

# Advanced Permanent Magnet Generator Topologies Using Multimaterial Shape Optimization and 3D Printing

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## Acknowledgments

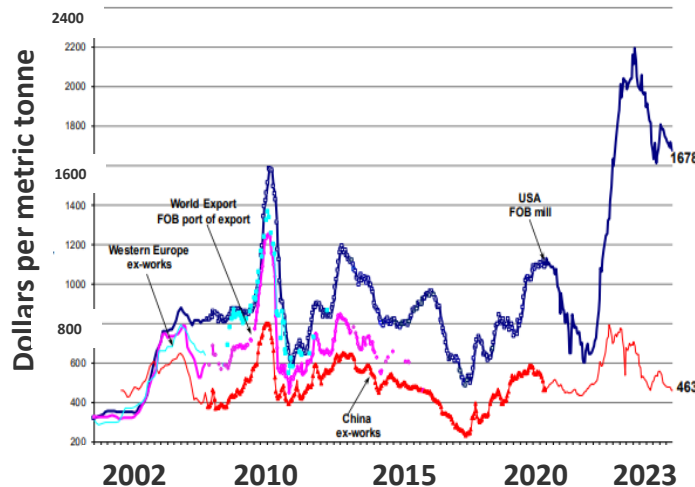
Tod Hanley (Bergey Windpower), Mike Bergey (Bergey Windpower)

# Background

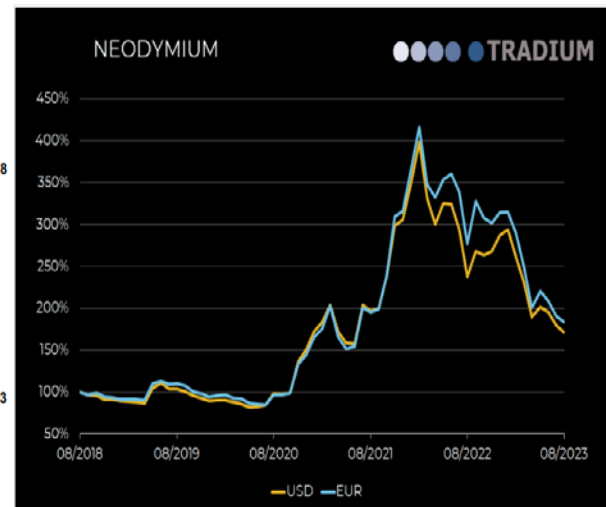
Several small wind OEMs are facing supply chain bottlenecks for key raw materials.

- Rare earth magnets and steel prices have been volatile.
- Manufacturing costs have doubled.

The OEMs are pursuing continuous improvements to their generator designs to lower the cost/kW installed.



Steel price trend. Source: [Steel Benchmarker](#)



Neodymium price trend. Source: [Tradium](#)



Bergey Excel 15-kW direct drive permanent magnet generator.

Photo credit: [Bergey Wind Company](#)



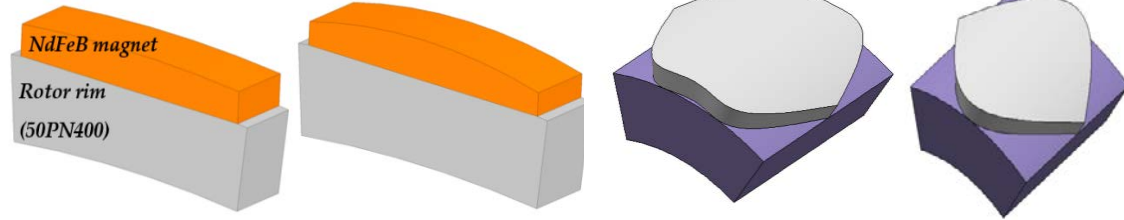
Aeolos 50-kW direct drive permanent magnet generator.

Photo credit: [Aeolos Wind Turbine Company, UK](#)

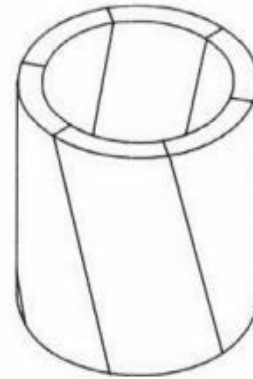
*PM mass typically between 5 and 15 kg.*

# Focus Areas for Small Wind OEMs

1. Improve efficiency
  - a) Thinner laminations
2. Minimize cogging torque
  - a) Magnet edge shaping (bread-loaf)
  - b) Varying magnet width
  - c) Skewing stator stack
3. Minimize manufacturing cost.



