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Experimental Characterization Test of a Grid-Forming Inverter for Microgrid Applications

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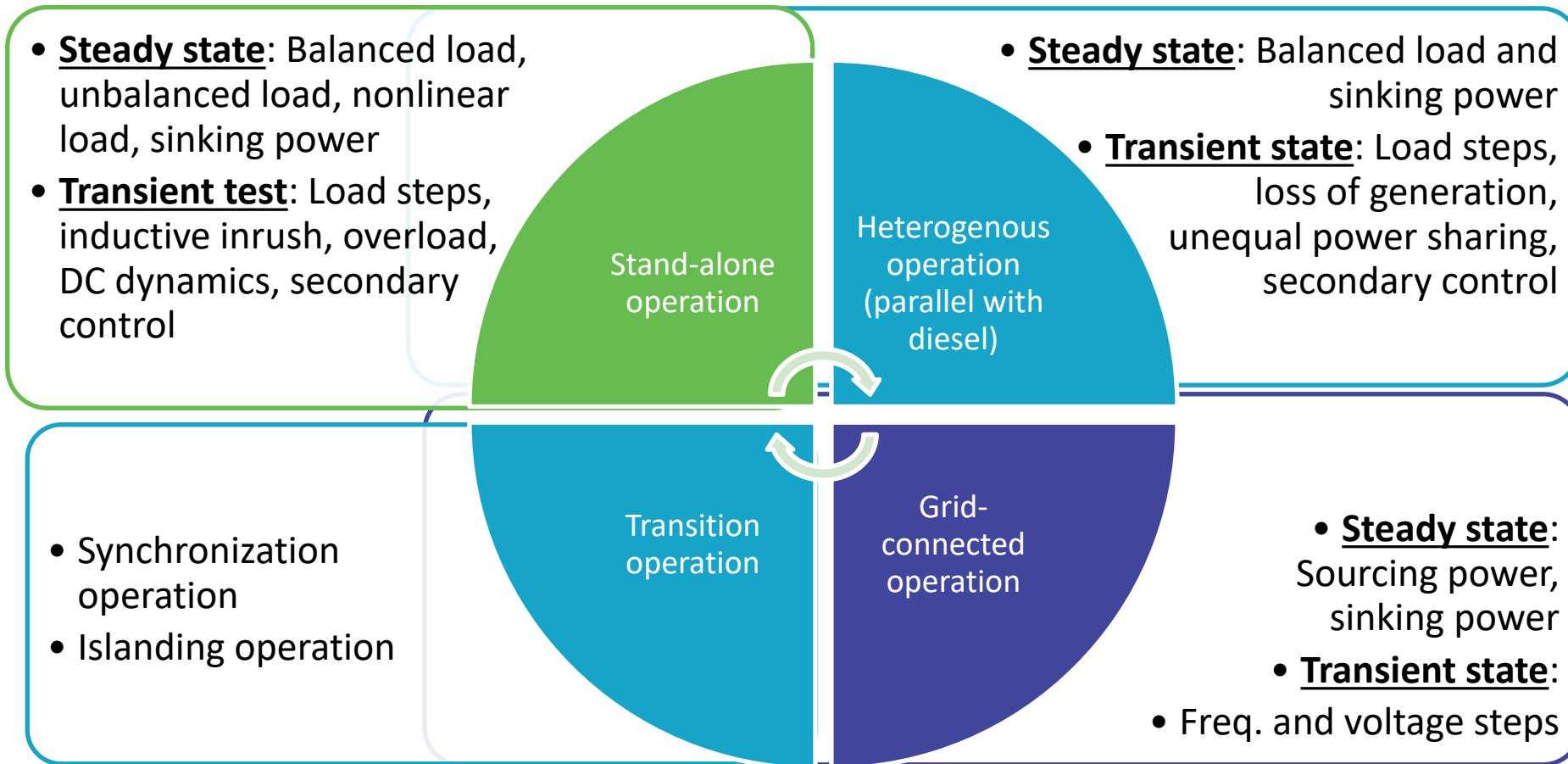


GOAL OF UNIFI MULTI-VENDOR GFM

INVERTER EVALUATION

- There is a lack of standard testing protocols for grid-forming (GFM) inverters.
 - Develop standard testing protocols to understand the performance of GFM inverters.
- Explore the interoperability and functionalities of GFM inverters.
 - Test the key operation functions of GFM inverters (stand-alone, heterogenous operation, grid-connected, and transition operation)
 - Use findings to drive GFM specifications.
- Provide findings and guidelines for industry and academia.
 - How to configure and control the GFM inverter?
 - What are the research gaps?

HIGH-LEVEL VIEW OF TESTING SCENARIOS



- Steady state: 5%, 10%, 25%, 50%, 75%, 100%, PF=1, 0.8 lagging and leading, pure inductive and capacitive loads
- Transient state: 25%, 50%, 75%, and 100% PF=1, 0.8 lagging and leading
- Transition operation: 50% PF=1, 0.8 lagging and leading

HARDWARE EXPERIMENT TEST SETUP

- GFM inverter specs.:
 - 250 kVA, need a delta:wyne transformer
 - GFM (VF), GFL (PQ), and grid-supporting control (VF/PQ) control.
- Testing circuit (microgrid):
 - Grid simulator (540 kVA)
 - PCC switch
 - GFL inverter (125 kVA)
 - Diesel (187.5 kVA)
 - Load banks (500 kVA).
- Control and communication:
 - Configure the GFM inverter to always operate in GFM control.
 - Modbus TCP
 - Heartbeat, voltage, and frequency droop intercept, and droop slope (Modbus register map).

