

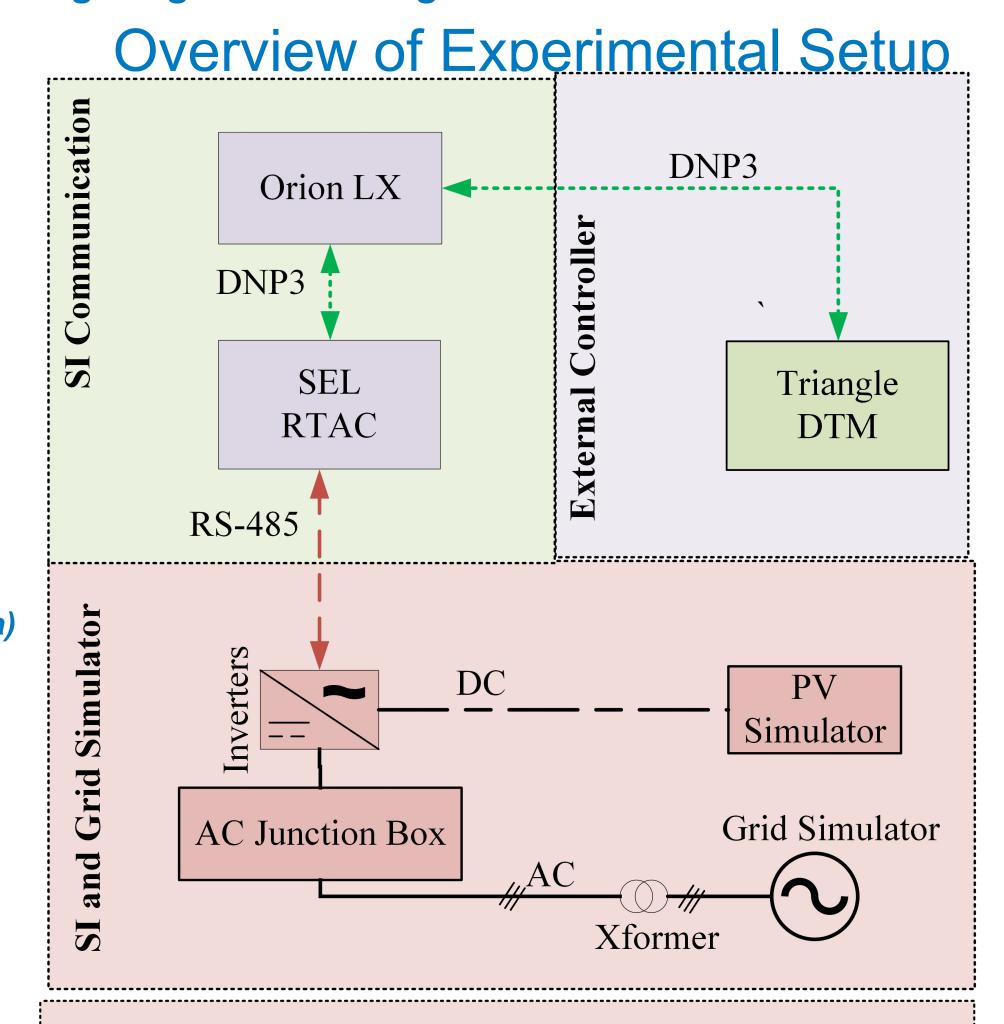
# Experimental Analysis of Distribution Network Voltage Regulation Using Rasel Mahmud, Subhankar Ganguly, Jing Wang, and Killian McKenna