Methods: Magnet shaping, e.g., use of bread-loaf and tapered bread-loaf magnets (Son and Lee 2023) and butterfly and egg-shaped magnets (Du and Lipo 2019).



Magnet skewing

Manufacturing of shaped magnets needs molds, including skewed ones, which increase their cost and wastage.



Stator stack skewing

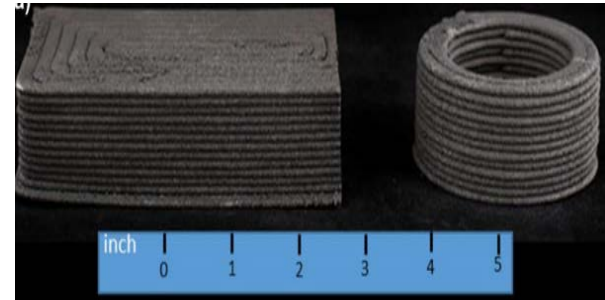
Skewing makes slot filling difficult and also increases tooling costs.

# Recent Trends in Manufacturing

- Fe3.0Si and Fe6.5 steels have been fabricated by selective laser melting and binder jetting and have resulted in new high-performing designs.
- NdFeB-bonded magnets fabricated via extrusion process have shown energy product of 20 MGOe demonstrated to date and have promising electrical properties.



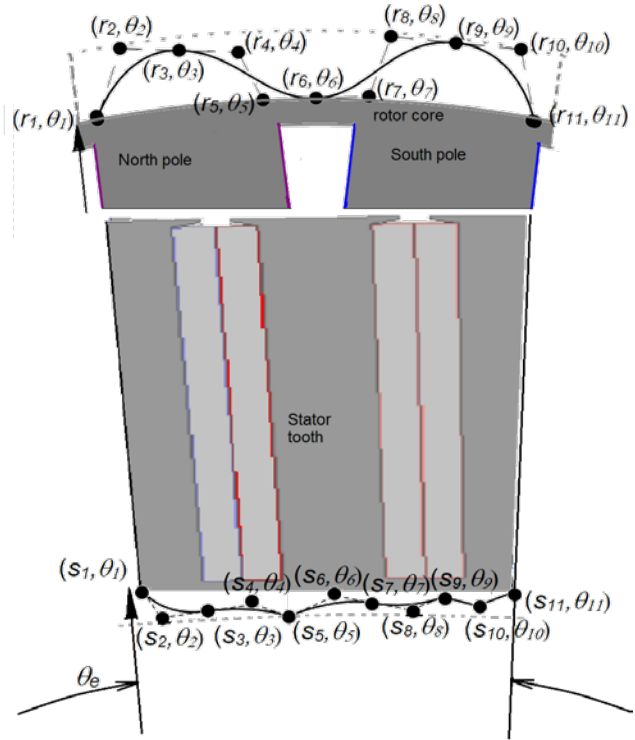
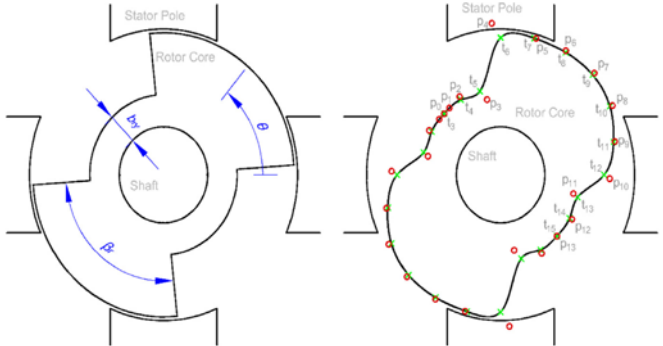
New cross-sectional geometries have been shown to reduce the eddy current losses in cores (Goodall et al. 2023).



Polymer bonded printed magnets from Gandha et al. (2020).

# Recent Trends in Design: Shape Optimization

- Boundaries of geometries are parametrized using curves.
- Recent work using Bézier curves by the authors showed smoother shapes that can be realized and better opportunities for lightweighting generator.



A rotor shaped by B-spline curves and machined by wire-EDM (electro-discharge machining). This technique is too expensive for mass production (Lee et al. 2003).

Bézier parametrization (Sethuraman and Vijayakumar 2022).

