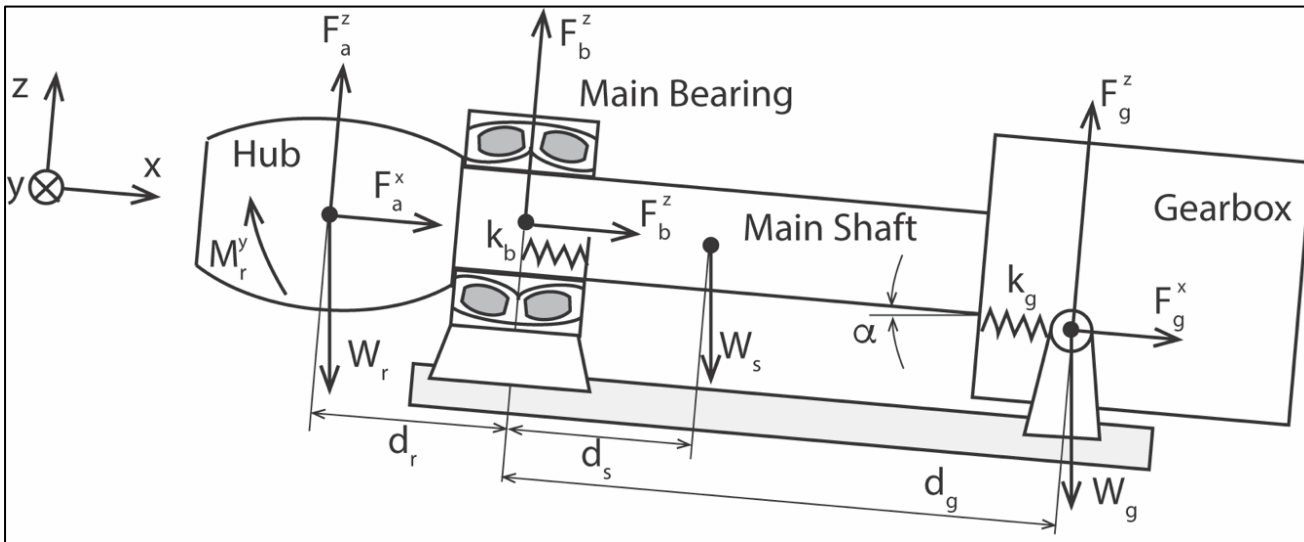


Generator-side (GS)

Rotor-side (RS)

Analytic Model for Global Loads and Motions

- Aerodynamic forces and moments as the input
- Linear estimations for component stiffnesses
- Bearing stiffness properties needed for motion estimations



Gearbox coupling force, vertical

$$F_g^z = \frac{M_r^y(t) + F_a^z(t)d_r - (W_r d_r - W_s d_s - W_g d_g) \cos \alpha}{d_g}$$

Main bearing force, vertical

$$F_b^z(t) = -F_a^z(t) - F_g^z(t) + (W_r + W_s + W_g) \cos \alpha$$

Axial roller/raceway motion

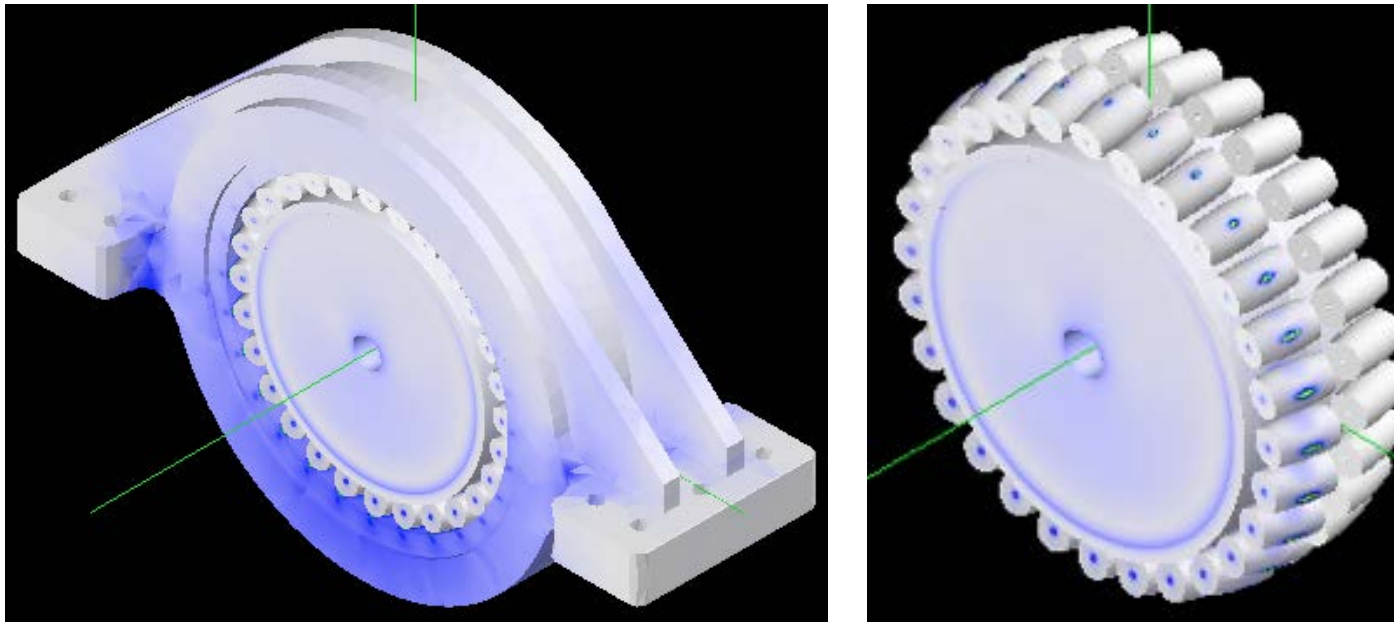
$$x(t) + x_r = \frac{F_a^x(t) + (W_r + W_s + W_g) \sin \alpha}{k_b^x + 2k_g^x}$$