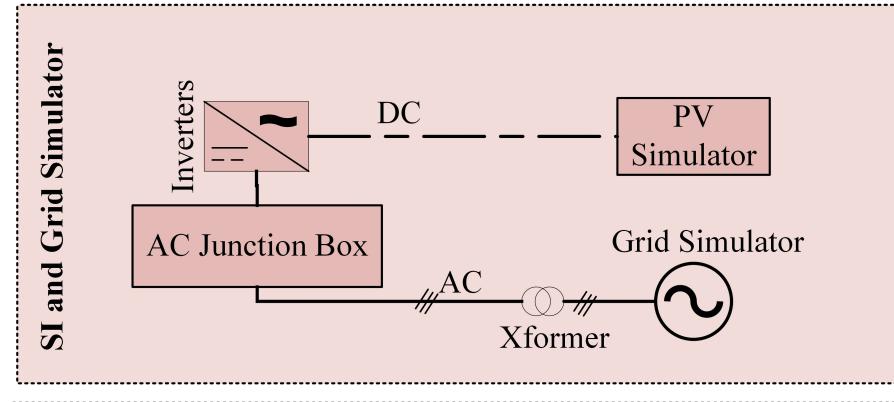
Smart Inverters

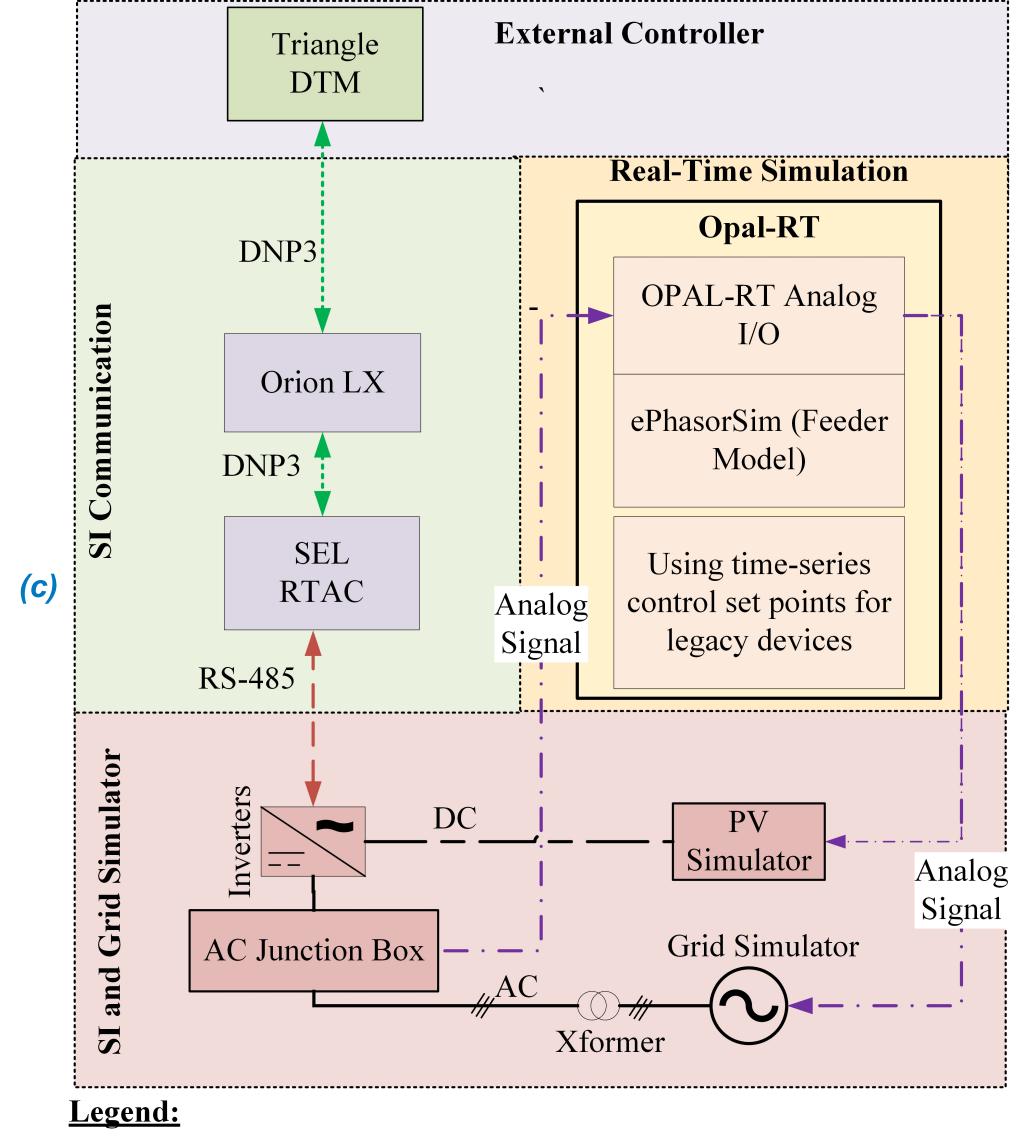
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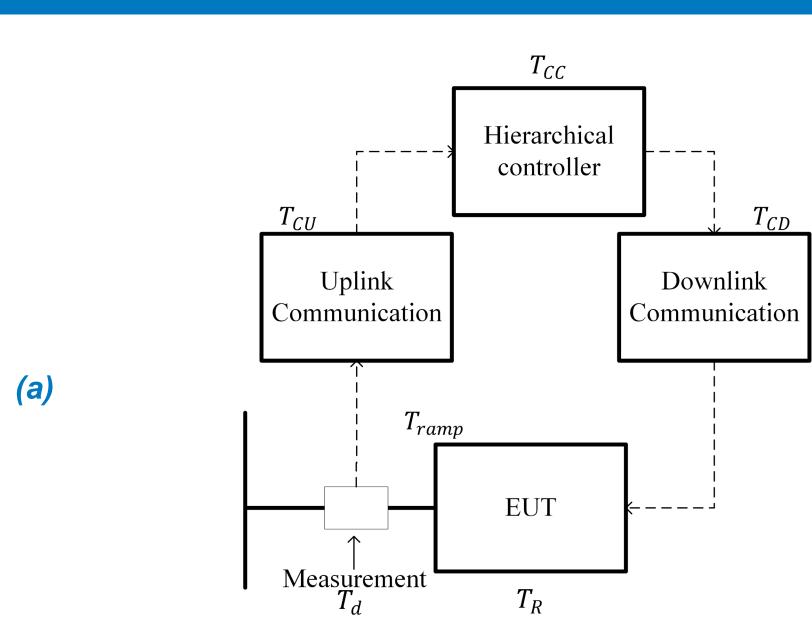
## Abstract

