

Multi Rotor  
2024



# MRS Modelling in OpenFAST

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National Renewable Energy Laboratory

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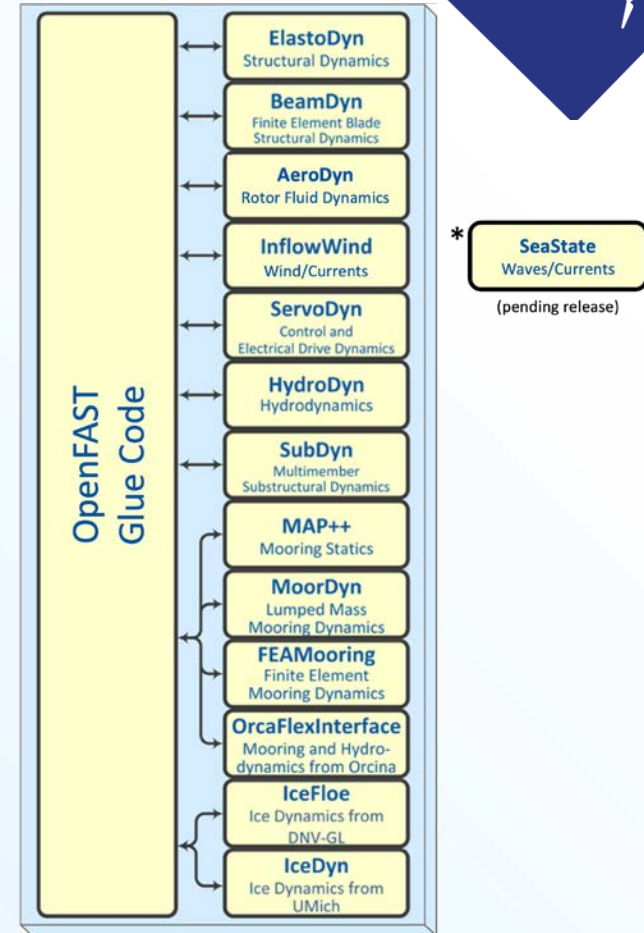


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# OpenFAST summary

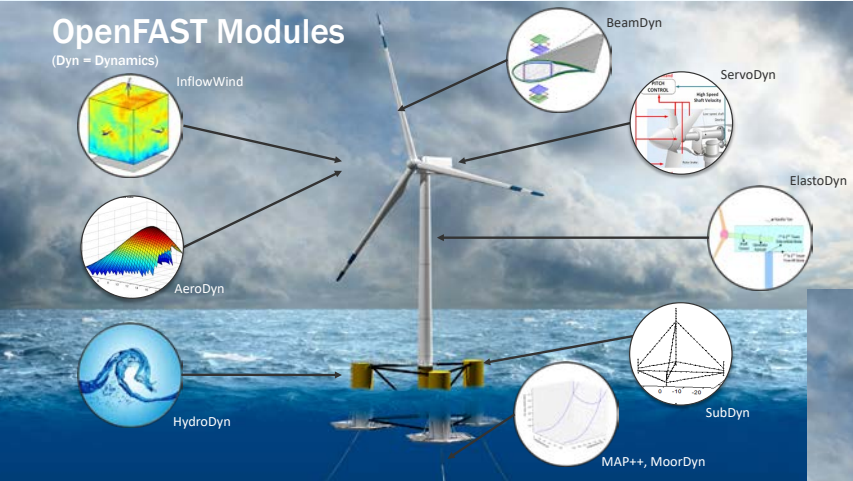
## Capabilities

- Models fixed and floating wind and marine turbines
- Computes nonlinear dynamics in the time domain
- Linearizes nonlinear equations and exports state-space models
- Glue code couples independent modules
  - Enables data encapsulation for distinct physics and/or components
  - Glue code can run more than one instance of a module
- Supports substructure flexibility for multi-member support structures
- Tight coupling between structural modules