x_r – resting position under gravity

Source: Bergua Archeli, R. et al. 2021. Up-Tower Investigation of Main Bearing Cage Slip and Loads. NREL/TP-5000-81240. <https://www.nrel.gov/docs/fy22osti/81240.pdf>.

Computational Model for Internal Loads and Stresses

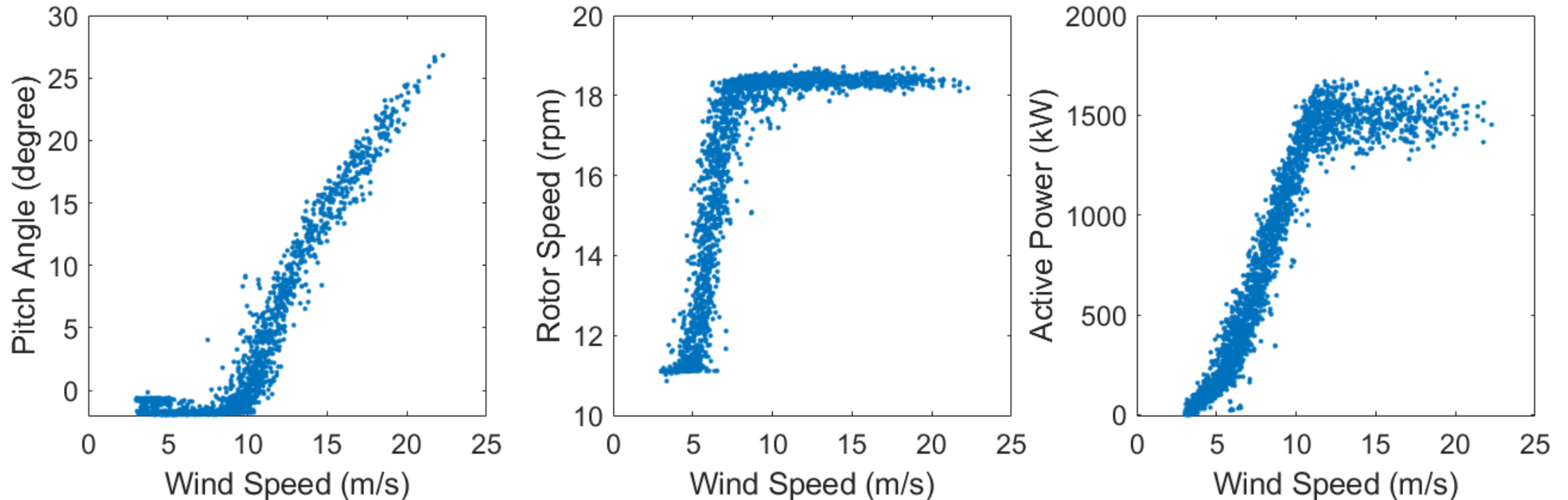
- Finite element/contact mechanics model computes load distribution, stresses, and strain
- Bearing clearances, roller, and raceway geometries included
- Bearing housing modelled as a flexible part



Source: Bergua Archeli, R. et al. 2021. Up-Tower Investigation of Main Bearing Cage Slip and Loads. NREL/TP-5000-81240. <https://www.nrel.gov/docs/fy22osti/81240.pdf>.