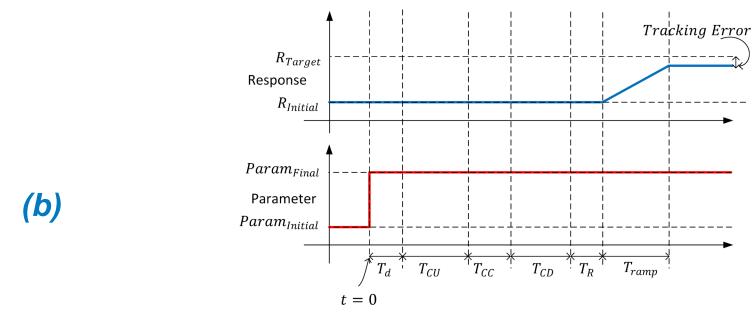
In this presentation, we discuss the potential of smart inverters (SIs) to provide grid services, focusing on their ability to regulate voltage in distribution networks. The paper presents an experimental study comparing two control methods for SI reactive power regulation: autonomous control and remote dispatch, highlighting important differences in response characteristics and emphasizing the need to consider these factors when planning for voltage regulation using SIs in distribution networks.









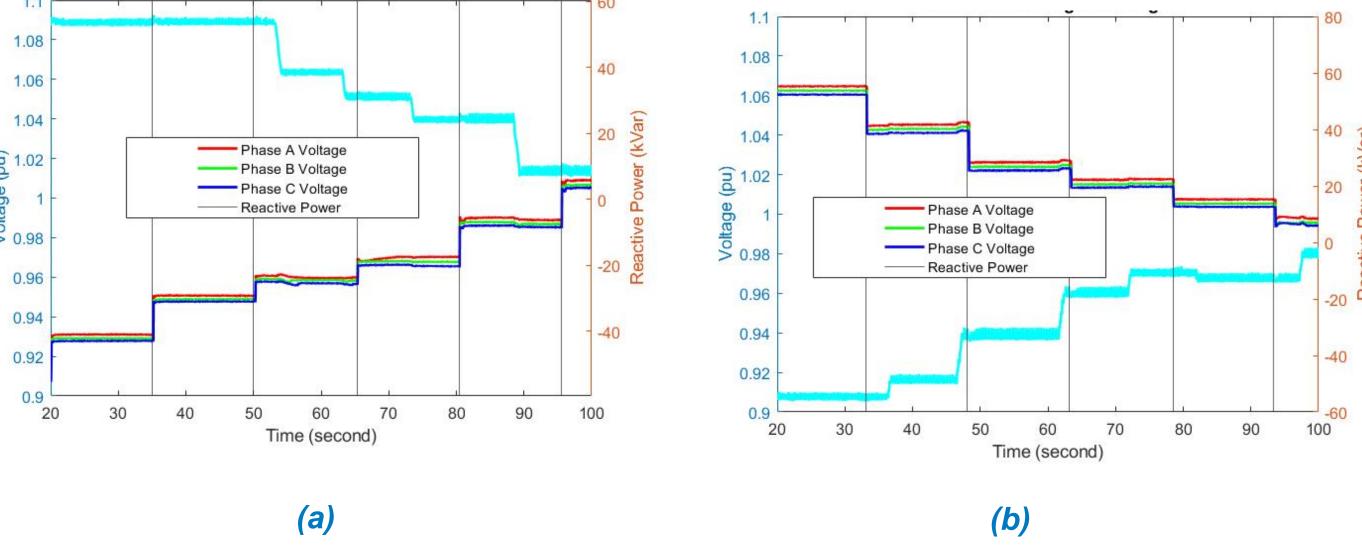


Grid services from inverter: a) generic connection and signal flow diagram for the SIs, b) typical response from SIs.