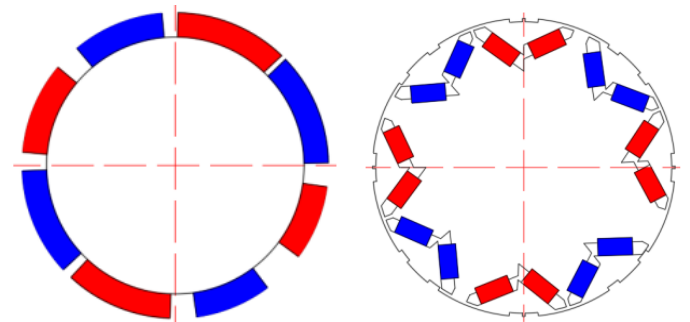
# Research Gaps

- Optimization techniques focus on **symmetrical design** approach.
  - Assumes that every pole or tooth geometry is identical and symmetric.
  - All electrical characteristics are repeated
- Very little research has been done on **asymmetrical design** approaches.
  - Selective shaping of poles allows for a variable air-gap profile and improves back-electromotive force waveform.
  - Can help conserve material and minimize mass.
  - Helps minimize cogging and ripple torques.

High manufacturing cost due to the complexity

More useful if the electric machine rotates in two directions—can result in excessive material use.

More useful if the electric machine rotates in one direction.

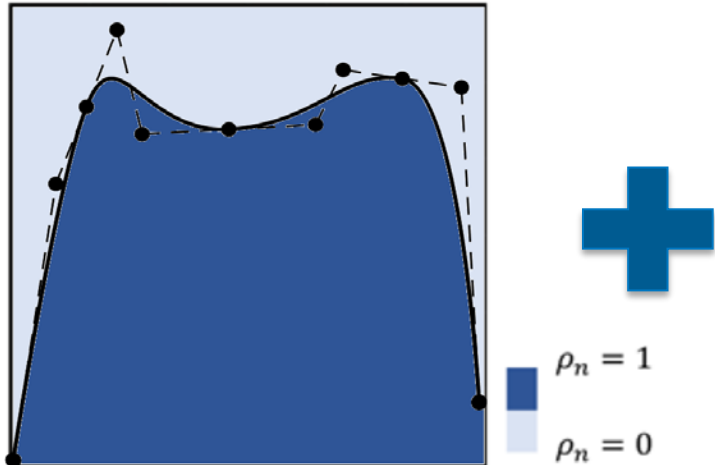


Examples of asymmetric designs (Sun et al. 2019).

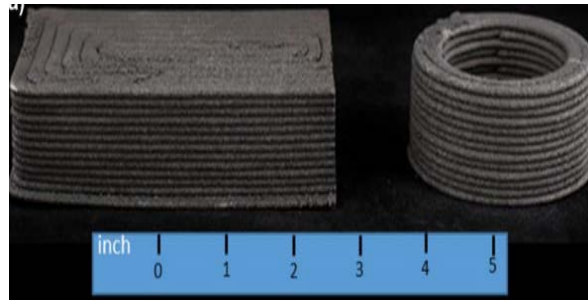
# This Work

Explored full design space for a baseline 15-kW wind turbine generator using printed materials (magnets and electrical steel):

- Interpolar shape optimization exploring novel symmetric and asymmetric designs
- Extending the Bézier curve approach for magnets and electrical steel for multimaterial shape optimization.

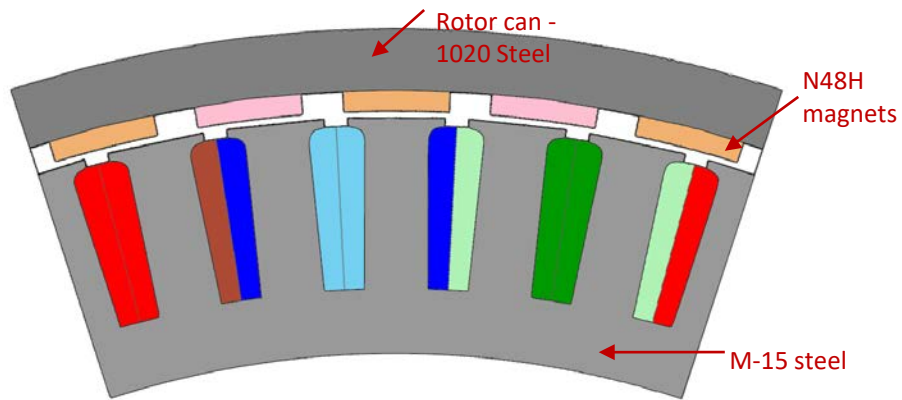


Bézier curve approach



Printed magnet properties inferred from Gandha et al. (2020).