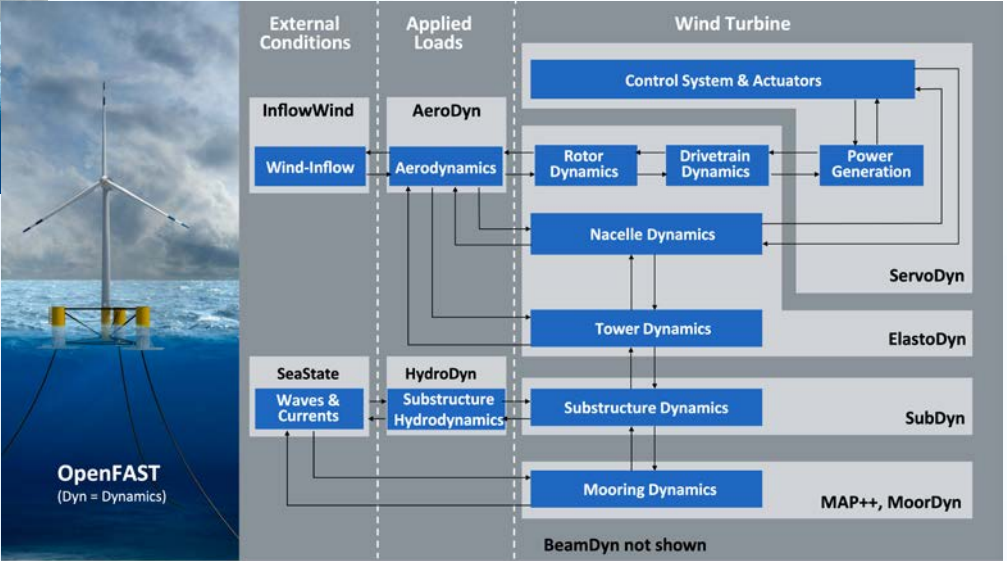


OpenFAST glue code and its modules. Image by Jason Jonkman, NREL

# OpenFAST for wind turbines

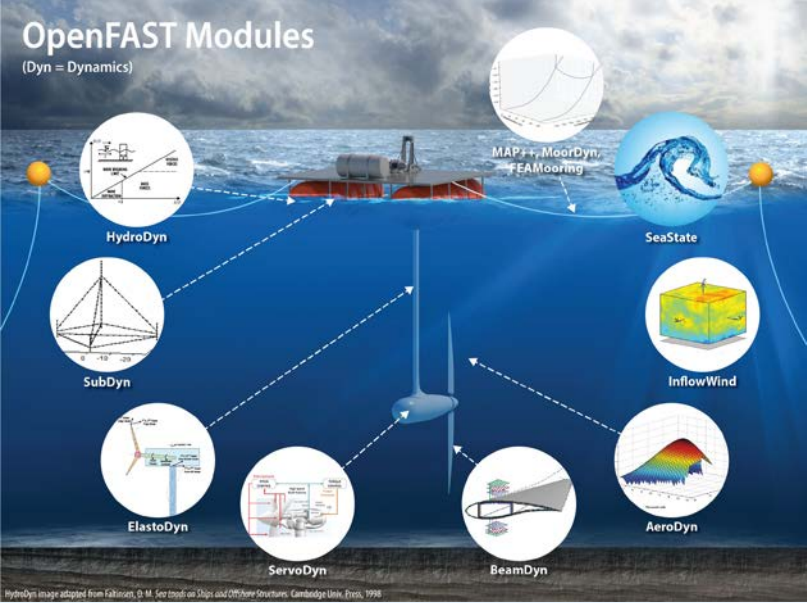


OpenFAST modules for a floating offshore wind turbine.  
Image by NREL Communications