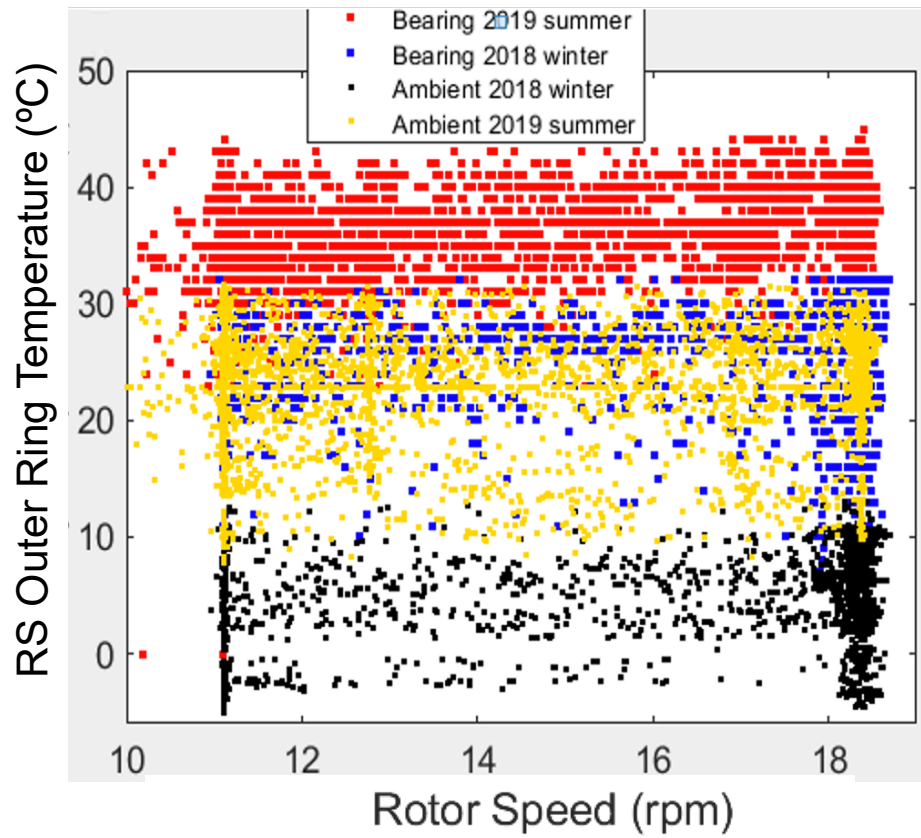
Turbine Operational Parameters

- Full operating envelope from the cut-in (3 meters per second (m/s)) to cut-out (25 m/s) wind speed
- Pitch angle remains near zero below 11 m/s and increases to 27° at the highest wind speeds
- Rotor speed rises from 11 revolutions per minute (rpm) at cut-in and reaches 18.4 rpm near 7 m/s wind
- Active power varies $\pm 20\%$ above rated wind speed.



Source: Guo, Y. et al. 2022. Acoustic Emission Measurement of a Wind Turbine Main Bearing. NREL/TP-5000-83370. <https://www.nrel.gov/docs/fy23osti/83370.pdf>.

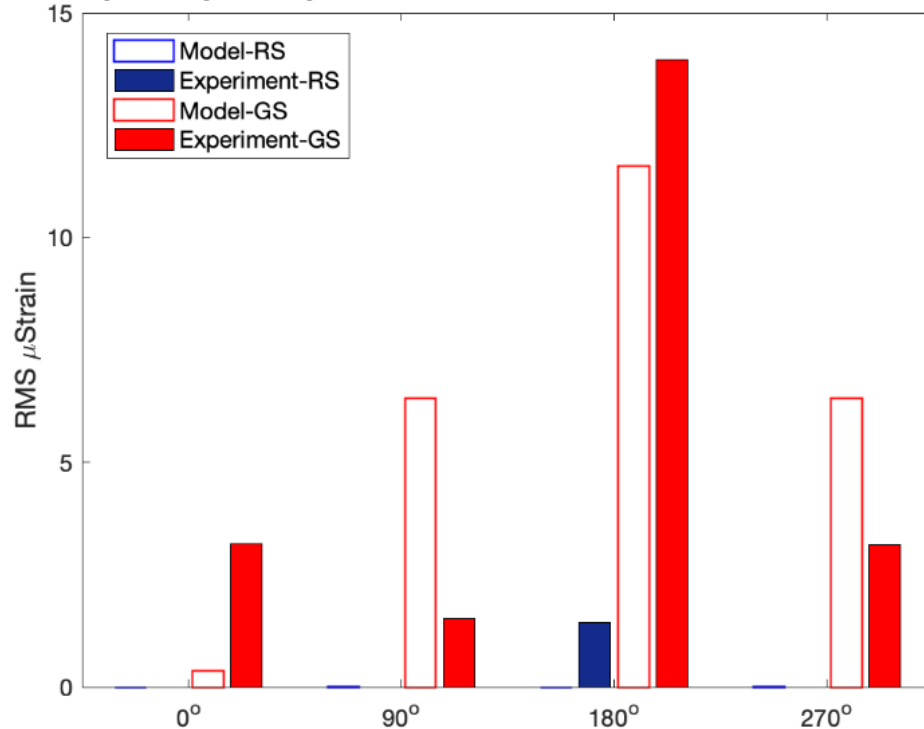
Operating Temperature of Main Bearing Outer Ring