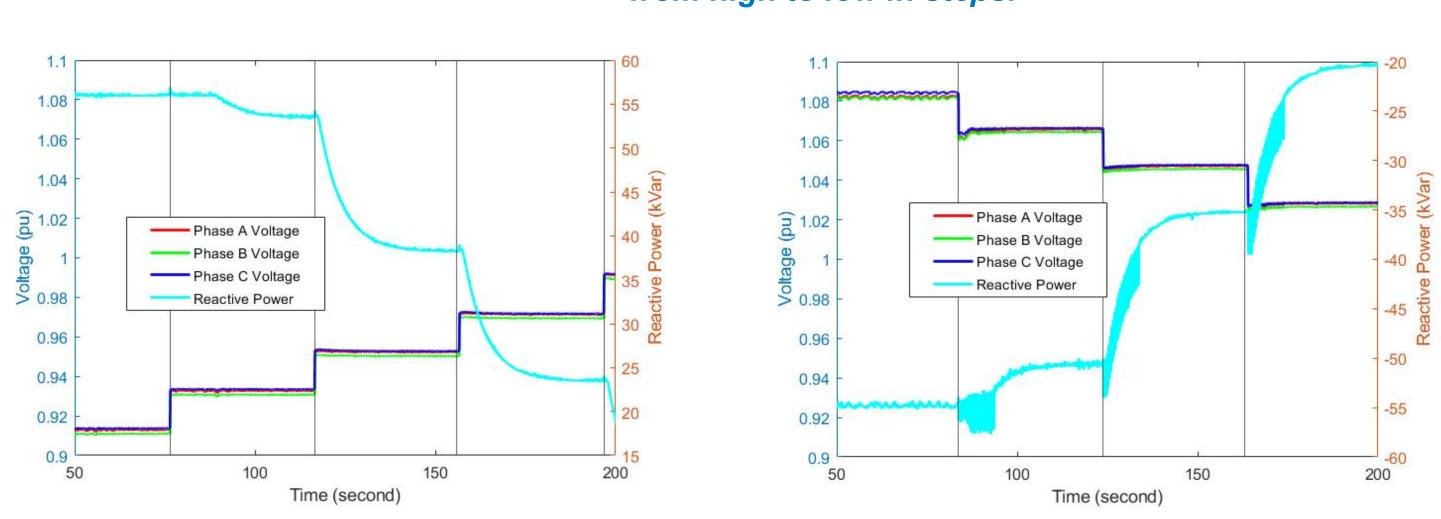
# **Experimental Results**

Case #	Description	Test Step	Objective
1	Remote dispatch method: Open-loop DTM to inverter Q command*	Send Q1=0kVar and Q2=55kVar** from DTM to inverter Send Q1=55kVar and Q2=0kVar** from DTM to inverter	Determine the ramping time (Tramp).
2	Remote dispatch method: Closed-loop DTM to inverter Q command* (volt-var in DTM)	Change AC PCC voltage from high to low and low to high.	Test the interoperability performance between the DTM and the inverters using the applied communication method.     