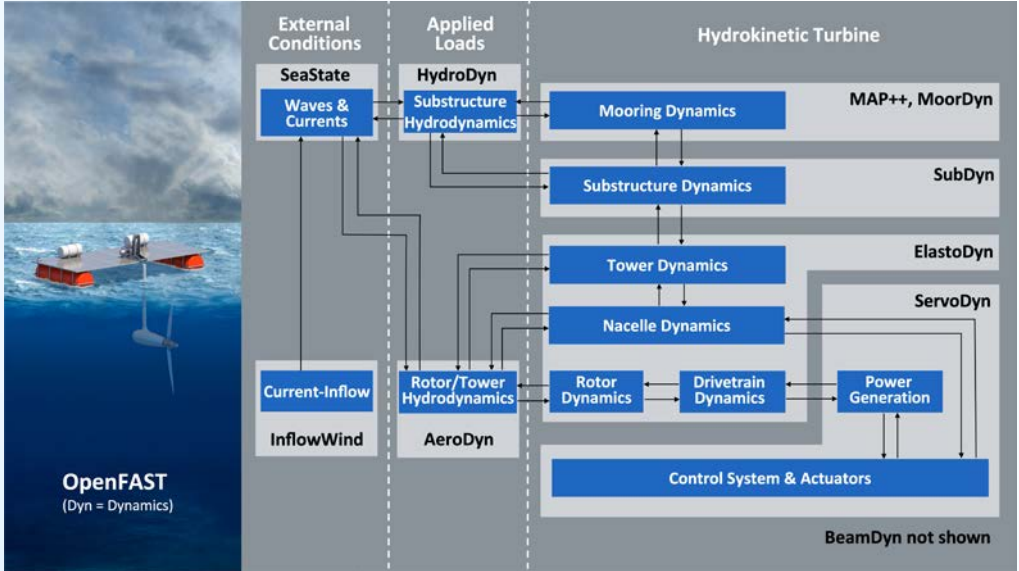


OpenFAST module coupling for a floating offshore wind turbine. Image by NREL Communications

# OpenFAST for marine turbines



OpenFAST modules for a floating marine turbine.  
Image by NREL Communications

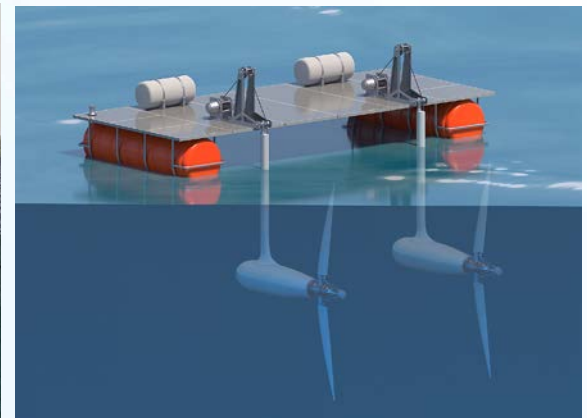
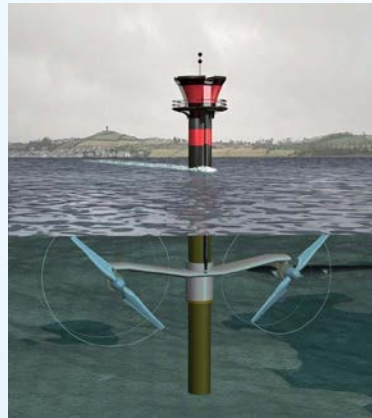


OpenFAST module coupling for a floating marine turbine. Image by NREL Communications

# OpenFAST for multi-rotors

## Objective

- Simulate coupled aero-hydro-servo-elastic dynamics of multi-rotor systems
  - Land-based, fixed-bottom, and floating offshore wind turbines
  - Fixed and floating marine turbines
- Allow nonlinear time domain simulations and full-system linearization



Example multi-rotor systems (from left to right: Vestas, Nezy<sup>2</sup>, SeaGen, MEGALODON)

# OpenFAST for multi-rotors

## Existing capabilities

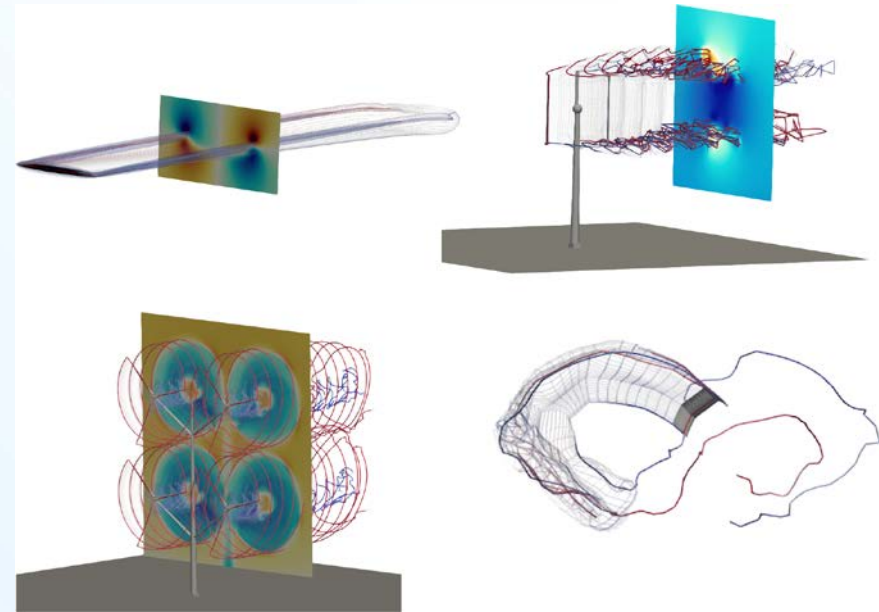
- AeroDyn driver can run multiple rotors

