

In-line, High-throughput Quality Monitoring for Fuel Cell and Electrolyzer Components based on Transmission and Reflection Imaging

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1 Background and Goals

2 Initial Proof-of-Concept Experiments

- **3** Web-line Experiments
- 4 Image Processing
- **5** Experimental Results
- 6 Conclusions and Future Work

Background and Goals

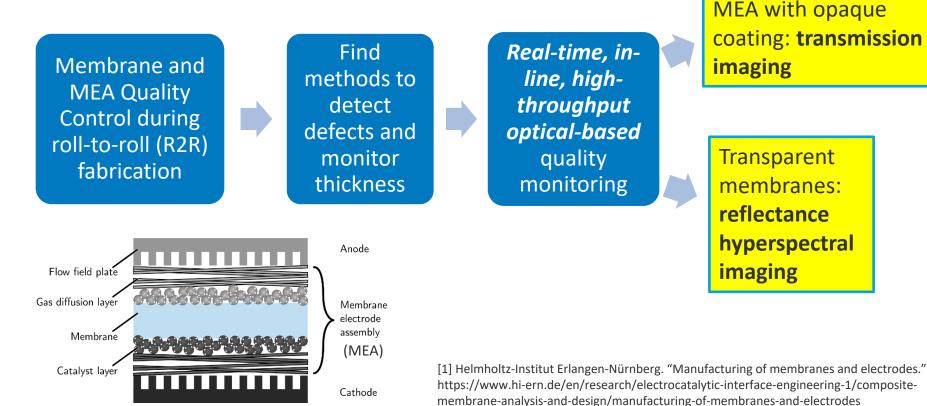


Figure 1. Schematic layout of fuel cell or electrolyzer [1]

NREL | 3

Initial Proof-of-Concept Experiments

MEA with opaque coating: **transmission imaging**

 Initial bench-top static experiment has shown that a reliable transmission signals can be obtained with continuous or pulsed light sources.

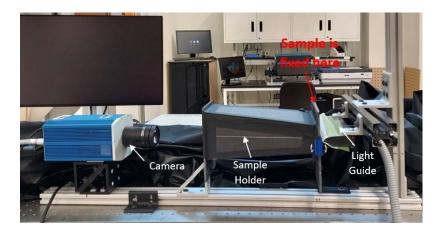


Figure 2. Bench-top transmission setup with continuous light source **with no less than 1s exposure time**

Sample Transmission Image	Light Source Name	Exposure Time (ms)	SNR	Ave Pixel Value
anne an	Halogen light	1000	613	2912
is a constrained with the set $x_{i+1} = x_{i+1}$ and $y_{i+1} = x_{i+1}$, where \mathcal{M}_{i}	Tactical Flashlight	1000	143	1195
	Flashpoint Flashlight	1000	452	3976
	Flashpoint Flashlight	100	1481	4019

Table 1. Comparison of different light sources for an opaque MEA sample



Figure 3. Bench-top transmission setup with pulsed flashlight with much less exposure time(<< 1 s)

Initial Proof-of-Concept Experiments

Transparent membranes: reflectance hyperspectral imaging

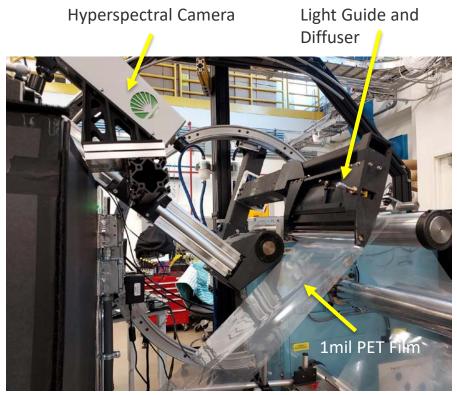
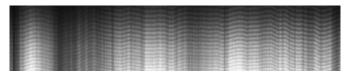
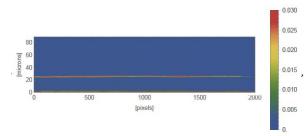


Figure 4. Static HSI imaging setup for 1mil PET film

- Light source: halogen light (used <2% light intensity of an 150W Intralux-dc 1100)
- Frame rate: 100 Hz
- Obtained the following clear fringes:



Thickness results for 1 frame:



| 5

Web-line Experiments

- In roll-to-roll dynamic configuration, the exposure time was set to 50 ms and the frame rate ~1Hz in 3 runs.
- Sample Product Name: Electrolyzer NSTF Catalyst Coated Membrane(Experimental)
- Sample Description: mitigated (black) membrane with two catalyst layers
- Web-line moving speed: 5 ft/min
- Tension of the web-line: 1 Pli(pounds/linear inch)
- Sample was spliced adjacent to PET film and enclosed in transparent plastic bags
- Camera and flashlight were synchronized via a cable/relay connection

MEA with opaque coating: transmission imaging

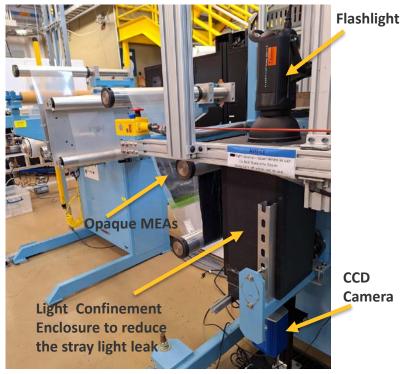
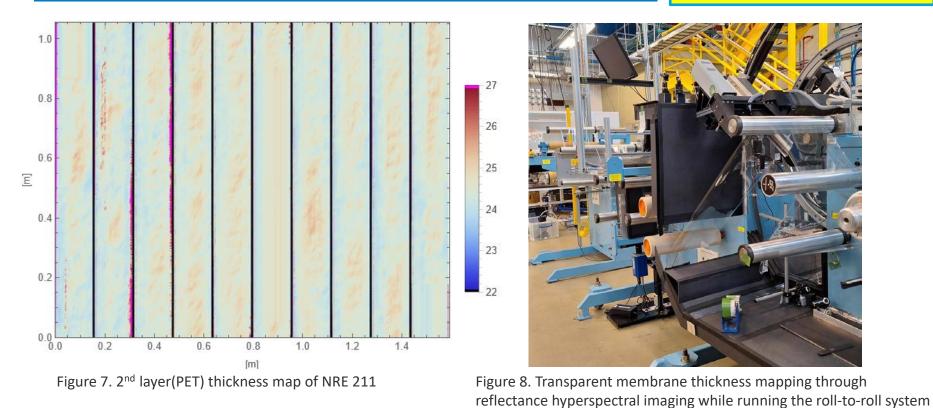


Figure 6. Transmission setup with pulsed flashlight on the moving roll-to-roll system

Web-line Experiments

Transparent membranes: reflectance hyperspectral imaging

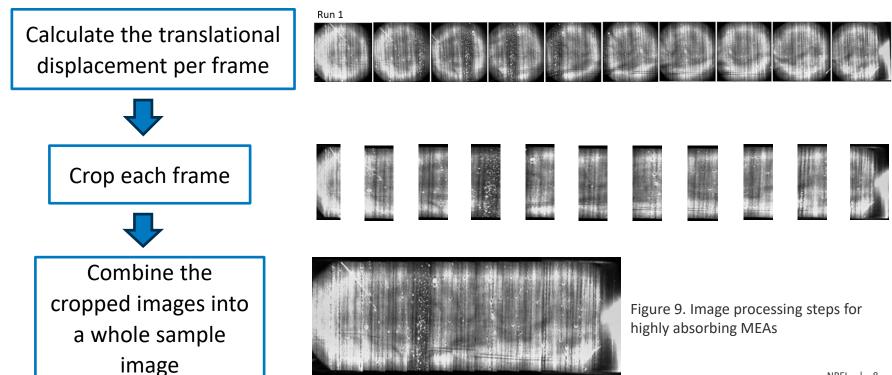


NREL | 7

Image Processing

MEA with opaque coating: transmission imaging

Batch Image Processing Routine written in Python Jupyter Notebook



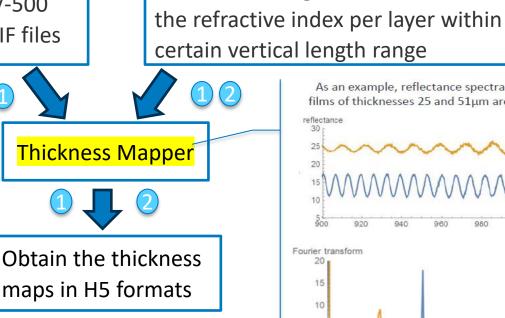


Transparent membranes: reflectance hyperspectral imaging

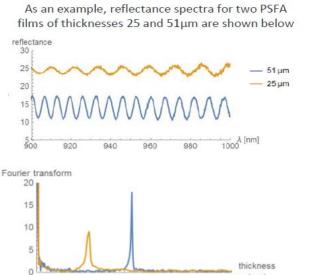
Convert raw MSV-500 camera data to TIF files