Characterize the inverter response in remote dispatch method.     Identify any stability and/or unknown issue for inverter control from an external controller.
3	Autonomous SI control: volt-var in inverter	Change AC PCC voltage from high to low and low to high.	<ol> <li>Characterize the volt-var function in autonomous SI control.</li> </ol>

#### Characterization Test Matrix



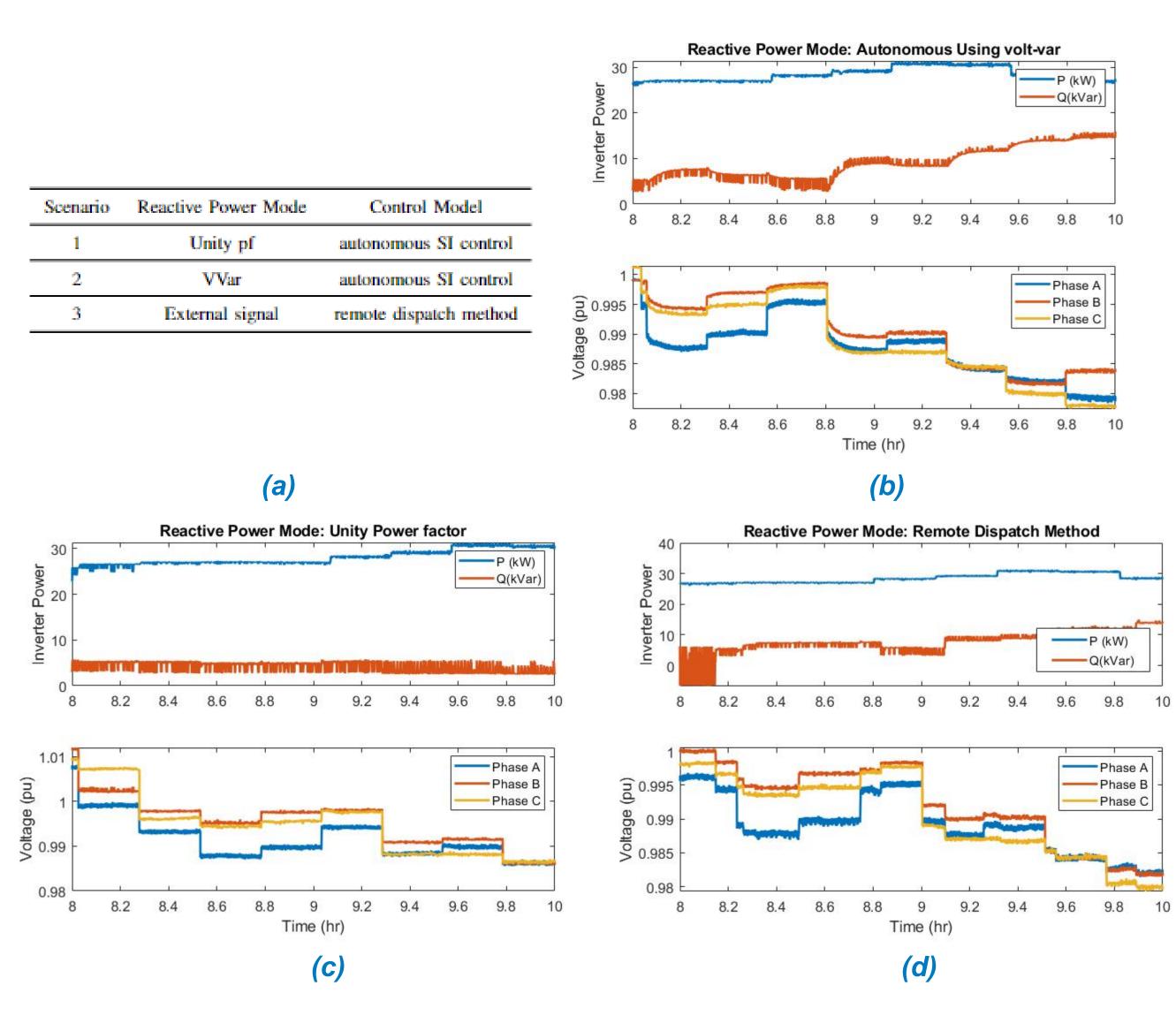
Performance of the inverter in remote dispatch method with volt-var hosted in the DTM: a) voltage changes from low to high in steps; b) voltage changes from high to low in steps.



