

Motivation

- High-voltage direct current (HVDC) systems within the AC grids will play a pivotal role.
- The voltage-source-converter (VSC) HVDC technology is self-commutated which allows for independent control of both active and reactive power.
- As the rapid growth of VSC-HVDC projects around the world, there is a need to capture the characteristics of VSC-HVDC damping control in the system planning stage.

Objective

- Model the VSC-HVDC damping control as equivalent transmission capability constraints (TCC) and incorporate in unit commitment (UC). Derive the constraint from the modified power system swing equation model.
- Develop three system damping control scenarios including moderate, fully, and poorly damped cases.
- Investigate this problem in Reliability Test System Grid Modernization Lab Consortium (RTS-GMLC) system and assess the impact of the constraints on inertia, power flow, and renewable curtailment.

System Swing Dynamics

Reduced system swing equation model is used to study the behavior of the inter-area oscillation,

$$\frac{M}{\omega_s} \cdot \frac{\partial^2 \delta_m}{\partial t^2} = P_m - P_e \quad [p. u.]$$

The approximated damping ratio for the equivalent machine is derived as,

$$\zeta = \frac{1}{2} D \sqrt{\frac{\omega_s}{2H \cdot P_{max} \cdot \cos \delta_0}}$$

The damping ratio $\zeta_{threshold}$ is set to ensure stability of the equivalent model,

$$\frac{1}{2} D \sqrt{\frac{\omega_s}{2H_{sys} \cdot P_{max} \cdot \cos \delta_0}} \geq \zeta_{threshold}$$

The maximal transmitted power constraints on parallel interregional AC transmission lines are then constrained as

$$P_{max} \leq \alpha, \quad \alpha = \frac{15K_d^2 \omega_s}{H_{sys} \cos \delta_0}$$

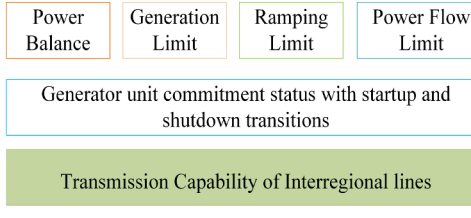
α is the VSC-HVDC damping control constraint limit, denoted as **VSC damping limit**.

VSC-HVDC Damping Control Constrained Unit Commitment

Final unit commitment (UC) formulation

Objective: minimize total generator startup and shutdown cost, fuel and -dual-fuel cost, and penalty of unserved energy

Subject to



Three scenarios with different damping control modes and VSC damping limits are simulated:

Scenario	POD Control	VSC Damping Limit α
Moderate Damped	FACTS and PSS	0.7
Fully Damped	Combination of VSC-HVDC, FACTS, and PSS	1
Poorly Damped	Malfunctions of VSC-HVDC, FACTS, and PSS	0.1

Numerical Results and Conclusion

Simulation parameters:

Simulation tool: PLEXOS 9.0

Test system: updated IEEE 73-bus with 3 regions, 95 AC lines, and 1 VSC line.

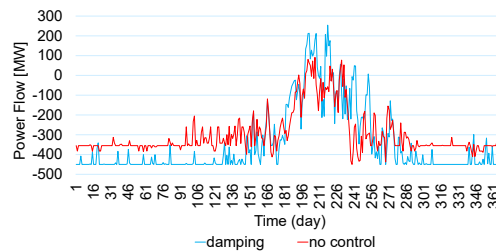


Figure 4. Power flows on line 325-121 of moderate and fully damped cases.

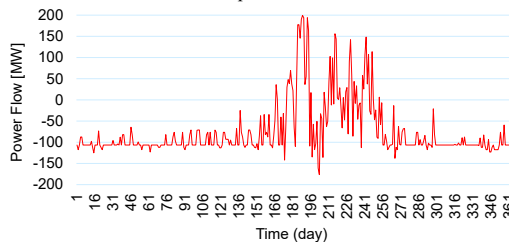


Figure 5. Power flow on AC transmission line 325-121 in poorly damped case.

- Implementation of HVDC POD increases the K_d of the system, and subsequently improves the transmission capability of interregional line.
- The transmission capability is significantly degraded due to oscillatory constraints with low damping coefficient setting

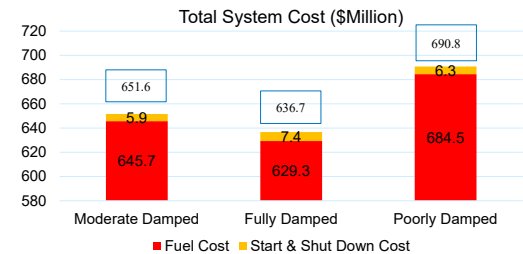


Figure 5. Comparison of annual system costs.

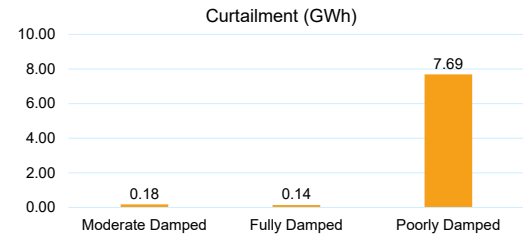


Figure 6. Comparison of annual wind and PV curtailment among scenarios.

- The fully damped case with proper VSC-HVDC power oscillation damping case control will lead to a more economic generator dispatch solution
- The annual system cost and curtailment of the fully damped case will decrease.
- The poorly damped case will dramatically increase the system cost and curtailment.