## Original AeroDyn driver

- Simulation of horizontal-axis turbines only
- Fixed nacelle position
- Power-law shear profile inflow

## Updated AeroDyn driver

- Arbitrary collections of wings, rotors, and towers
- (including multiple rotors)
- Arbitrary rigid-body motions of lifting surfaces
- Aerodynamic interactions using free vortex wake model (OLAF)

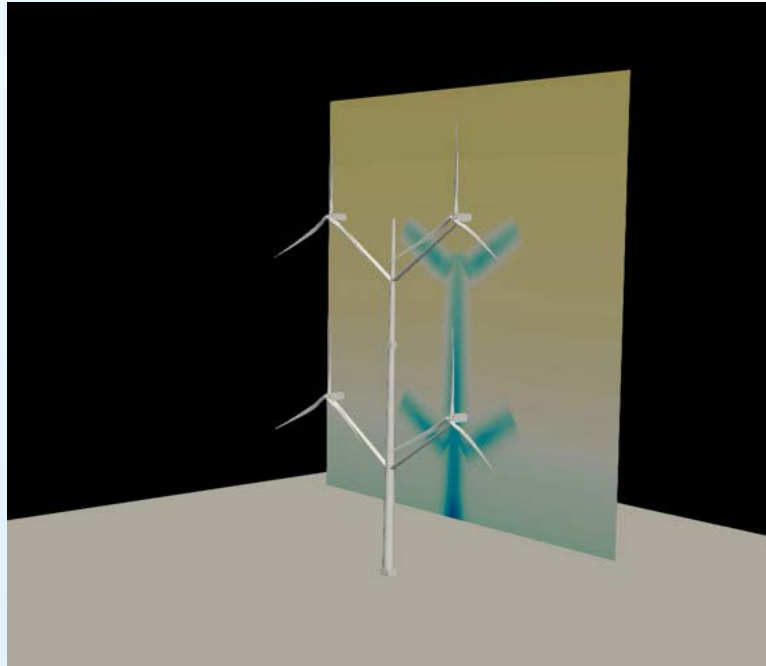


Examples of wind energy concepts to which the AeroDyn driver may be applied: (clockwise from top left) elliptical wing, VAWT, kites, and multi-rotor systems.

Illustration by Emmanuel Branlard

# OpenFAST for multi-rotors

## Existing capabilities



Quad-rotor horizontal-axis wind turbine (HAWT) simulated in OLAF.