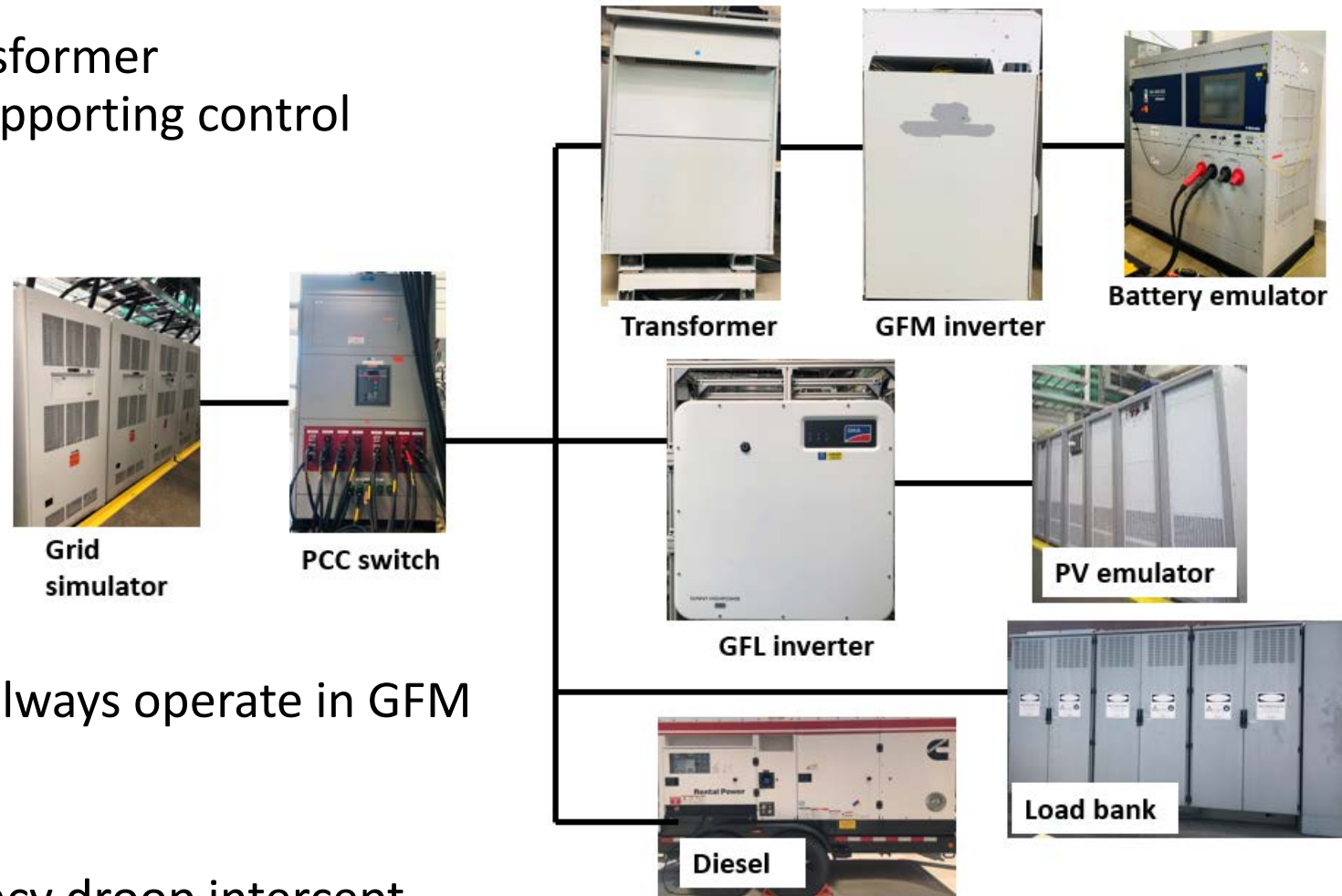
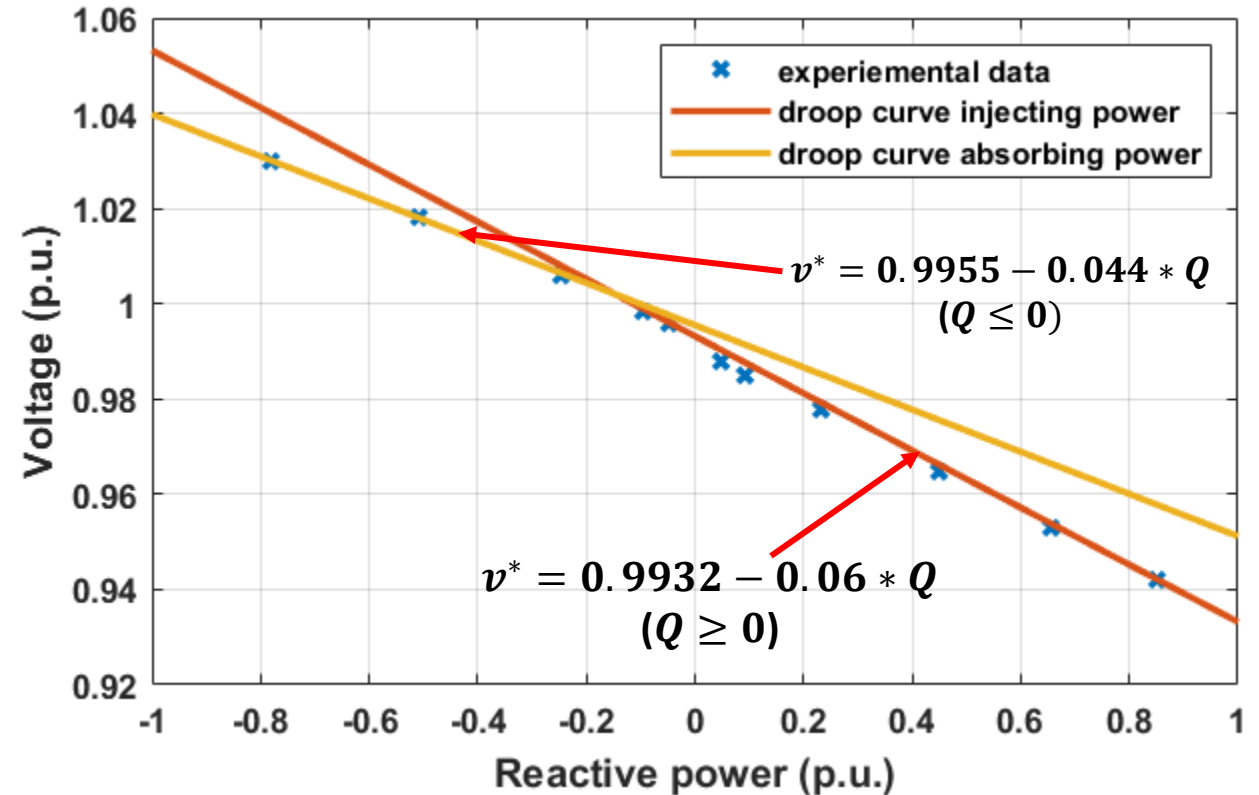


Photo credit: NREL

TESTING CONFIGURATION

- Configure the droop settings:
 - Frequency droop: 0.25%
 - 60 Hz
 - Disable the coupling with reactive current/power (default).
 - Voltage droop: 5%
 - 480 V (1 p.u.)
 - Disable the coupling with active current/power.
- Verify the droop characteristics:
 - Frequency droop matches the testing results.
 - Voltage droop is off due to the transformer.

Voltage droop characterization



TESTING CONFIGURATION

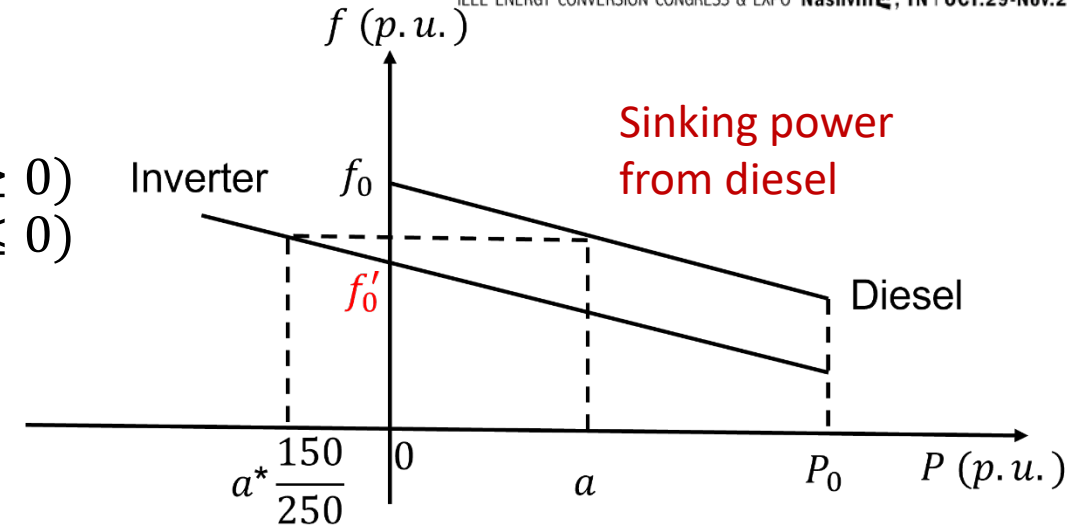
- Stand-alone islanded operation:

Secondary control

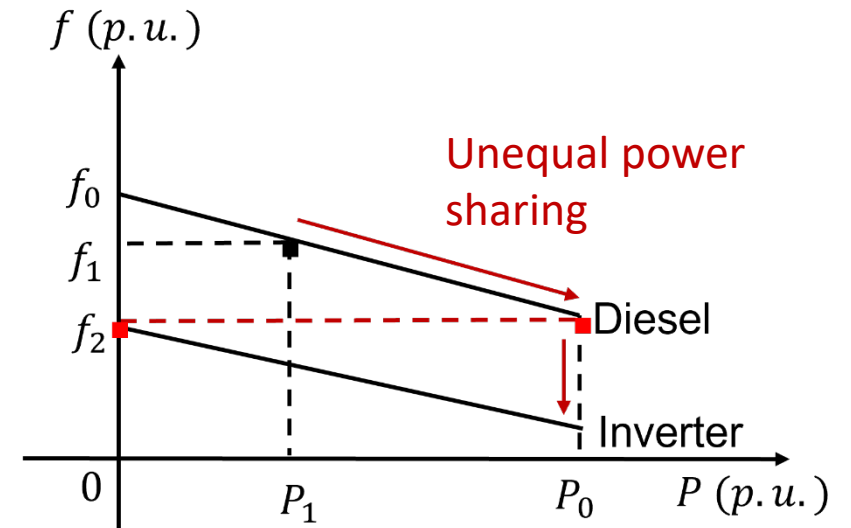
$$\begin{cases} f_0 = 60 + m * 60 * P \\ v_0 = 480 + n * 480 * P + (1 - 0.9932) * 480 \quad (Q \geq 0) \\ v_0 = 480 + n * 480 * P + (1 - 0.9955) * 480 \quad (Q \leq 0) \end{cases}$$

- Heterogeneous islanded operation:

- Diesel droop settings:
 - Frequency: 0.6%, -0.36 Hz representing 60 Hz
 - Voltage: 3.7%. 0% representing 1 p.u.
- Configure the GFM inverter and diesel with the same droop settings:
 - Frequency: 0.6%,
 - Voltage: 6%.
- Equal power sharing (baseline)
- Unequal power sharing.



$$f'_0 = 60 - 60 * 0.006 * (0.25 + 0.15) \quad (a=0.25)$$

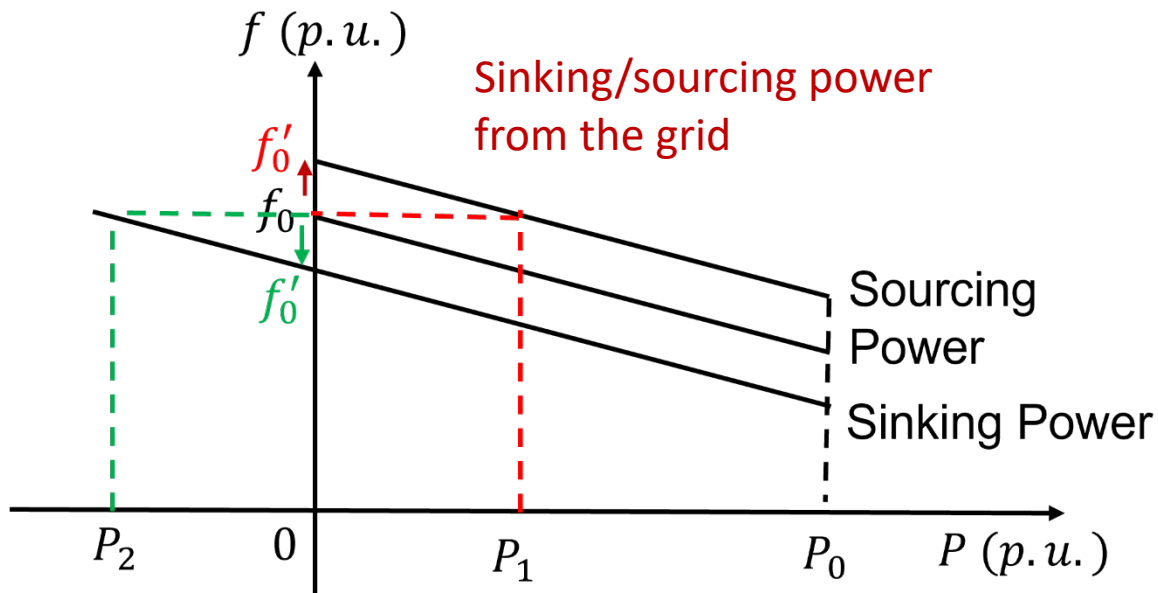


TESTING CONFIGURATION

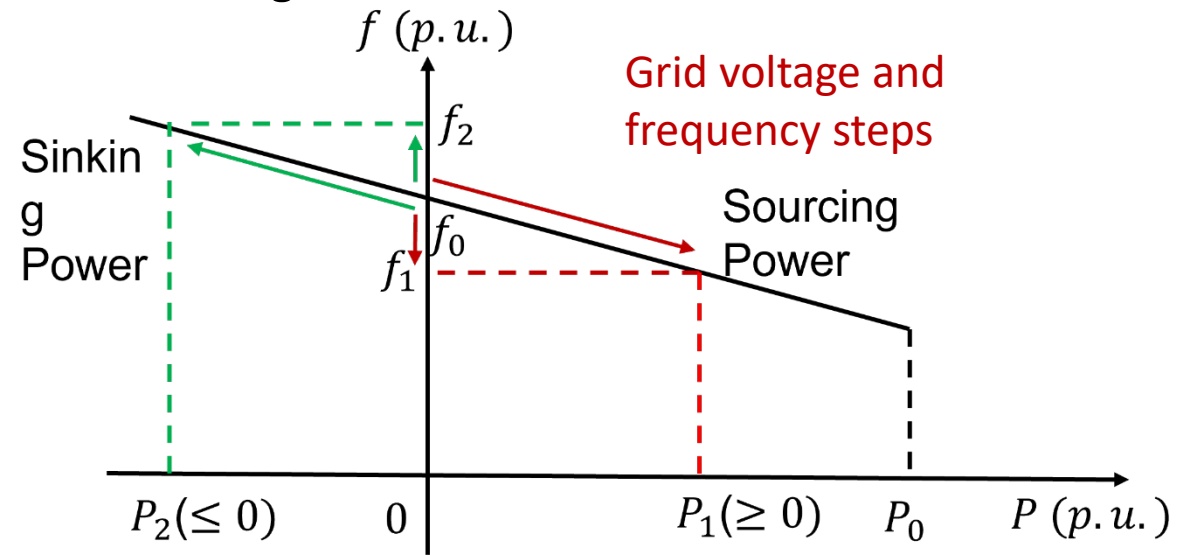
- Grid-connected operation

- For active power, it is a balance game between the grid frequency and the inverter voltage:
 - $f_{grid} = f_{Inv}$, no power flow
 - $f_{grid} > f_{Inv}$, active power flows from the grid to the inverter
 - $f_{grid} < f_{Inv}$, active power flows from the inverter to the grid