- Operational temperatures of healthy main bearings are typically between 5°C and 47°C
- Bearing temperature approximately 20°C to 25°C higher than ambient
- In summer, bearing temperature roughly 15°C higher than winter
- Bearing temperature does not increase meaningfully with rotational speed

Result Correlation: Model and Experiments

Bearing Ring Tangential Strain at Rated Wind Speed



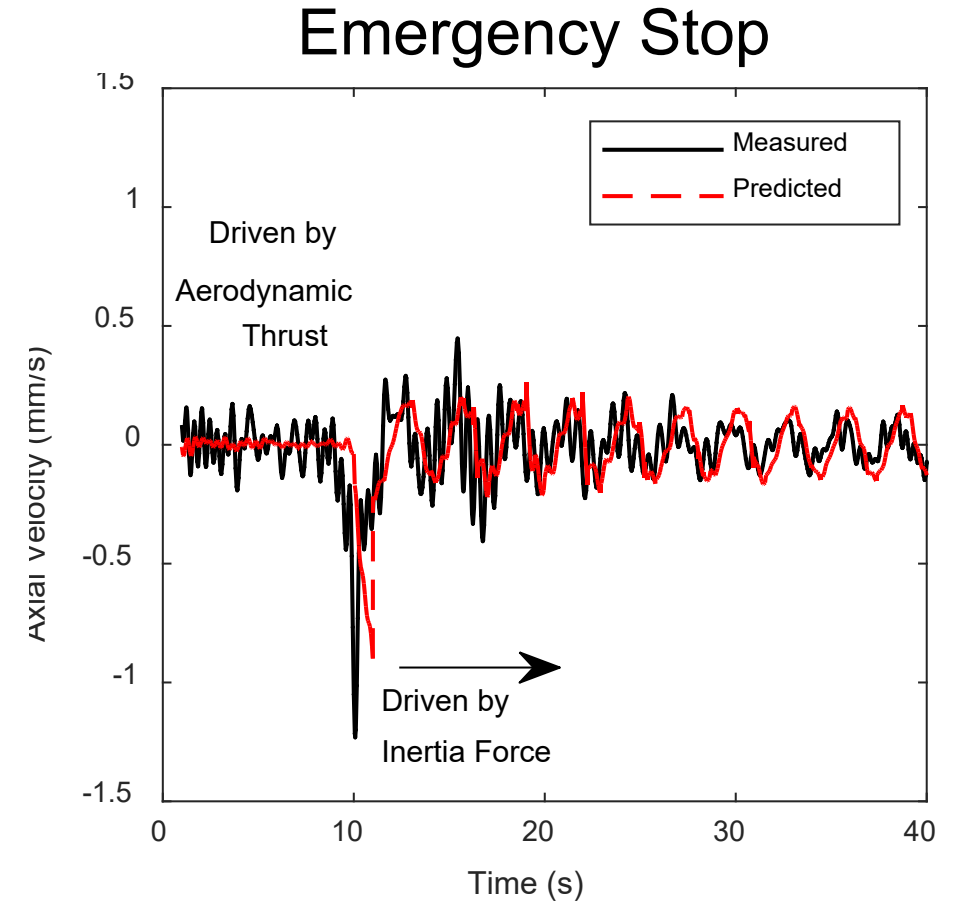
- Agreement between experimental and modeling results reasonably good
 - Nature of the contact (rather than bonded) strain gauge – data drifting might occur
 - Lack of bedplate and other model details
- Highest strain occurs at 180° when load highest
- Rotor-side bearing row almost unloaded

Source: Bergua Archeli, R. et al. 2021. Up-Tower Investigation of Main Bearing Cage Slip and Loads. NREL/TP-5000-81240. <https://www.nrel.gov/docs/fy22osti/81240.pdf>.

Does relative axial motion damage main bearing?