*Illustration by Emmanuel Branlard*

# OpenFAST for multi-rotors

## Under development

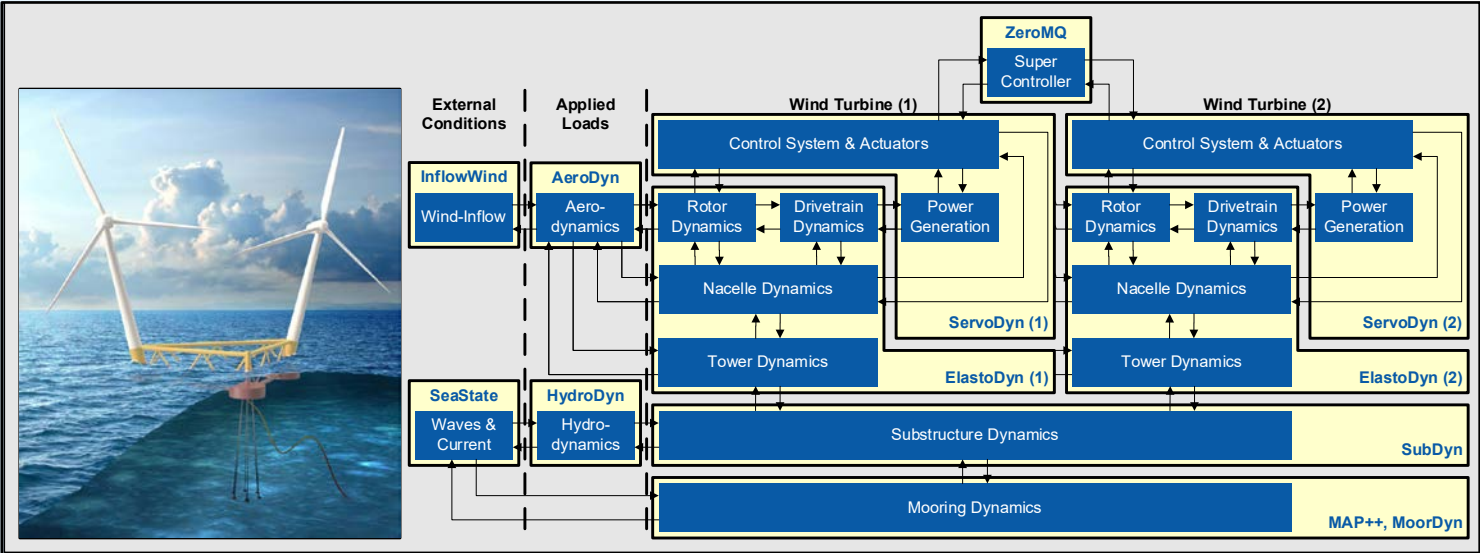
- Define the number of turbines  $N$  and their origins at the glue-code level
- One rotor, drivetrain, nacelle, and optional tower per turbine
- $N$  instances of ElastoDyn model the rotor, drivetrain, nacelle, and tower structural dynamics (one instance per turbine)
- $N$  instances of ServoDyn model the turbine control and electrical drive dynamics (one instance per turbine)
- Each turbine has its own degrees of freedom and configuration
- Allow multiple interface joints in SubDyn
- Develop a system-level super controller to allow coordinated control
- Multi-rotor functionalities in AeroDyn coupled to other modules

## Distinction from previous work

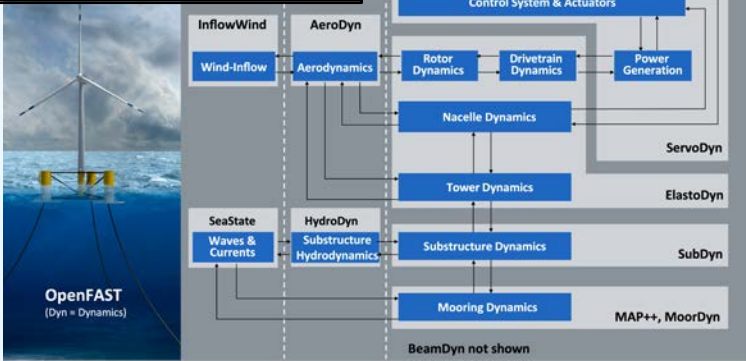
- Modelling of floater hydro-elasticity, which may be important for large floaters supporting multiple turbines