- The same for the reactive power output.



$$f'_0 = 60 - 60 * 0.006 * (P_1 - 0) \text{ (e.g., } P_{new} = P_1 \text{ and } P_{old} = 0)$$



$$f_1 = 60 - 60 * 0.006 * (P_1 - 0) \text{ (e.g., } P_{new} = P_1 \text{ and } P_{old} = 0)$$

f_1 and f_2 are grid simulator stepped frequency

TESTING CONFIGURATION

- Transition operation:
 - Key for smooth microgrid transition operation: **Minimize the PCC power flow and maintain the same operating point before and after the transition operation.**

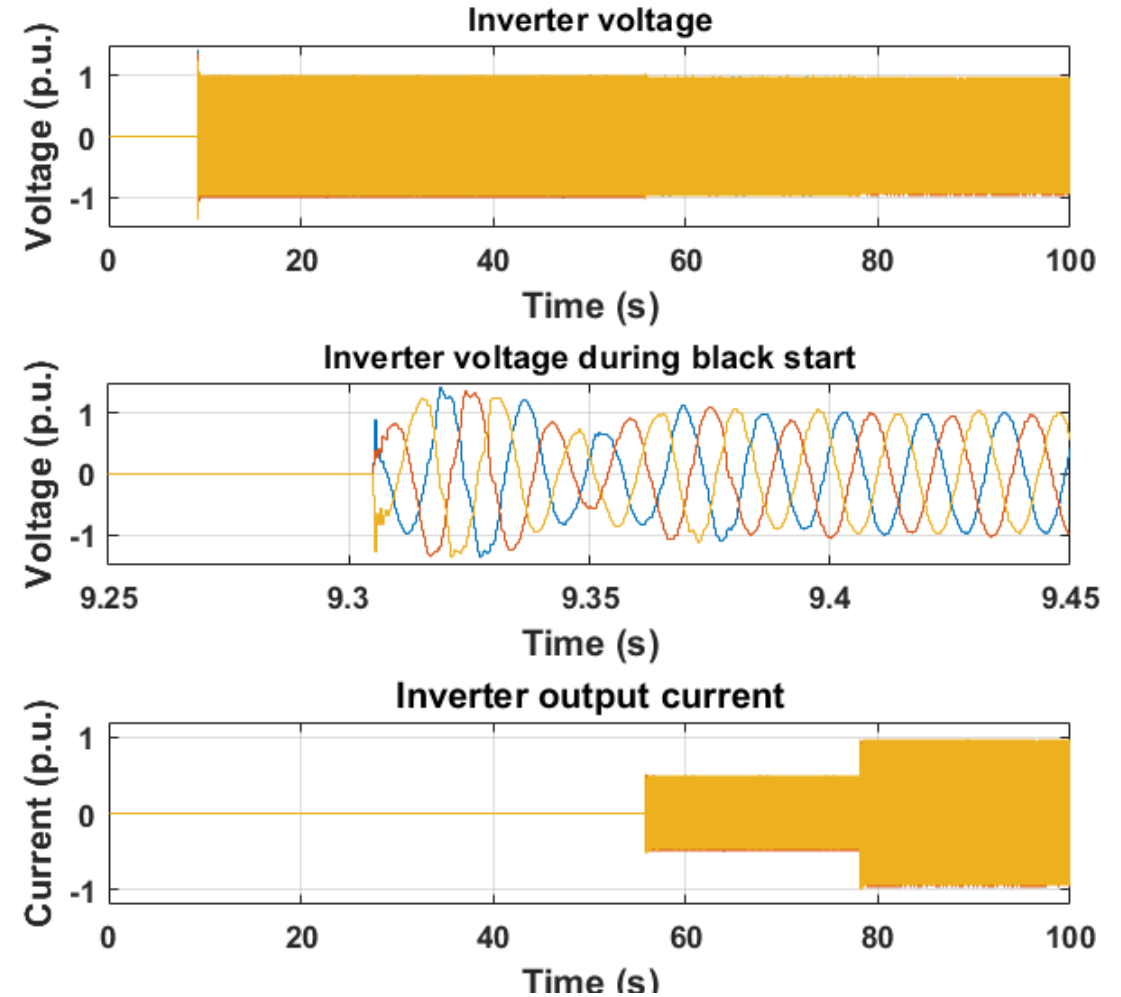
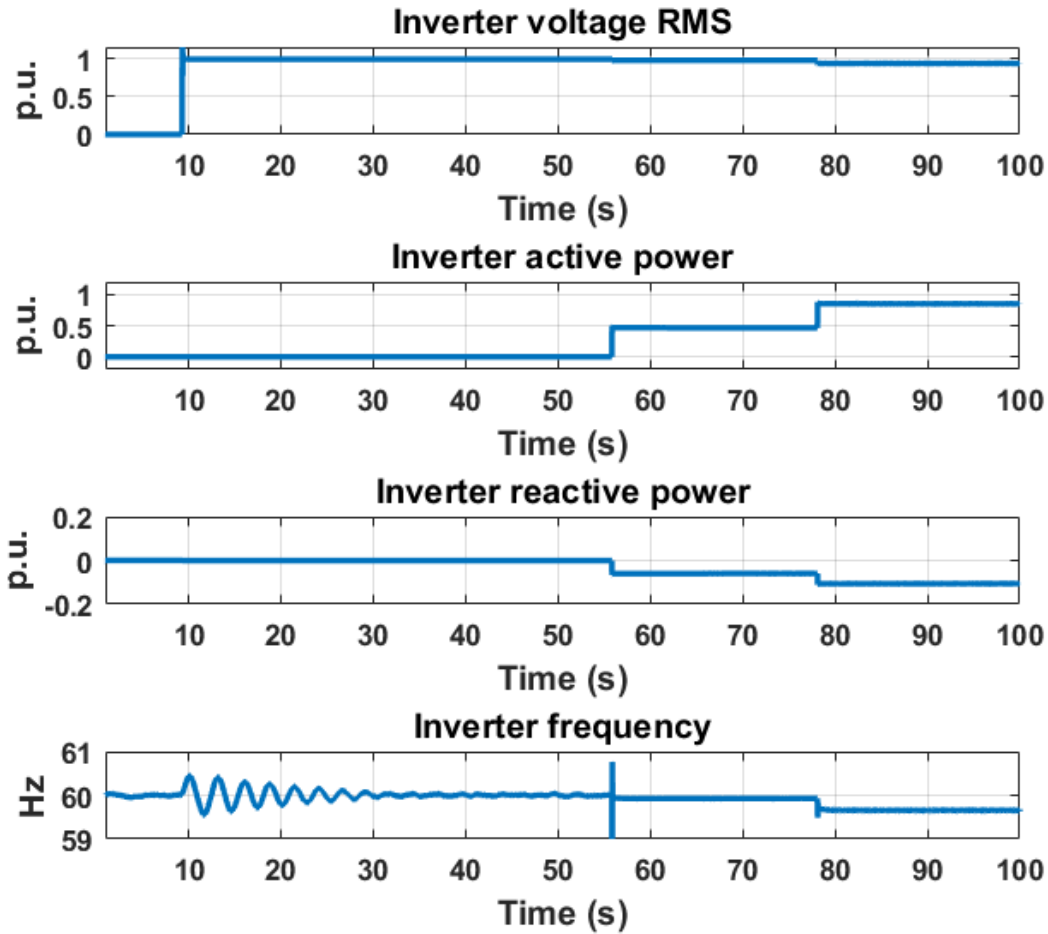
Loading (50%)	Islanded	Synchronization Key strategy: PCC power flow is minimized and inverter maintains the same operating point (v, I, P, Q, f)	Grid-connected	Islanding (same strategy as synchronization operation)
PF=1	Inverter with load	Before CB is closed, shift the frequency droop up by $\Delta f = 0.006 * 0.5 * 60 = 0.18$ Hz.	Inverter supplies all the load	Inverter supplies all the load
PF=0.8 lagging	Inverter with load	Before CB is closed, shift the frequency droop up by $\Delta f = 0.006 * 0.4 * 60 = 0.144 \approx 0.14$ Hz, shift the voltage droop up by $(0.0841 * 0.5 * 0.6 - 0.0119) * 480 = 6.4$ V	Inverter supplies all the load	Inverter supplies all the load
PF=0.8 leading	Inverter with load	Before CB is closed, shift the frequency droop up by $\Delta f = 0.006 * 0.4 * 60 = 0.144 \approx 0.14$ Hz, shift the voltage droop down by $(0.0679 * 0.5 * 0.6 + 0.008) * 480 = 13.6$ V	Inverter supplies all the load	Inverter supplies all the load