Offline Mode

Online Mode



[2] Rupnowski, P. (2022). In-Line Membrane Thickness Mapping with Real-Time Data Processing (No. NREL/PO-5900-82774). National Renewable Energy Lab.(NREL), Golden, CO (United States).



60

80

100 [µm]

Generate Configuration files to show

0

20

40

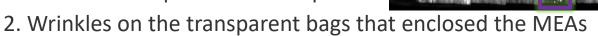
[2]

Experimental Results

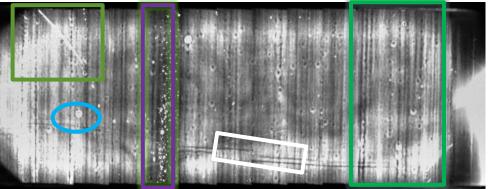
MEA with opaque coating: transmission imaging

Features are detected during web-line scanning:

- 1. Non-uniformity of the opaque MEAs
 - white diagonal line
- circular white spots
- cross-web bands
- dark CW stripe with white speckles



- 3. Non-uniformity of the light
- 2 and 3 can be eliminated or corrected for
- We do not know which layer is nonuniform (Pt and Ir could be distinguished using XRF or through Reflectance imaging)
- Correlation between T variation and loading variation is not established here.



Experimental Results

Transparent membranes: reflectance hyperspectral imaging

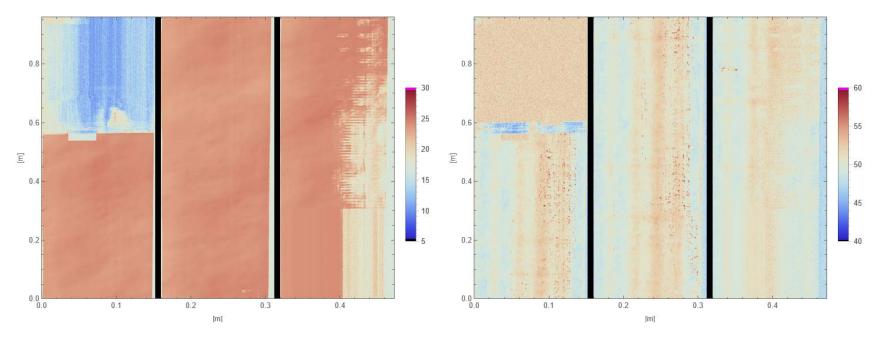


Figure 10. NRE 212 Layer 1(PET) Thickness Map

Figure 11. NRE 212 Layer 2(Nafion) Thickness Map

Conclusions and Future Work

MEA with opaque coating: transmission imaging

- Initial bench-top static experiment proves the concepts of performing transmission imaging of highly absorbing MEAs.
- The transmission imaging in a moving roll-to-roll environment showed a strong transmission signal, demonstrating a potentially viable pathway for real-time, in-line, high-throughput dynamic optical transmission imaging for uniformity/defects testing of the opaque MEAs and their components.
- > Future Work:
- Light uniformity correction
- Expand width of the FOV
- Develop system for 50ft/min
- Synchronize web-line motion with camera/flashlight to obtain good repeatability with identical phase of each run

Conclusions and Future Work

Transparent membranes: reflectance hyperspectral imaging

- Initial static experiment proves the concepts of performing reflectance hyperspectral imaging of transparent membranes.
- The hyperspectral imaging in a moving roll-to-roll environment showed clear fringes, demonstrating a potentially viable pathway for real-time, in-line, high-throughput dynamic optical imaging for membrane thickness monitoring in mass production.
- > Future Work:
- Increase the thickness detection accuracy for multi-layer membranes
- Increase the thickness detection accuracy at the border of two adjacent materials
- Add the function of the relative position detection of each layer
- Tune the system to accommodate higher web-line speed
- Synchronize the web-line motion with the image acquisition

Thank you!

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