# Baseline Design Specifications and Targets



Baseline 15-kW permanent magnet synchronous generator modeled around Bergey wind turbine

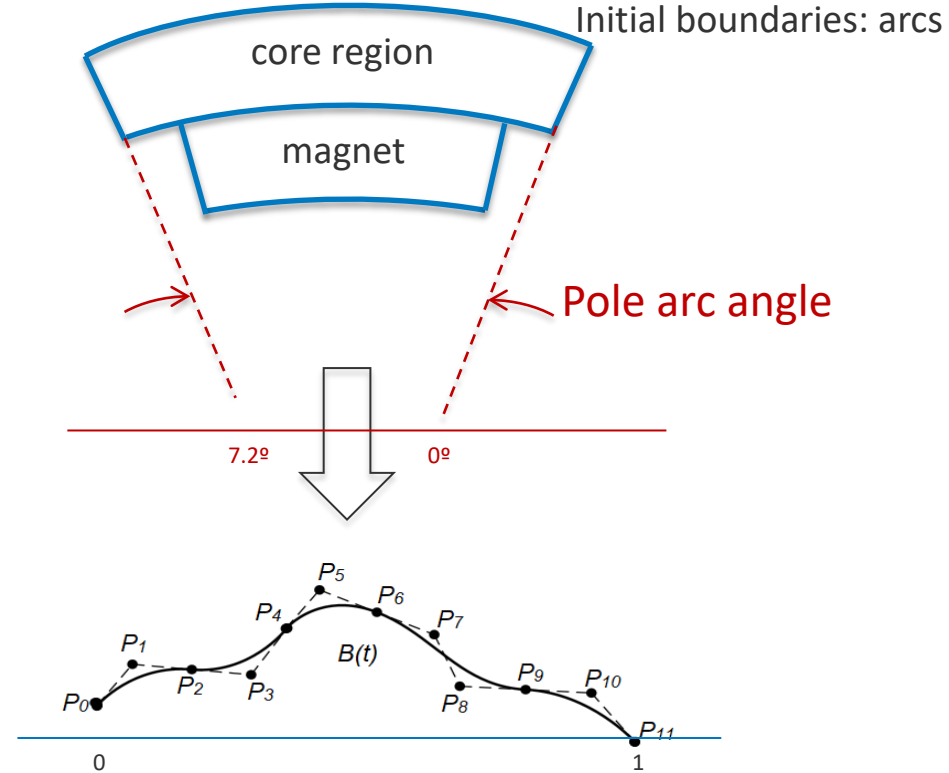
- Fractional-slot concentrated winding
- *Slot-pole combination*
  - 60 slots, 50 poles.

## Performance Parameters and Optimization Targets

Parameter	Baseline	Target
Rated voltage	$\leq 575$ V	$\leq 575$ V
Efficiency	95%	$\geq 95\%$
Cogging torque	33 Nm	$< 25$ Nm
Magnet material	Sintered	Printed polymer-bonded (0 % Dy)
Magnet resistivity ( $\Omega\text{m}$ )	$1.5 \times 10^{-6}$	0.0258
Normal coercivity at 60°C	1041.7	485.9
Magnet $BH_{\text{max}}$ (MGOe)	45	20
Rotor core material	1020 steel	1020 steel/cast iron
Magnet mass	1 p. u.	$< 0.9$ pu
$B_{\text{rmin-SC and stall}}$ (T)	0.45	0.3
$T_{\text{winding}}$	180°C	180°C
$T_{\text{mag}}$	60°C	60°C

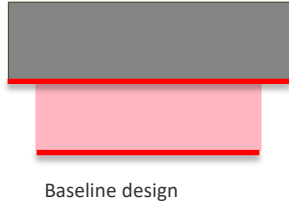


- Rotor and magnet boundaries were simultaneously changed to result in shapes that yielded better performance.
- Circular arcs were converted to **parametrized Bézier curves** with control points defining the radius at each angular position.
- Shapes can be easily manufactured by transferring control points to commercial CAD tools or 3D printers.
- Very popular for designing turbine blades and ship hulls.

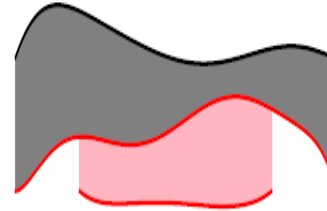
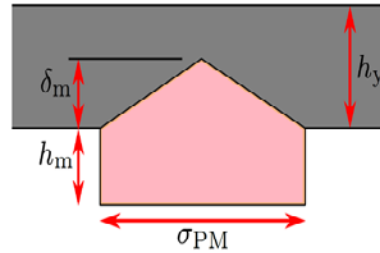


Boundaries redefined using Bézier curves.