Relative Axial Velocity Between Bearing Rings

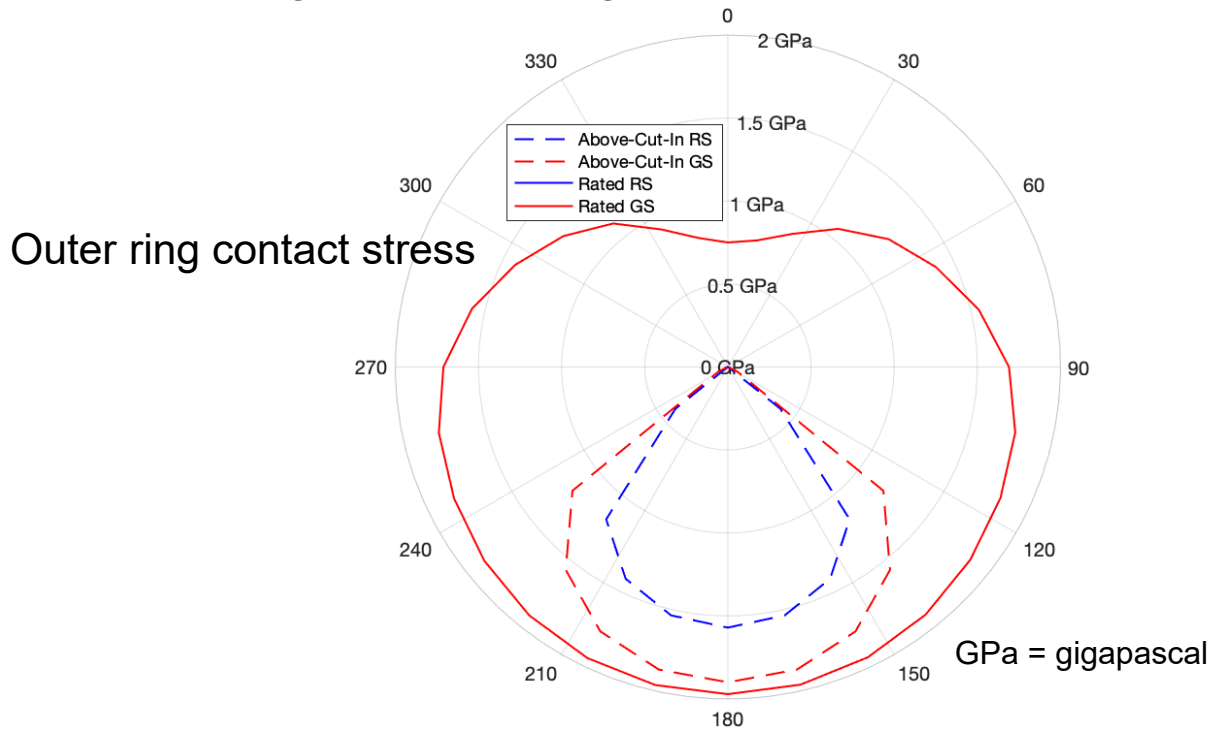
- Axial motion within axial clearance in spherical roller bearings – up to several millimeters
- When axial velocity < 10% of speed of rolling (352 mm/s), no appreciable effects on lubrication film (threshold based on SKF experiments)
- Measured maximum axial velocity < 1.5 mm/s during emergency stop – lubrication film deterioration not anticipated
- Generally good agreement between model and experimental results