EXPERIMENTAL RESULTS—STAND-ALONE

- Balanced load:
 - The inverter can operate within the full spectrum of its active and reactive power.
 - THD of V and I are mostly below 5% except capacitive load (5% and 10%).
 - Inverter voltage drops below 0.95 p.u. at 100% loading.
 - There is a strong coupling between voltage and active power.
- Unbalanced load:
 - Inject negative sequence current.
 - Capable of handling all the unbalanced loading test
 - Voltage imbalance is below 0.25%.
- Sinking power:
 - Able to absorb the excessive active and reactive power from the GFL inverter.
- Load step:
 - Can handle all the load steps.
- Overloading:
 - Can handle all the overloading except PF 0.8 lagging and leading from 1.6 p.u.
 - Duration: 5~9 seconds.

EXPERIMENTAL RESULTS—STAND-ALONE

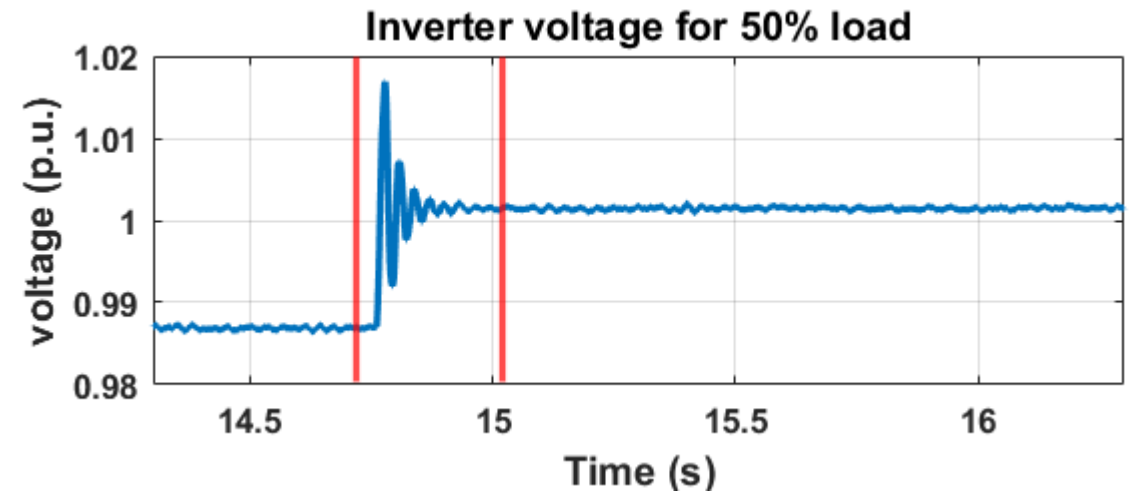
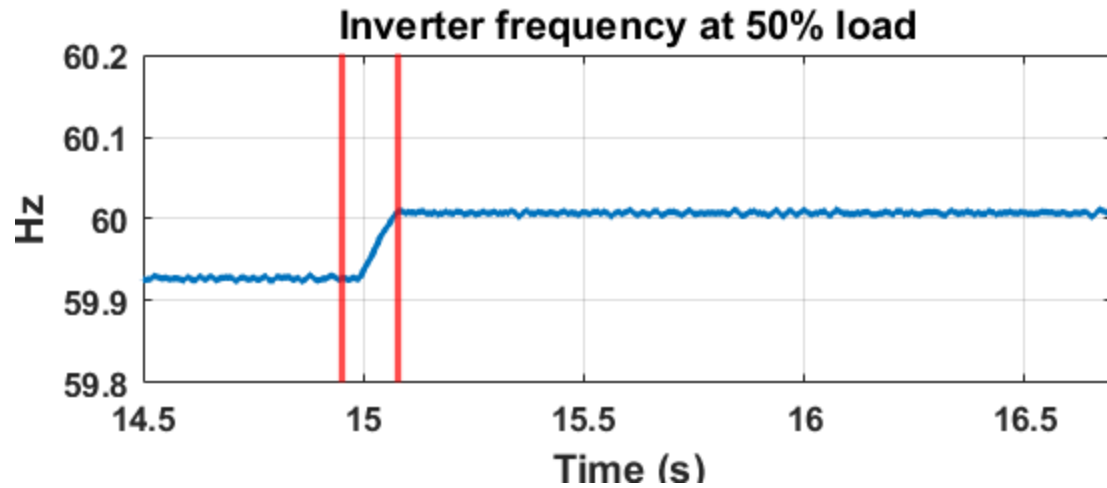
Black start: Energize transformer → 50% load → 100% load.