# OpenFAST for multi-rotors

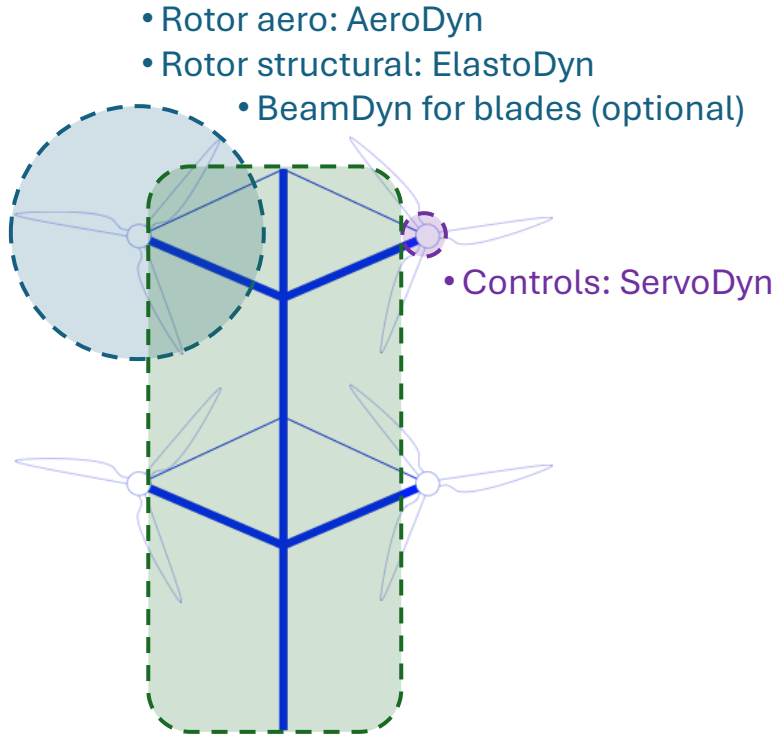
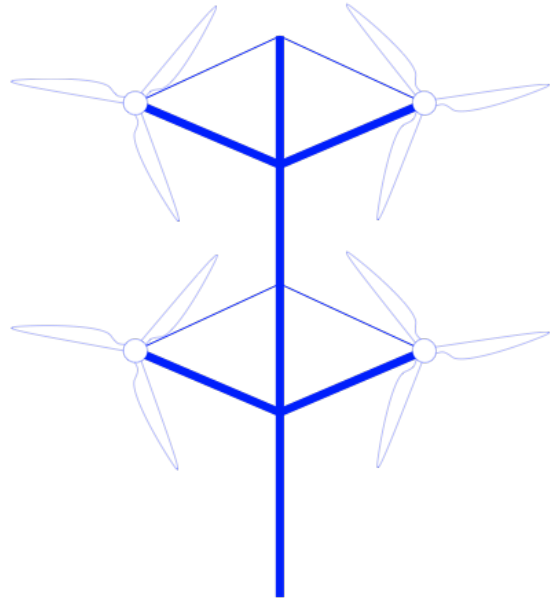


Partitioning of physics into OpenFAST modules for multi-rotor systems (shown with the Hexicon TwinWind concept). Illustration by Jason Jonkman, NREL



# OpenFAST for multi-rotors

## Multi-rotor land-based wind turbine



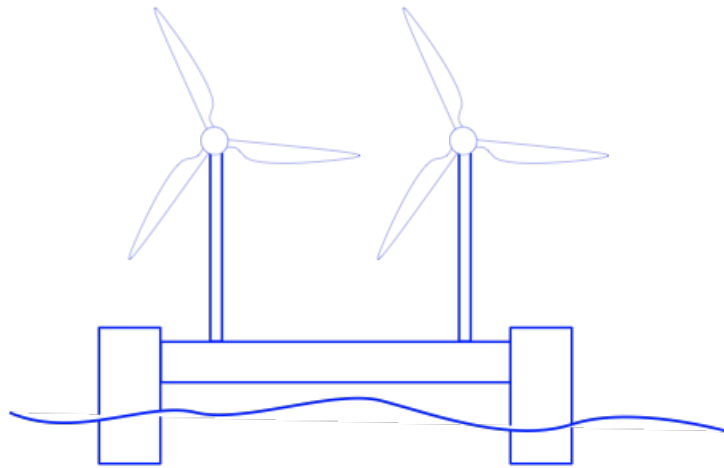
- Rotor aero: AeroDyn
- Rotor structural: ElastoDyn
- BeamDyn for blades (optional)