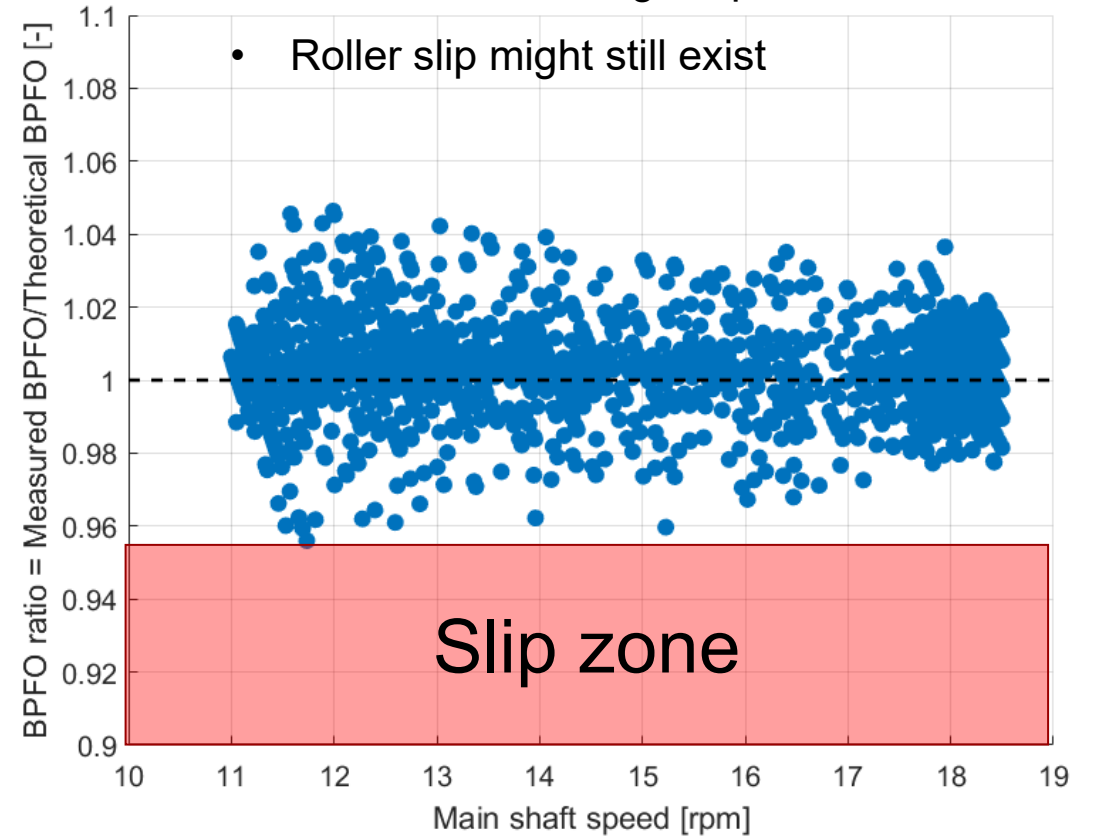
Does bearing cage slip during operation?

Measurement Results – Tangential Strain

- Tangential strain measurement used to examine cage slip
- Measured vibration signature at roller pass frequency compared against theoretical value under pure rolling: <0.95 might indicate cage slip