EXPERIMENTAL RESULTS—STAND-ALONE

Secondary control: 50% PF=1 load applied

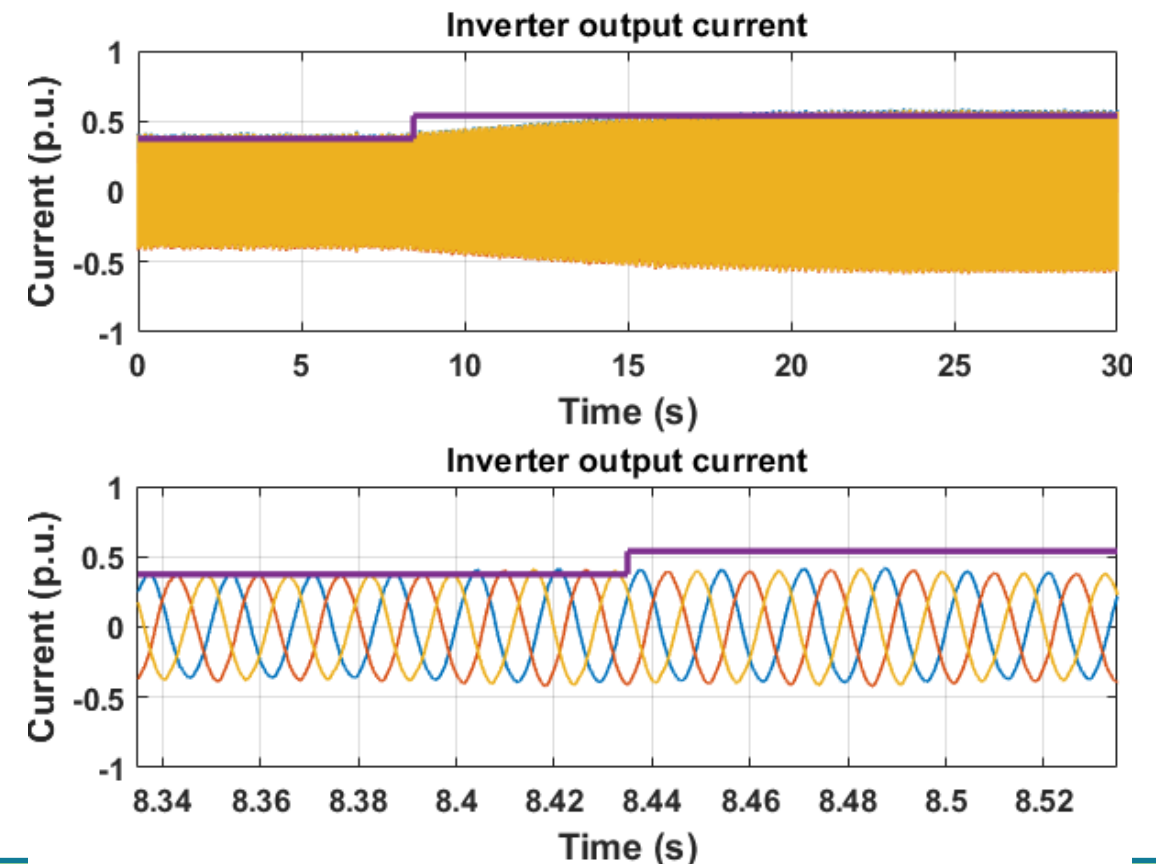
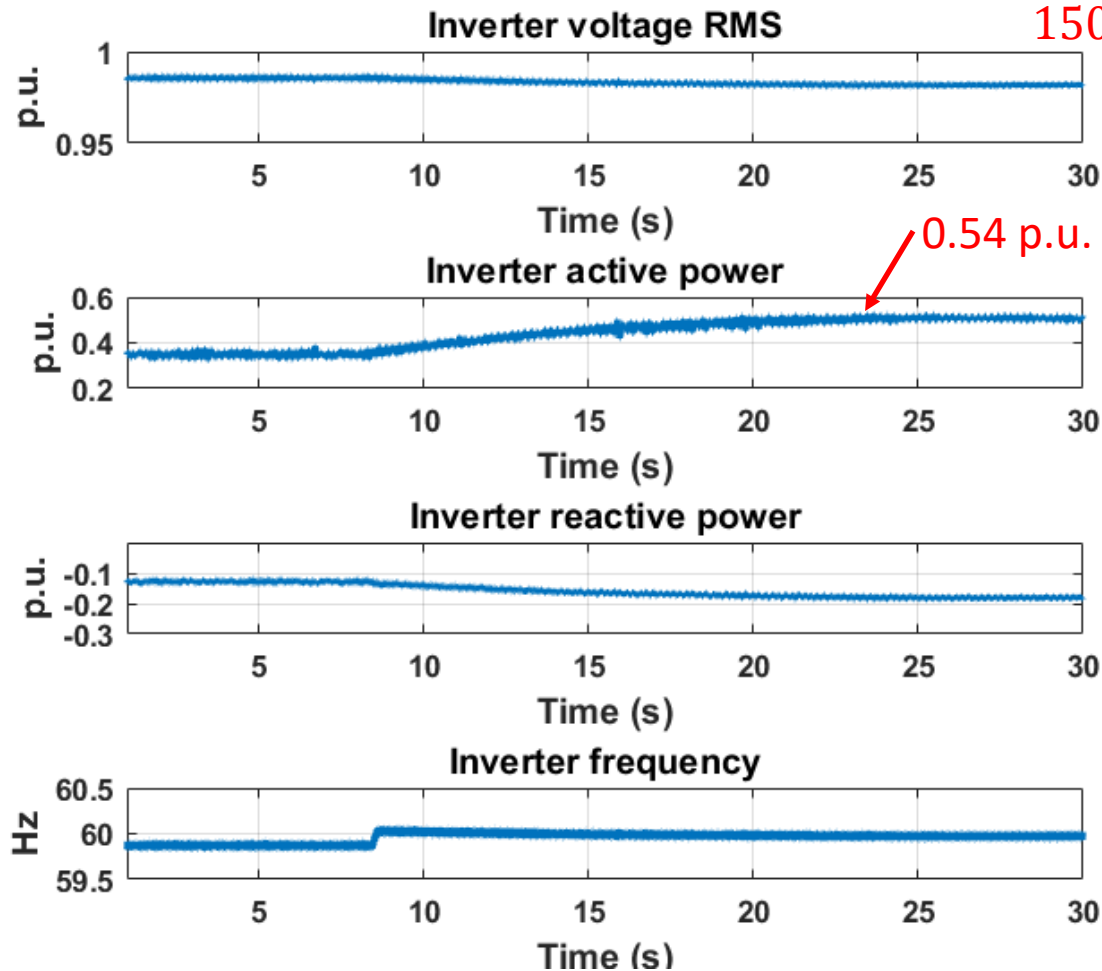
- Frequency: smoothly regulated to the nominal value with 0.25 s
- Voltage: Exhibits oscillations and reaches steady state within 0.5 s.



Unequal power sharing: Start from equal power sharing → take 90% of the load.