# Types of Parametrization



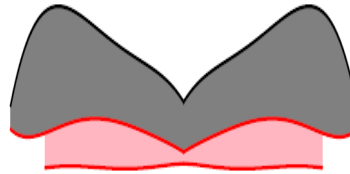
- Five different parametrizations were studied.
- Both front and rear side of magnets are shaped.
- The optimized designs with printed magnets were compared against baseline Bergy design with N48H grade.



Asymmetric pole: nonconstant air-gap



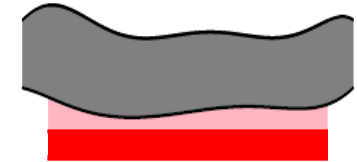
Asymmetric pole: constant air-gap



Symmetric pole: nonconstant air-gap



Symmetric pole: constant air-gap



Multimagnet asymmetric pole: constant air-gap

# Symmetry Parametrization

- Three Bézier curves define the shape of one pole.
- Each curve is defined by six points.
- Each point in cartesian coordinate  $\rightarrow$  polar coordinate.
- Shape of right half==mirror symmetry of left.

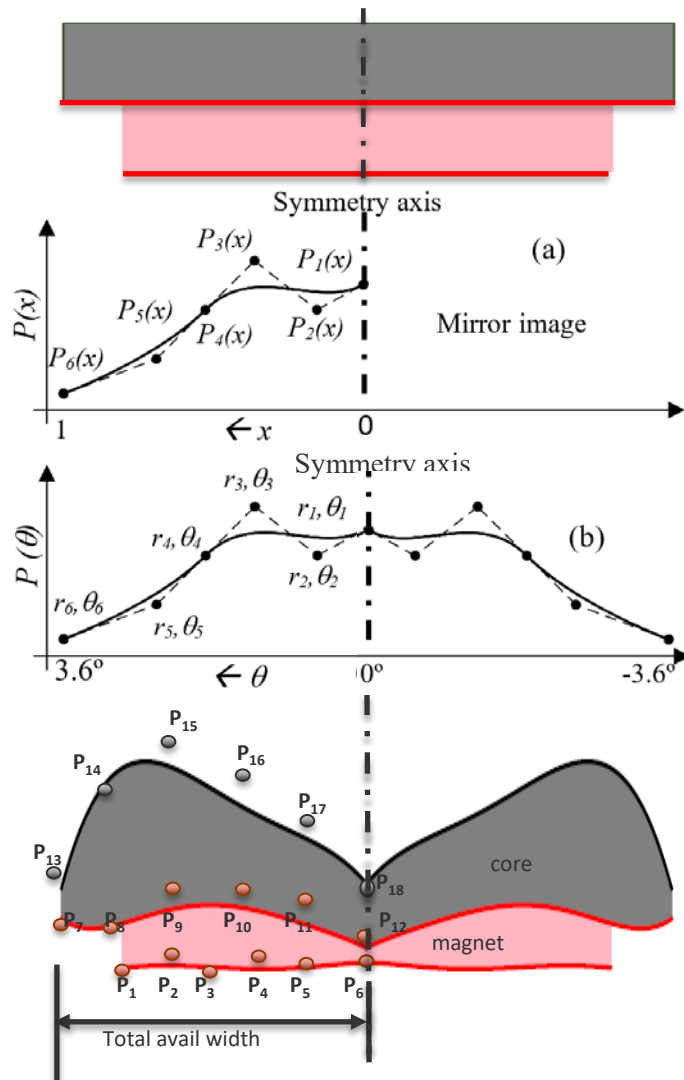
$$P_i(\theta_i) = r_i, \theta_i$$

$$= P_i(x_i) \cos(i\delta\theta), P_i(x_i) \sin(i\delta\theta), \text{ for } i = 1 \text{ to } 6$$

Design variables:

18 control points : P1-P18

$$\text{Ratio} = \frac{\text{actual width}}{\text{total available width}}$$



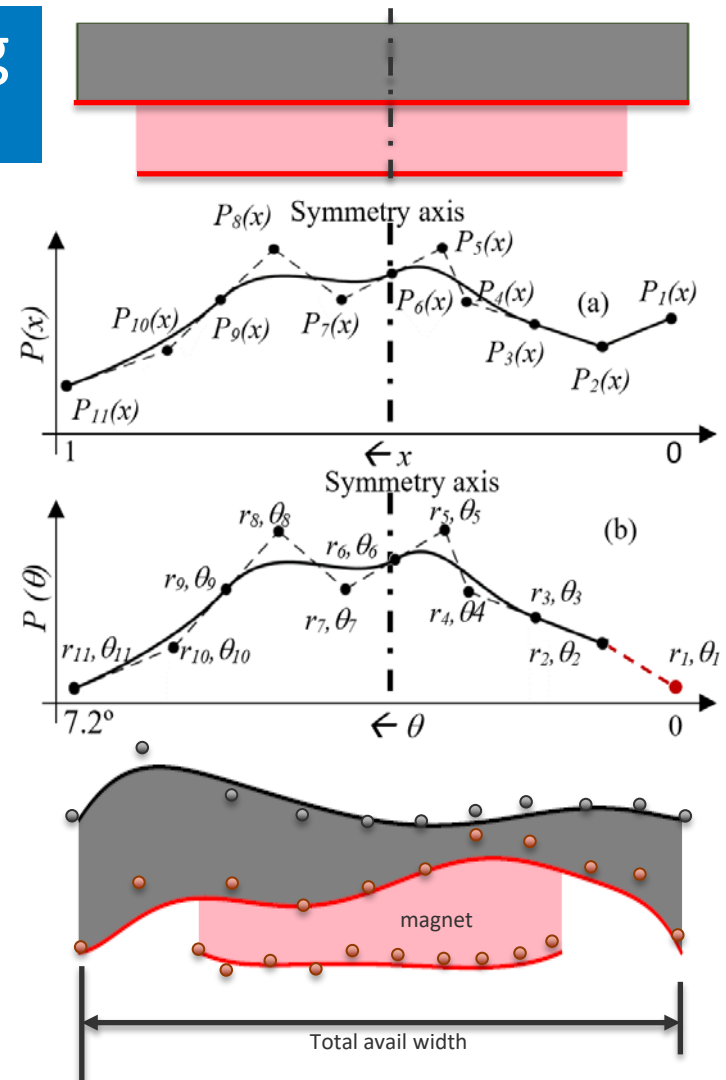
# Asymmetry Parametrization Using 33 Control Points

- **Three Bézier curves define the shape of one pole.**
- **Each curve is defined by 11 points.**
- **Each point in cartesian coordinate  $\rightarrow$  polar coordinate.**
- Shape has no symmetry with respect to center line.

Design variables:

33 control points : P1-P33

$$\text{Ratio} = \frac{\text{actual width}}{\text{total available width}}$$



# Multimaterial Parametrization

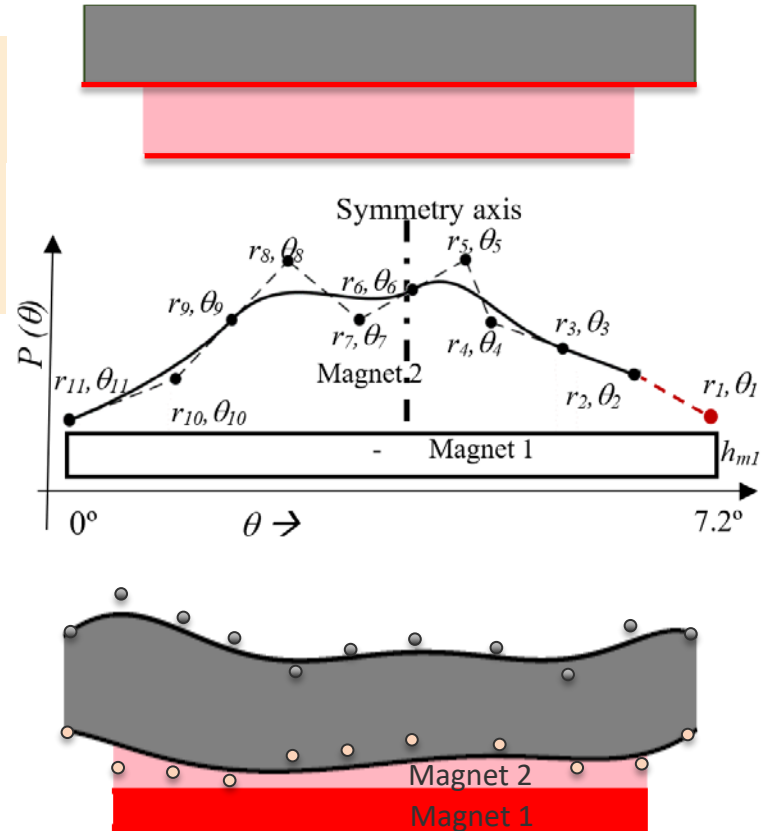
- Two Bézier curves define the shape of one pole.
- Design controlled by 11 control points on each curve.
- Sintered magnet closest to air gap.
- Sintered magnet is assumed to have a flat base.