- No evidence of cage slip!
- Roller slip might still exist

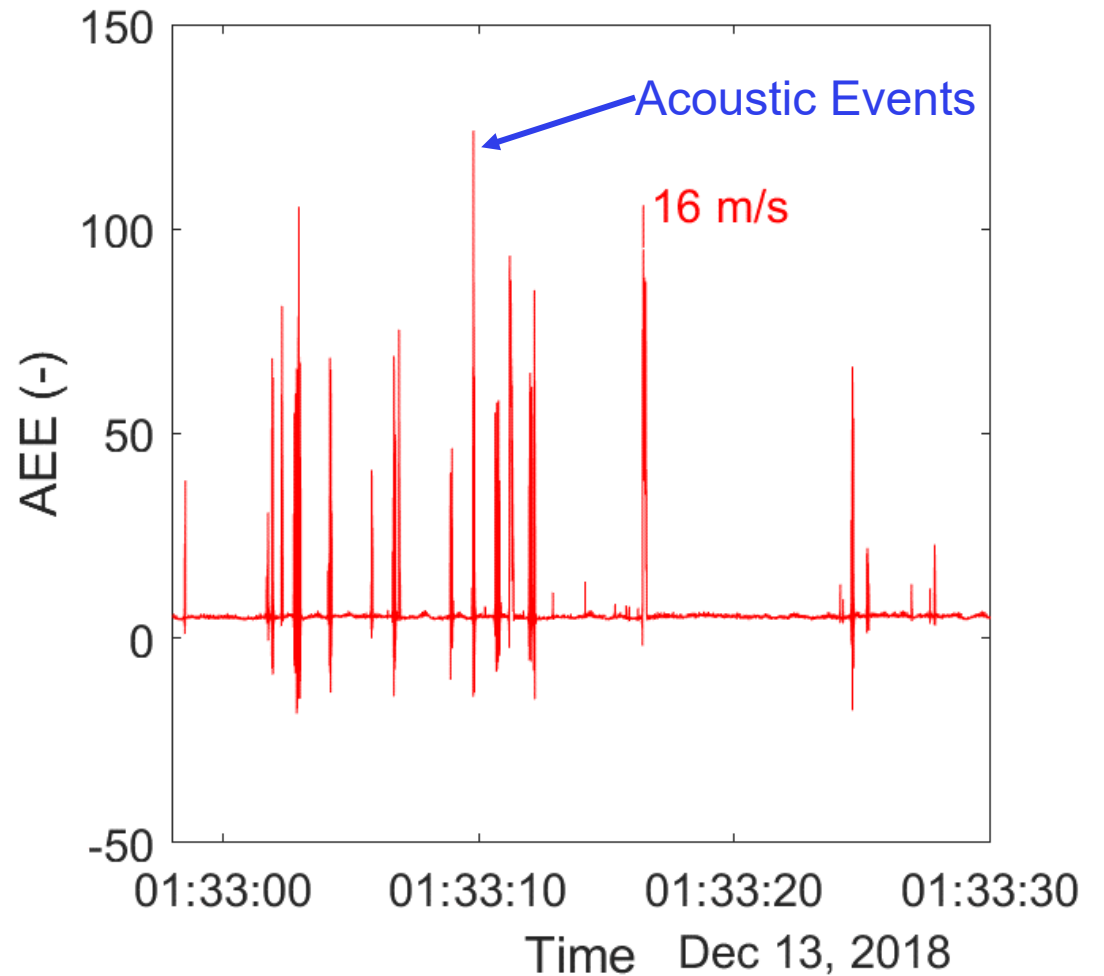
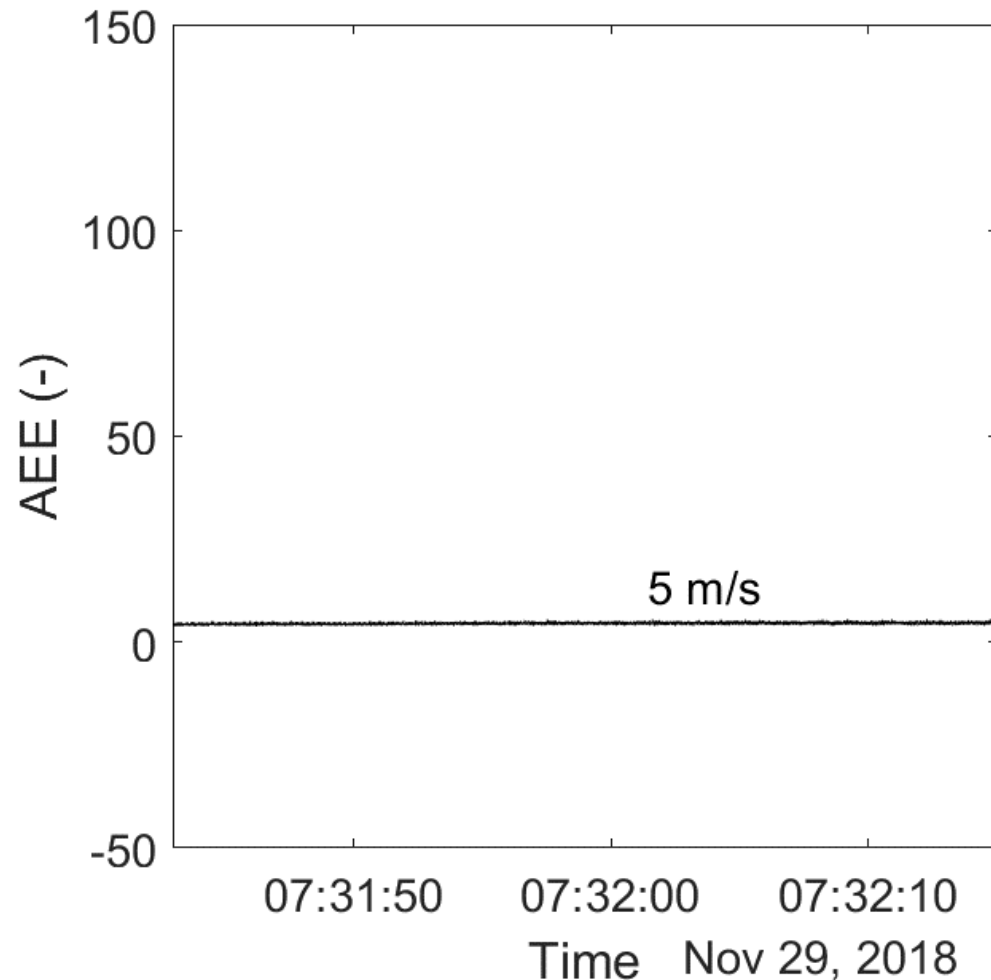


BPF0 = ball-pass frequency for the outer ring

Source: Bergua Archeli, R. et al. 2021. Up-Tower Investigation of Main Bearing Cage Slip and Loads. NREL/TP-5000-81240. <https://www.nrel.gov/docs/fy22osti/81240.pdf>.

