

Partnership Project

City and Borough of Sitka, Alaska - Modeling and Controls Assistance and Renewable Energy Resource Assessment

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□ Sizing of wind penetration in hydro-rich environment of Sitka

- Practical Sitka grid model for dynamic analysis
- Dynamic model of wind to assess the stability and control impacts
- Dynamic model of Blue Lake and Green Lake synchronous machines to assess the stability and control impacts
- □ Analysis of efficiency of load control
- Analyze stability and grid control impacts of wind capacity expansions and locations
- □ Analyze wind-hydro control coordination

Developed detailed dynamic Sitka OPAL-RT model to evaluate grid stability and control impacts

□ Developed real-time model – Unbalanced 738-bus electric grid at 120 V, 12.5 kV, 69 kV, etc.

□ Analyzed case with wind generation analysis at Beaver Lake Hump

□ Analyzed case with wind generation analysis at Lucky Chance Ridge

- □ Analyzed case with wind generation analysis at Starrigavan Ridge
- □ Considered wind generation 3 MW, 6 MW, 9 MW, 12 MW, 15 MW

Detailed time domain dynamic models of Blue Lake and Green Lake generators

□ Input data received in CSV format which was transformed to create OPAL-RT model

Wind Generation Locations (Near Roundabout and Blue Lake Station)



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Wind Generation Locations (Green Lake Station)



Sitka Grid Model Performance – Base Case Load Flow



Sitka nodes at various voltage levels

Sitka Utility Microgrid Analysis – OPAL-RT Multi-Rate Modeling for Grid Control Analysis



Sitka Utility Microgrid Performance Validation



Wind Generation Model



Wind Generator Model



Pitch Control: Wind turbine has a pitchable blade to regulate the aerodynamic power extracted from wind and is connected to the generator through a low-speed shaft, a high-speed shaft and a mechanical gear-box.



Equivalent Circuit in Synchronous Reference Frame for Controls Design

 $[P_g: power delivered to the grid from the generator, P_g^*: reference power, <math>\beta$: pitch angle, β_{cmd} : pitch angle command, V_s and V_r : stator and rotor voltage, respectively, R_s and L_{ls} : stator resistance and inductance, respectively, R_r and L_{lr} : rotor resistance and inductance, respectively, ω_s and ω_{rl} : synchronous speed and angular slip frequency, respectively, ω_r : rotor speed, λ_s and λ_r : stator and rotor flux linkage, respectively, L_m : mutual inductance]

Variable-Speed Doubly-Fed Induction Generator (DFIG) Wind Energy System



DFIG Wind Energy System with Turbine Controller, Rotor Side Converter (RSC), and Grid Side Converter (GSC) Controllers [1], [2]



Block Diagram of RSC Controller

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 $[Q_{a}:$ reactive power at the grid-side, Q_{a}^{*} : reference reactive power, $V_{dc}:$ dc-link voltage, $V_{dc}^{*}:$ reference dc-link voltage, V_{ad} and $V_{ad}:$ dq components of grid-side voltage, respectively, i_{gd} and i_{ad}: dq components of grid-side current, respectively, L_a: grid-side filter inductance, V_{rd} and V_{rd}: dq components of rotor-side voltage, respectively, Ird and ird: dq components of rotor-side current, respectively, o: inductance ratio]

Hydraulic-Turbine-Governor (HTG) Model for Synchronous Generator



Non-Linear Hydraulic Turbine + PID Governor Model + Servo-Motor



Second-Order Gate Model [3]

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Non-Linear Hydraulic Turbine Model

Synchronous Machine Model

Nominal Active Power: 7.8 MW Terminal Voltage Control: Field Excitation System Electrical Torque & Power Controls: HTG Model

 $[\omega_{ref}: reference speed (pu), P_{ref}: reference mechanical power (pu), \omega_e: actual speed (pu), d\omega: speed deviation (pu), P_e: actual electrical power (pu), P_m: mechanical power for the machine block (pu), K_a: servo-motor gain, t_a: time constant in s, t_w: water starting time, R_p: permanent droop gain, K_{beta}: speed deviation damping coefficient, K_{TG}: turbine governor gain]$

[1] J. Lee, E. Muljadi, P. Srensen and Y. C. Kang, "Releasable Kinetic Energy-Based Inertial Control of a DFIG Wind Power Plant," in *IEEE Transactions on Sustainable Energy*, vol. 7, no. 1, pp. 279-288, Jan. 2016, doi: 10.1109/TSTE.2015.2493165.

[2] R. Sakamoto, T. Senjyu, N. Urasaki, T. Funabashi, H. Fujita and H. Sekine, "Output power leveling of wind turbine generators using pitch angle control for all operating regions in wind farm," *Proceedings of the 13th International Conference on, Intelligent Systems Application to Power Systems*, Arlington, VA, 2005, pp. 1-6, doi: 10.1109/ISAP.2005.1599291.