Design variables:

12 control points : P1-P22






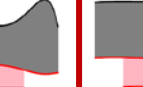


$$\text{Ratio} = \frac{\text{actual width}}{\text{total available width}}$$

Thickness of sintered magnet

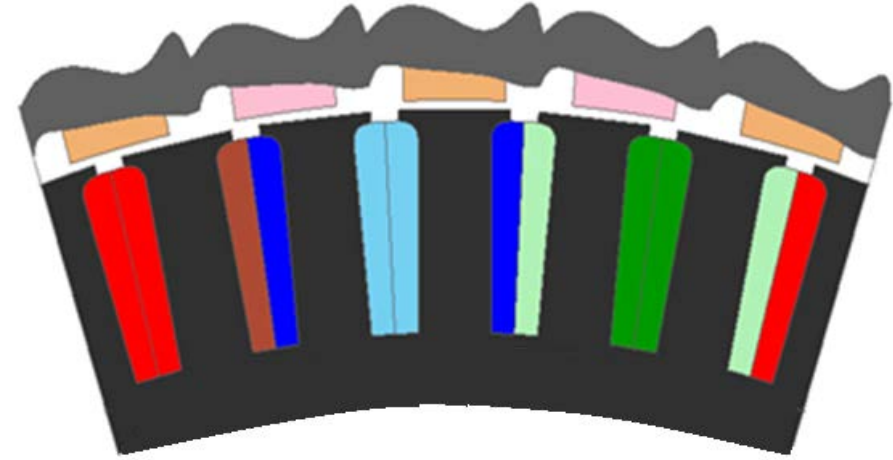


# Results

Asymmetric designs were lighter by up to 27% and 35% respectively.

Designs	Baseline Design	I	II	III	IV	V	VI	VII
		Re-Optimized Baseline	Crown Design	Asymmetric Pole: Nonconstant Air Gap	Asymmetric Pole: Constant Air Gap	Symmetric Pole: Nonconstant Air Gap	Symmetric Pole: Constant Air Gap	Multimaterial Asymmetric Pole: Constant Air Gap
Magnet material	Sintered higher grade with zero dysprosium	N48H sintered magnet with zero dysprosium	55.5% weaker printed polymer-bonded magnet with zero dysprosium					
Magnet mass (pu)	1.0	0.59	0.84	0.75	0.73	0.845	0.82	0.65
Efficiency (%)	96.1	96.9	97.1	96.9	96.88	97.05	96.99	97.05
$B_{rmin}$ (T)	0.453	0.456	0.3	0.31	0.31	0.299	0.302	0.50
$T_{cog}$ (Nm)	25.33	24.8	24	24.21	23.18	27.5	24.78	24.105
Ratio	proprietary	69	65.8	64.62	60.23	65.95	60.64	68.97
Optimized design								
% magnet weight change	-	-41	-16.0	-25	-26.5	-15.45	-18	-35

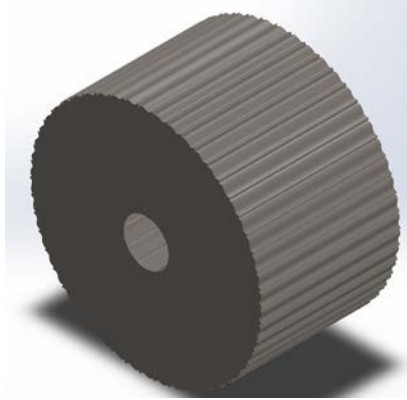
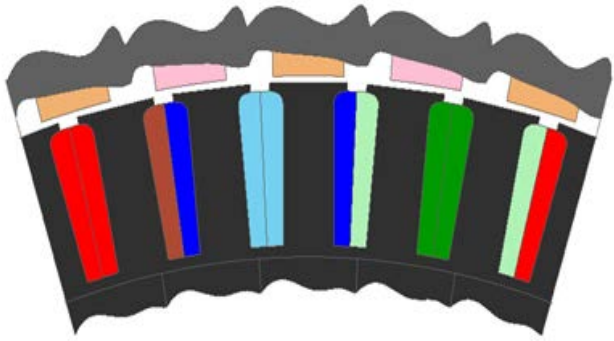
# Results From Magneto-Thermal Evaluation



Notice the material bias for a counterclockwise direction.