**Is there metal-to-metal contact
between bearing surfaces?**

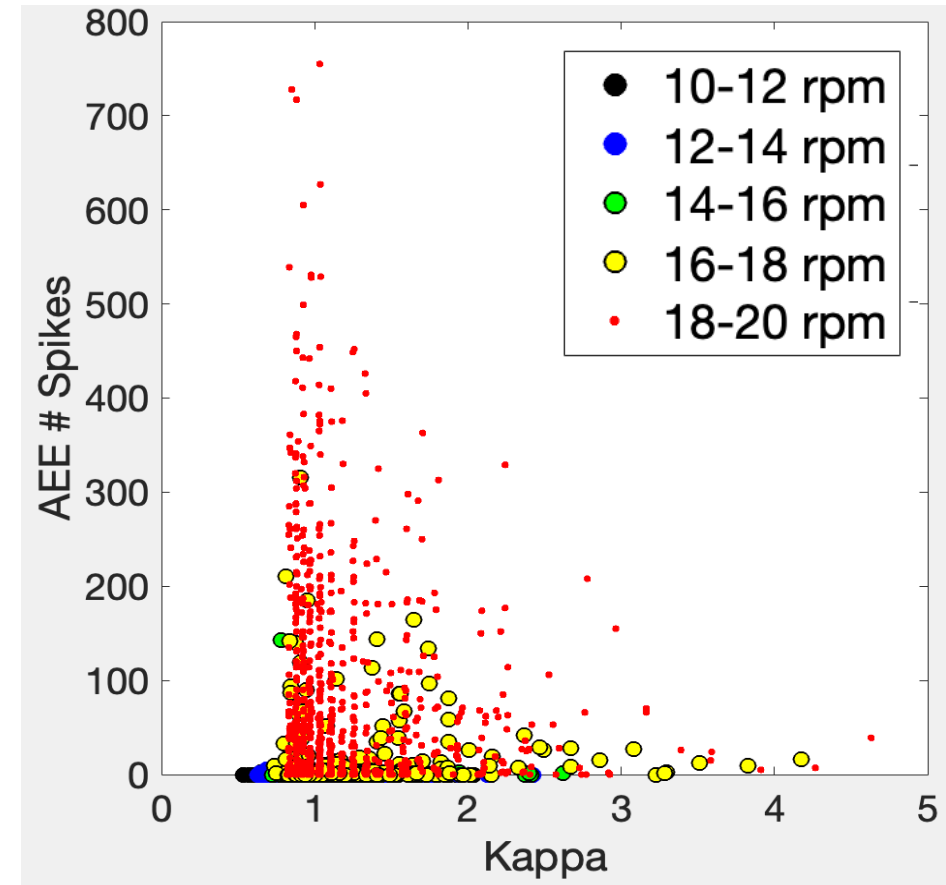
Measurement Results – AEE Wave Forms (Rectified and Enveloped)



Source: Guo, Y. et al. 2022. Acoustic Emission Measurement of a Wind Turbine Main Bearing. NREL/TP-5000-83370. <https://www.nrel.gov/docs/fy23osti/83370.pdf>.

Acoustic Emission vs. Kappa (Viscosity Ratio)

- Kappa can indicate lubricant conditions, with a typical desired range from 1 to 4
- When Kappa is less than 1, risk of roller/raceway asperity contact present
- Main bearing is often under mixed lubrication during normal operation
- Elevated AEE spikes combined with low Kappa may indicate roller/raceway asperity contact
 - Kappa ≈ 1 and main shaft speed ≥ 18 rpm



Conclusions

- Typical operational conditions of a spherical roller main bearing of a three-point-mount wind turbine drivetrain described
 - Strain gages used to examine load zone and cage slip
 - Relative axial velocity between bearing rings derived from proximity measurements
 - Acoustic emission monitors metal-to-metal contact
- Analytic and finite element/contact mechanics models established, and results match experimental data reasonably well
 - Analytic model estimates bearing loads, and relative axial motion and velocity
 - Finite element/contact mechanics model computes internal loads, stress, and strain

Conclusions

Key question – **Why do some main bearings fail prematurely?**

- *Does axial roller/raceway motion damage main bearing?*
 - *Relative axial velocity between bearing rings much lower than speed of rolling – lubrication film deterioration not anticipated*
- *Does the bearing cage slip during operation?*
 - *No appreciable cage slip discovered for the generator-side row*
 - *No cage slip anticipated for the rotor-side row because of shared cage*
 - *Roller slip might still exist*
- *Is there metal-to-metal contact between the rollers and raceways?*
 - *Spikes and elevated values of the acoustic emissions present during operations*
 - *Lubricant film might not be sufficient to prevent asperity contacts in some conditions*

Contact: yiguo@dtu.dk and jonathan.keller@nrel.gov



Acknowledgments

This work was authored in part by the National Renewable Energy Laboratory, operated by Alliance for Sustainable Energy, LLC, for the U.S. Department of Energy (DOE) under Contract No. DE-AC36-08GO28308. Funding provided by the U.S. Department of Energy Office of Energy Efficiency and Renewable Energy Wind Energy Technologies Office. The views expressed herein do not necessarily represent the views of the DOE or the U.S. Government.

NREL/PR-5000-86519