[3] IEEE Working Group on Prime Mover and Energy Supply Models for System Dynamic Performance Studies, "Hydraulic Turbine and Turbine Control Models for Dynamic Studies," *IEEE® Transactions on Power Systems*, Vol. 7, No. 1, February, 1992, pp. 167-179.

Step Change in 3+3+3 MW Wind Generation in Blue Lake, Green Lake and Starrigavan



Total load is 11.85 MW.





Step Change in 3+3+3 MW Wind Generation in Blue Lake, Green Lake and Starrigavan







Wind Generation Buses



Step Change in 6 MW Wind Generation (Blue Lake)

Total load is 11.85 MW. Synchronous Generation Response (Blue Lake) PCC L-L RMS Voltage (Wind Generation) Green Lake Machine Bus Voltage 10 Blue Lake Machine Bus Voltage -Va 7.2 -Va -Va 13 13 8 -Vb -Vb -Vb -Vc Power(MW) Vc Vc 7.1 12.8 12.8 6 Voltage(kV) 12.4 12.4 voltage(kV) 8.9 4.0 2 h voltage(kV) 157 2 Wind Generation (Blue Lake Switchyard) 12.2 12.2 0 6.7 7 12 12 -2 20 6.6 6 100 120 40 60 80 140 100 120 140 20 40 60 80 20 40 60 80 100 120 140 120 20 60 80 100 140 40 5 Time(sec) time(sec) Time(sec) time(sec) Power(MW) Medium Voltage Node (fvu-gen) Low Voltage Node (dp1) High Voltage Node (medv-tap) 4.35 72 -Va Va 1 Synchronous Generation Response (Green Lake) -Vb Vb Vb 4.3 215 Vc -Vc 71 0 4.25 (A) 4.2 Voltage(kV) 8 6 0 (V) 210 10 -1 20 40 60 80 100 120 140 \$ 205 Time(sec) 5 4.1 Power(MW) 4.05 67 200 66 2 20 60 80 100 120 140 100 120 140 20 40 60 80 20 40 60 80 100 120 140 Time(sec) Time(sec) Time(sec) 0 -2 20 60 100 120 40 80 140 Time(sec)

Step Change in 6 MW Wind Generation (Green Lake)

Total load is 11.85 MW.



Step Change in 6 MW Wind Generation (Starrigavan)



Ramp Down in 6 MW Wind Generation (Blue Lake)



Ramp Down in 6 MW Wind Generation (Green Lake)



Ramp Down in 6 MW Wind Generation (Starrigavan)



Step Change in 9 MW Wind Generation (Green Lake)

20

40

60

Time(sec)

80

100

120

Time(sec)



Step Change in 9 MW Wind Generation (Starrigavan)



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Ramp Down in 9 MW Wind Generation (Green Lake)

Time(sec)

Time(sec)



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Ramp Down in 9 MW Wind Generation (Starrigavan)



Bus Over-Voltage Tests for 12 MW Wind Turbine Installation (Green Lake)

-Vb

Vo

70 80

Time(sec)



Time(sec)

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Bus Over-Voltage Tests for 15 MW Wind Turbine Installation (Green Lake)

Time(sec)

-Va

-Vb

Vc



Time(sec)

Time(sec)

Bus Over-Voltage Tests for 12 MW Wind Turbine Installation (Starrigavan)





Bus Over-Voltage Tests for 15 MW Wind Turbine Installation (Starrigavan)

Time(sec)

Time(sec)

 Time(sec)



Load Increase to Limit Bus Over-Voltages

- 3 MW load control is activated to mitigate over-voltage due to 15 MW wind turbines installation
- PCC bus voltages are still outside the limit



Frequency Instability and Generation Control

- 15 MW wind power is ramping down to zero
- Frequency ramps down. Restoration by hydro generation control after it's below 59.5 Hz
- At t = 28.5 s, synchronous machine controls are activated, load is reduced by about 3 MW and each machine supports around 6 MW to stabilize frequency.



Ramp Down in Wind Generation

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Frequency restoration starts below 59.5 Hz via the generation controls

For Stability:

- Load-Generation balance is crucial
- Only load control cannot ensure stability
- Blue and Green synchronous generation controls are essential

Conclusions

Built dynamic model which evaluates grid stability and control impacts with addition of renewable generation

- □ As wind generation size grows **voltage stability** can be a potential challenge.
- As wind gusts ramp up/down, **frequency stability** can be a potential challenge (*especially at higher wind generations*).
- □ Wind-Hydro control coordination is essential to achieve robust Sitka grid control.
- □ Hydro generation **load acceptance**, and ramp up/down capability should be assessed (especially at higher wind generation)

Conclusions

Existing hydro and load control can support up to 9 MW of wind penetration.

- Advanced load control in microgrid is not sufficient to achieve robust voltage stability in Sitka grid.
- Upgrades to controls/storage needed for stability and control with additional wind/solar generation.



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