• Controls: ServoDyn

- Support structure aero: N/A
- Support structure structural: SubDyn

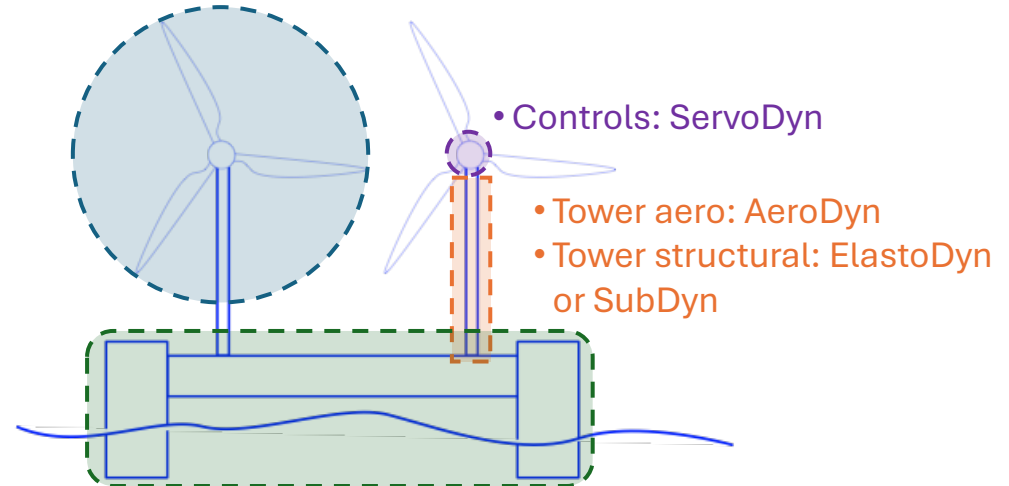
# OpenFAST for multi-rotors

## Multi-rotor floating offshore wind turbine



Multi-rotor wind turbine concept. Illustration by Derek Slaughter, NREL

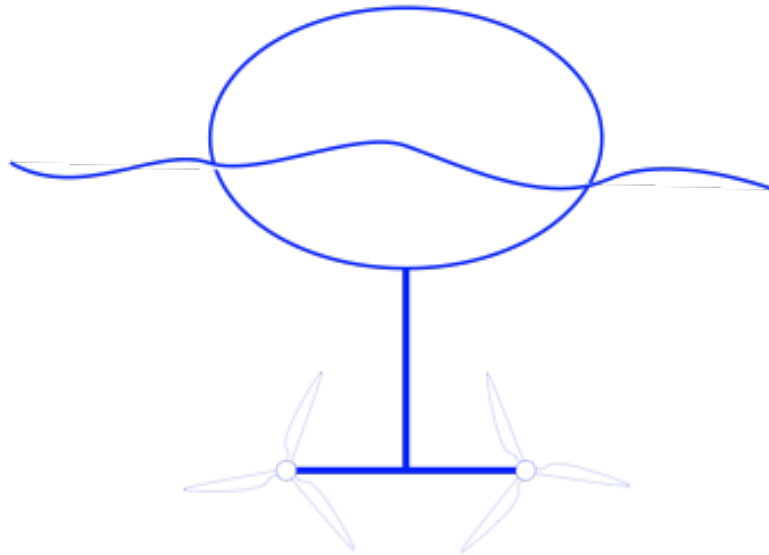
- Rotor aero: AeroDyn
- Rotor structural: ElastoDyn
- BeamDyn for blades (optional)



- Controls: ServoDyn
- Tower aero: AeroDyn
- Tower structural: ElastoDyn or SubDyn
- Platform hydro: HydroDyn
- Platform structural: SubDyn