Test result to characterize the inverter volt-var response in autonomous SI control: a) voltage changes from low to high; b) voltage changes from high to low.

Characterization Parameter	Statistical Parameter	Remote Dispatch	Autonomous
$T_L^{-1}$	Mean	11.74	0.77
Unit: second	Std. deviation	4.78	0.31
	Maximum	20.16	1.20
	Minimum	2.80	0.20
Positive ramp rate 2	Mean	10.87	0.45
Unit: %/second	Std. deviation	3.68	0.13
	Maximum	16.26	0.58
	Minimum	6.37	0.15
Negative ramp rate 3	Mean	-10.02	-0.49
Unit: %/second	Std. deviation	2.96	0.01
	Maximum	-4.50	-0.47
	Minimum	-14.05	-0.51

Quantitative Comparison of remote dispatch method to autonomous SI control Response



PHIL test result to evaluate the applicability of remote dispatch method and autonomous SI control: a) Scenarios tested Using PHIL Setup, b) Scenario 1, c) Scenario 2, d) Scenario 3.

### Conclusion

- The experimental study successfully demonstrated and validated the communication setup from a remote controller to a smart inverter (SI) using intermediate communication gateways.
- The study demonstrated that the smart inverter (SI) successfully received external control signals for remote dispatch of reactive power set points, with response times varying from 2 to 20.16 seconds. The remote dispatch method also exhibited faster ramp rates, ranging from 6.3%/second to 16.26%/second (positive) and -4.5%/second to 14.05%/second (negative), while the autonomous SI control mode, including inverter embedded control response, showed slower average ramp rates of 0.45%/second (positive) and -0.49%/second (negative).
- Delays in communication and response times may pose concerns for voltage control, suggesting potential benefits of utilizing a hybrid communication architecture that combines remote control and dispatch with the ability to receive inverter measurements for updating remote settings from a centralized controller.

Experimental setup to evaluate the performance of grid services from smart