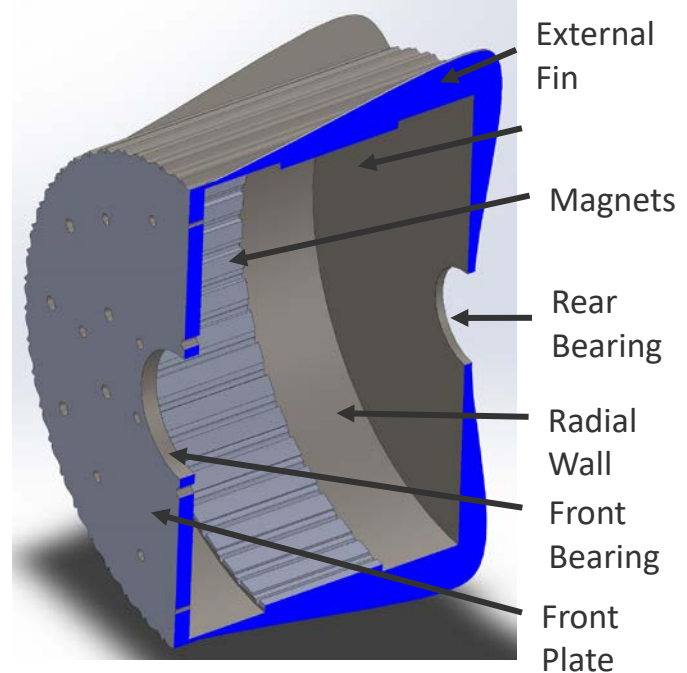
- Asymmetric pole designs are lighter than symmetric pole designs → overuse of materials for unidirectional application, especially wind turbine generators.
- Magnet profiling near the air gap (nonconstant air gap designs) can minimize cogging torque; however, it results in heavier designs.
- The combination of sintered and printed magnets in a layered approach is cost-competitive and results in lightest designs.

# Structural Evaluation of Asymmetric Rotor Can



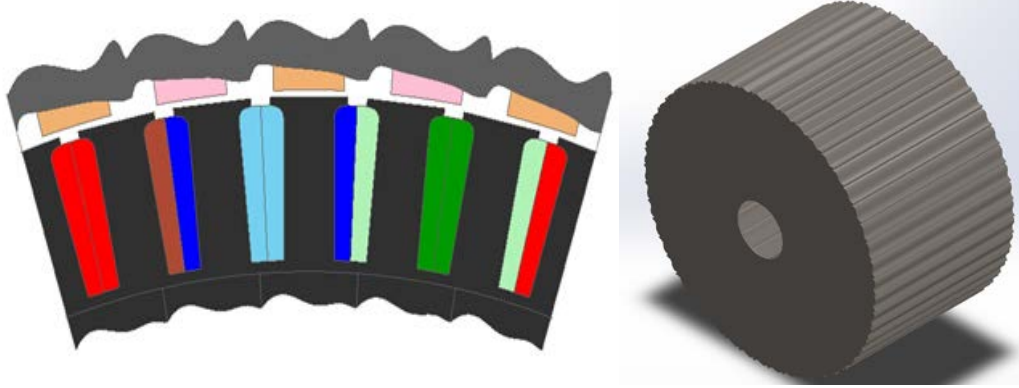
Six parameters were varied to further explore the design space.

- 2D model extruded to 3D.
- Goals: Verify structural integrity by static structural analysis.
- New features: Stiffening fins visible on the back side of the rotor can.
- Parametrize the can and optimize the dimensions





# Results From Structural Evaluation



- Wave-shaped profile on the rotor cylinder adds stiffness to radial deformation.
- It can also help improve aerodynamic efficiency.
- Optimal solution within the design space, which reduced overall mass by approximately 13 kg.

Parameter	Baseline	Optimized
Radial wall thickness (mm)	10.312	3.175
Front plate thickness (mm)	19.05	12.7
Back plate thickness (mm)	9.525	3.175
Number of fins (mm)	0	0
Total structural mass (kg)	108.83	95.16
Radial stiffness/weight	2,027.8	1,063.5

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NREL/PR-5000-87649

This work was authored in part by the National Renewable Energy Laboratory, operated by Alliance for Sustainable Energy, LLC, for the U.S. Department of Energy (DOE) under Contract No. DE-AC36-08GO28308. Research at NREL and ORNL were funded by the U.S. Department of Energy Office of Energy Efficiency and Renewable Energy Wind Energy Technologies Office. The views expressed in the article do not necessarily represent the views of the DOE or the U.S. Government. The U.S. Government retains and the publisher, by accepting the article for publication, acknowledges that the U.S. Government retains a nonexclusive, paid-up, irrevocable, worldwide license to publish or reproduce the published form of this work, or allow others to do so, for U.S. Government purposes.

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