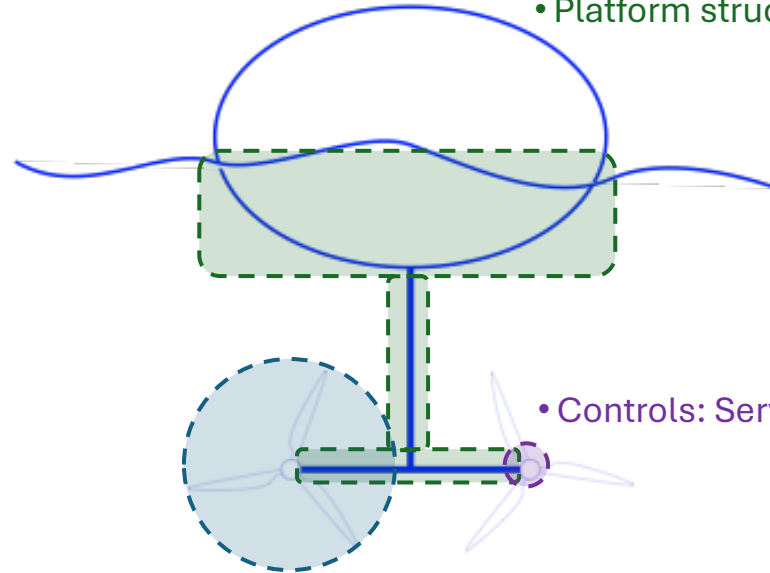
# OpenFAST for multi-rotors

## Multi-rotor floating marine turbine



Multi-rotor marine turbine concept. *Illustration by Derek Slaughter, NREL*

- Platform aero: N/A
- Platform hydro: HydroDyn
- Platform structural: SubDyn



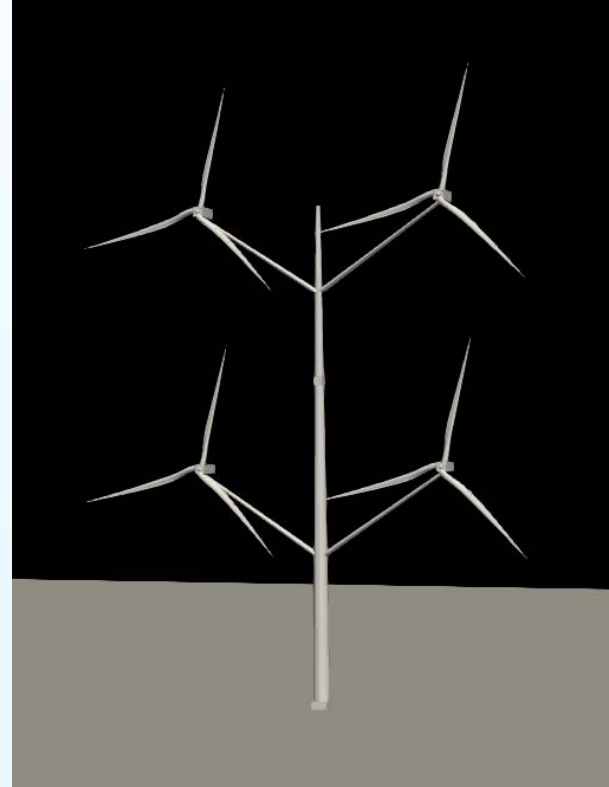
- Controls: ServoDyn

- Rotor aero: AeroDyn
- Rotor structural: ElastoDyn
- BeamDyn for blades (optional)

# Summary

## Conclusions

- OpenFAST can model aero-hydro-servo-elastic dynamics of individual wind and marine turbines
- OpenFAST is being modified to enable coupled simulation of systems with N turbines on a single platform
- Support structure flexibility will enable loads coupling between turbines
- Super controller will allow coordinated control



Quad-rotor HAWT. Illustration by Emmanuel Branlard

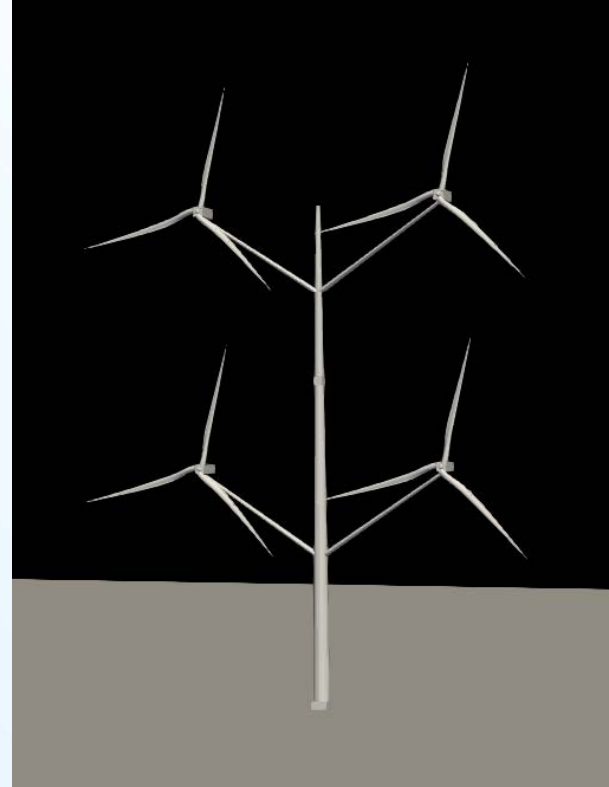
# Summary

## Timeline

- Next update at NAWEA conference in October by Jason Jonkman
- Tentative release at the end of 2024

## Potential future work

- Aerodynamic loading of multi-member support structures
- Vertical-axis turbines
- Yaw control of a superstructure holding multiple rotors
- FAST.Farm for multi-rotor systems



Quad-rotor HAWT. Illustration by Emmanuel Branlard

# Acknowledgements

- U.S. Department of Energy Water Power Technologies Office
- U.S. Department of Energy Wind Energy Technologies Office
- U.S. Department of Energy Advanced Research Projects Agency – Energy
- Jason Jonkman, Derek Slaughter, Andy Platt

<https://github.com/OpenFAST/openfast/tree/main>

<https://openfast.readthedocs.io/en/main/>

NREL team encourages and supports community code contributions

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