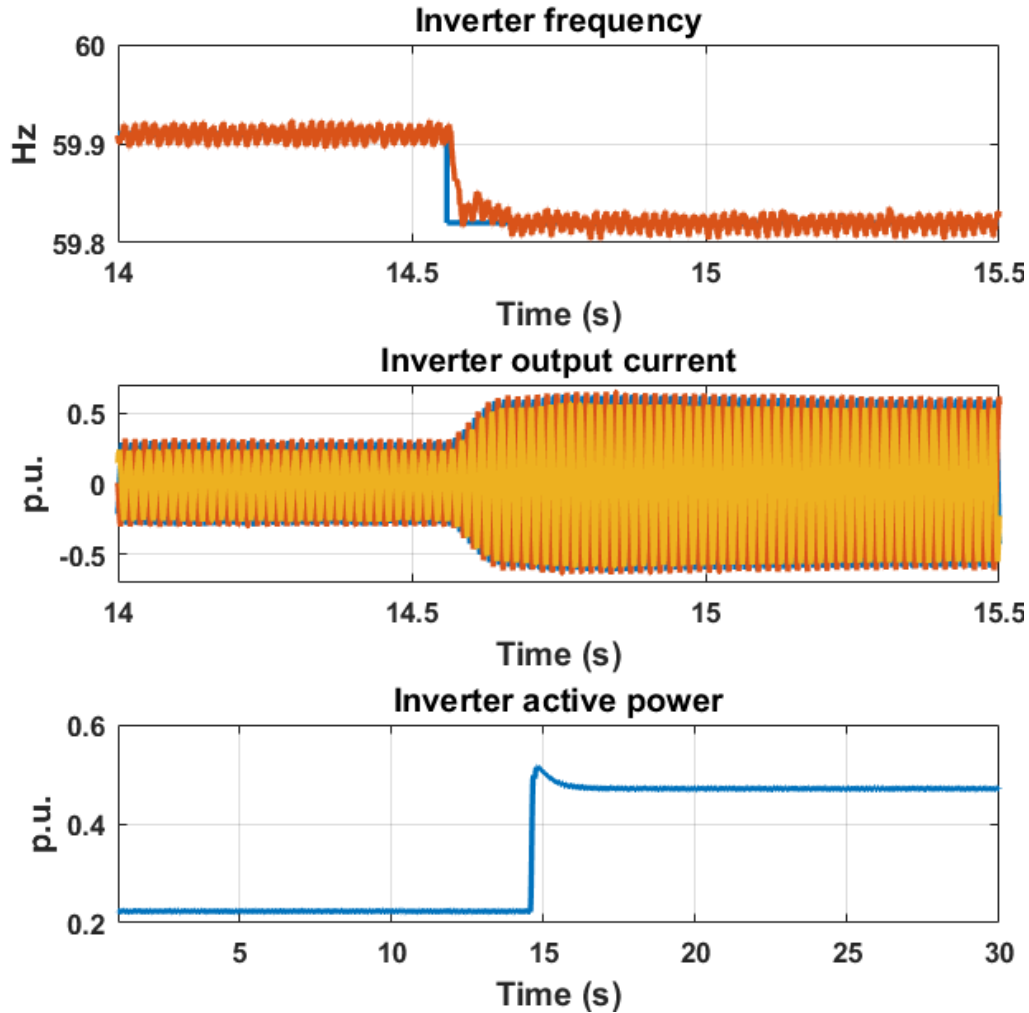
$$\frac{150}{150 + 250} = 37.5\%$$

$$0.9 * \frac{150}{250} = 0.54$$

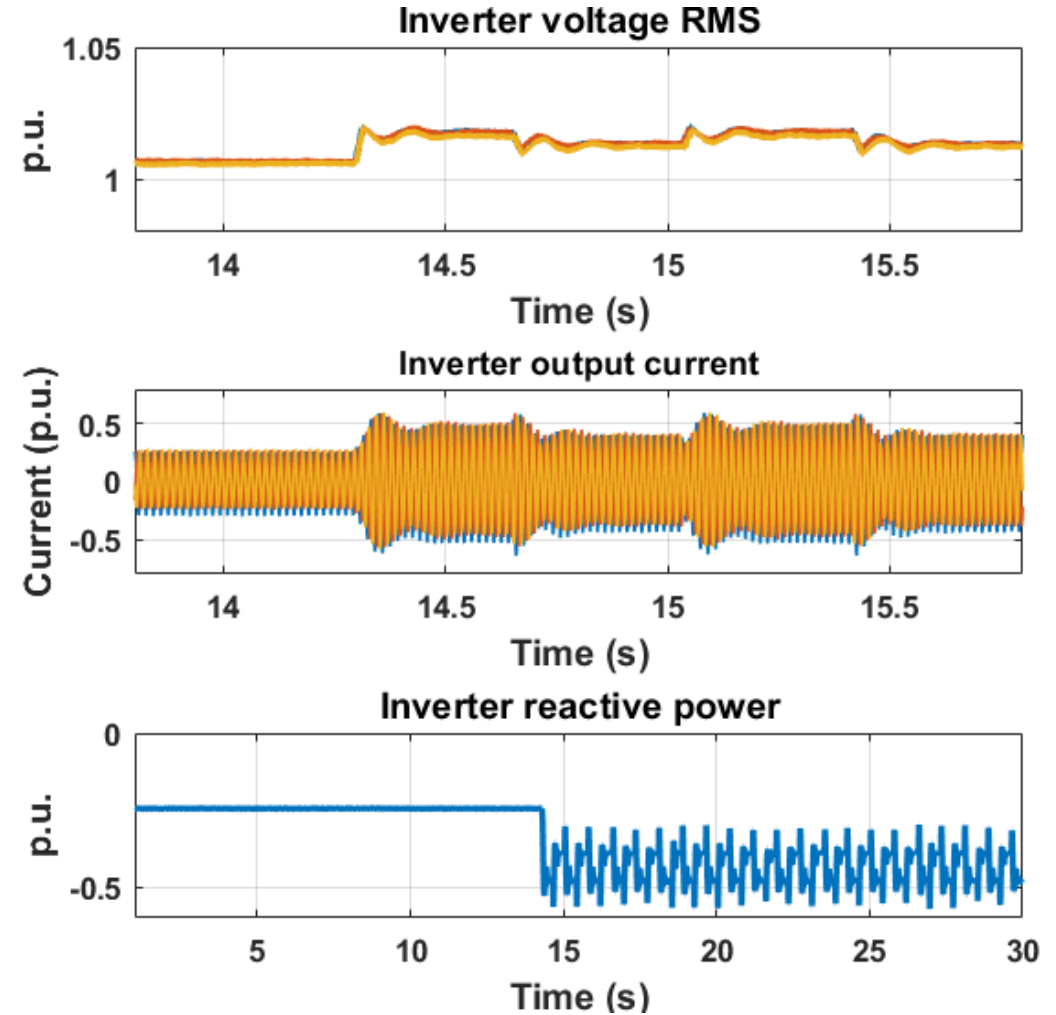


- Sourcing active power:
 - There is noisy current when the frequency droop is not shifted.
 - Inverter outputs the target active power except the 100% (derating effect).
 - Voltage THD is below 0.5% and current THD is high with low power (5% and 10%).
 - No overshoot in the output current.
 - Inverter absorbs reactive power and increases when the loading is increased.
- Sourcing reactive power:
 - Outputs the reactive power slightly lower than expected
 - Voltage THD is below 0.5% and current THD are all above 5%
 - Inverter output current shows overshoots and settles within 1 s .
- Sinking active power:
 - Can complete all the testing
 - Inverter absorbs the target active power
 - No oscillations
 - Inverter absorbs slightly higher power than expected
 - Voltage THD is below 0.5% and current THD is above 5% from 5% to 50%.

Grid simulator step-down frequency



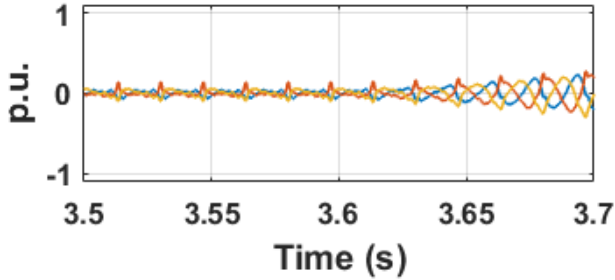
Grid simulator step-up voltage



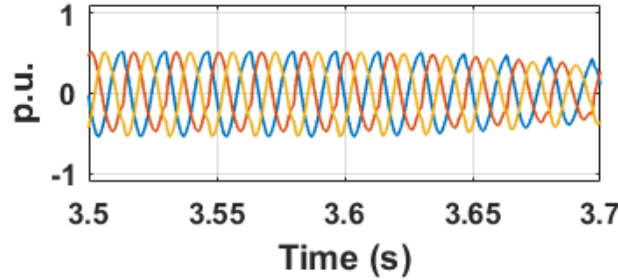
EXPERIMENTAL RESULTS—TRANSITION

OPERATION (PF=1 50% LOAD)

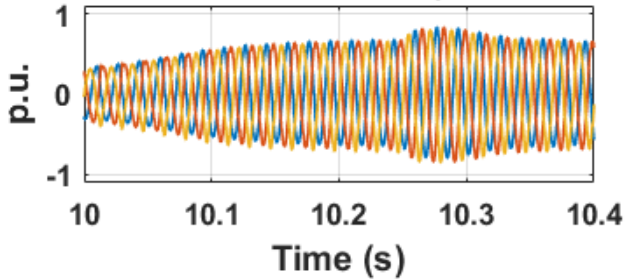
Inverter current during synchronization



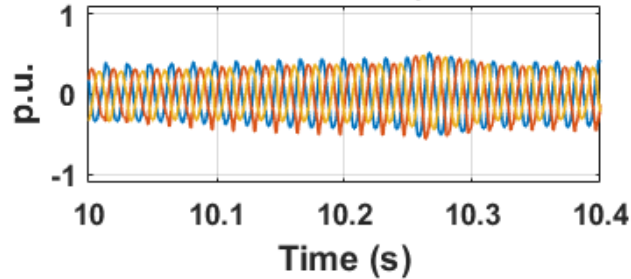
PCC current during synchronization



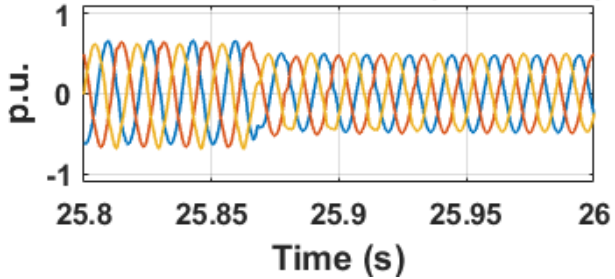
Inverter current during dispatch



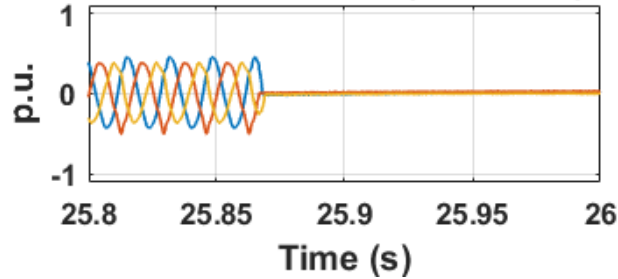
PCC current during dispatch



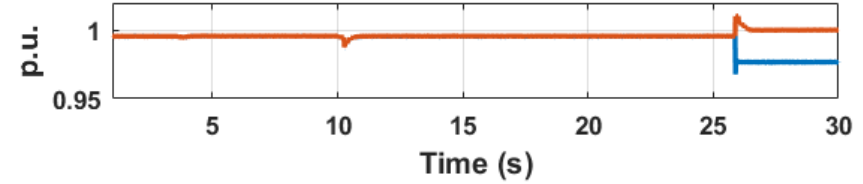
Inverter current during islanding



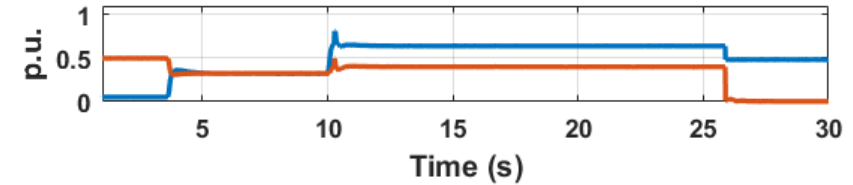
PCC current during islanding



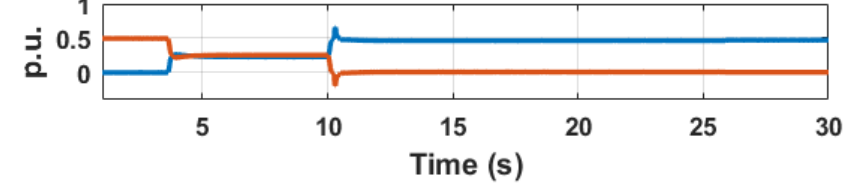
Inverter (blue) and PCC (red) voltage RMS



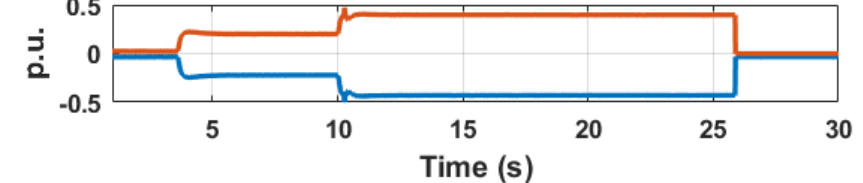
Inverter current and PCC RMS



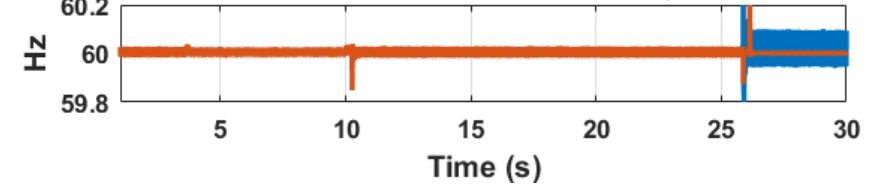
Inverter and PCC active power



Inverter and PCC reactive power



Inverter and PCC frequency



CONCLUSION

- Develop a testing protocol to perform extensive lab testing of GFM inverter.
 - Understand the control functionalities and interoperability.
- The frequency and voltage droop need to be characterized.
- Tuning the droop slope can easily cause stability issues.
- We can perform secondary control and dispatch GFM inverters like GFL inverters through adjusting the droop intercept.
- Reactive power sharing is a problem.
- More studies are needed for grid-connected operation, especially for reactive power dispatch.

KEY FINDING: Interoperability and dispatch of GFM inverters is all about droop!!!

Acknowledgement and Disclaimer

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