

Spectral Analysis of Regular Material Point Method and its Application to Study High Pressure Reverse Osmosis Membrane Compaction and Embossing

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Date: 5th September 2024

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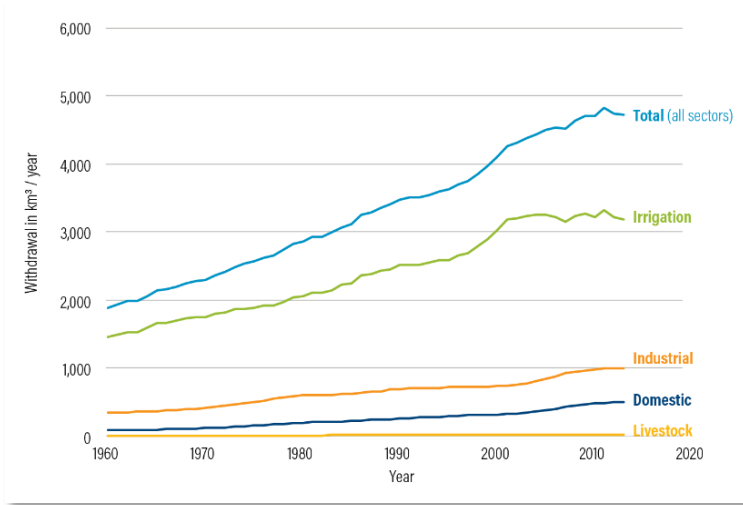
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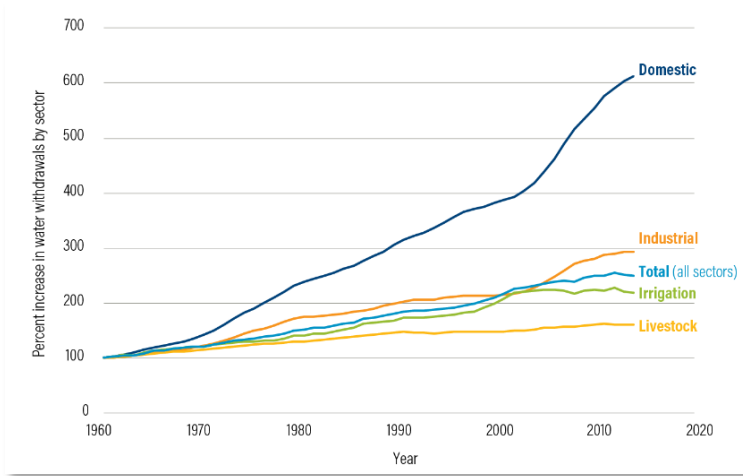
- Introduction and background on NAWI UHPRO project
- Analysis of regular material point method
- Application of MPM to UHPRO membrane compaction problem
- Conclusions & Perspectives

Introduction

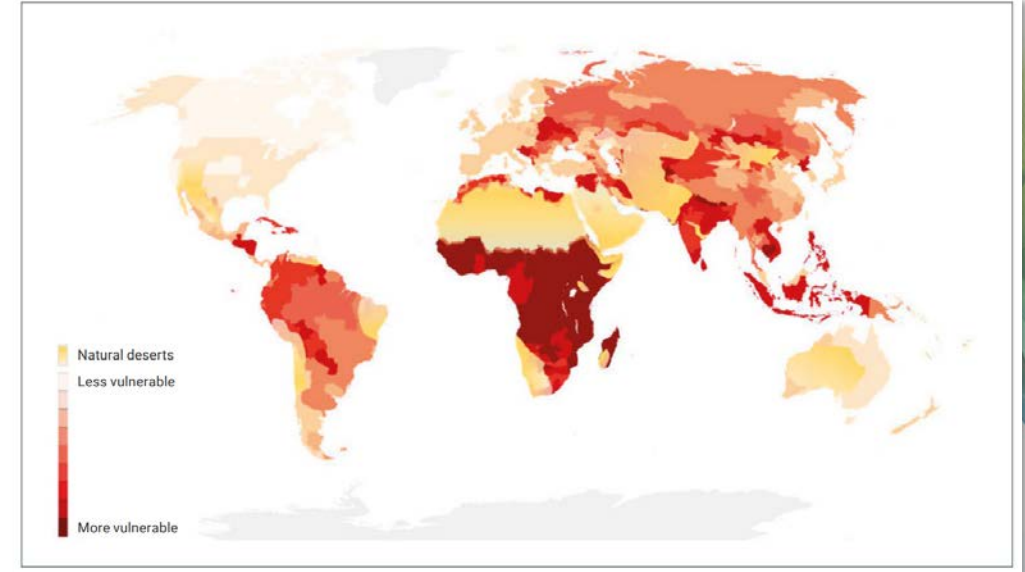
Introduction – World Water Shortage



Water withdrawals in km³/year¹



Percentage water withdrawals increase over time¹

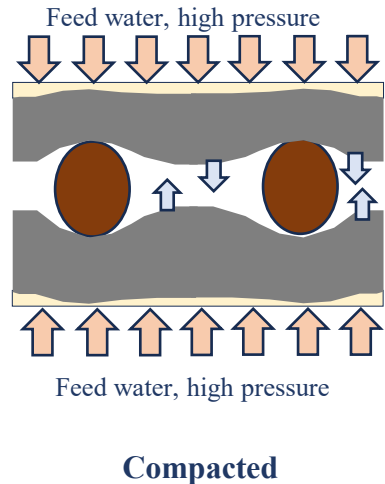
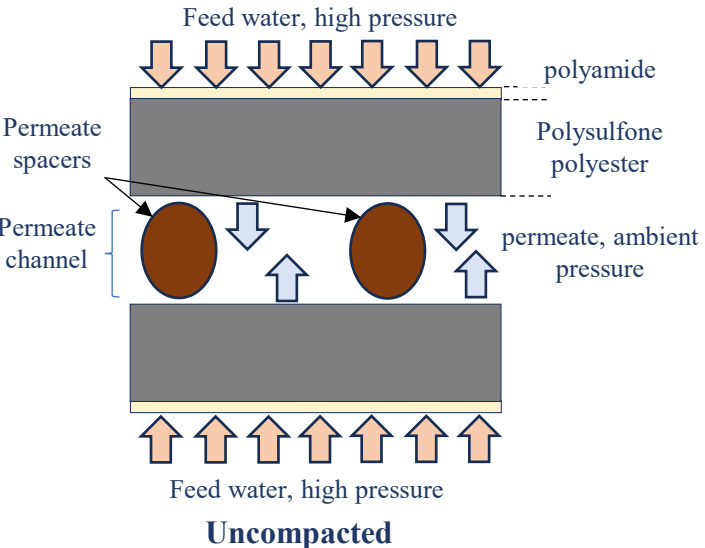


Drought vulnerability index, 2022²

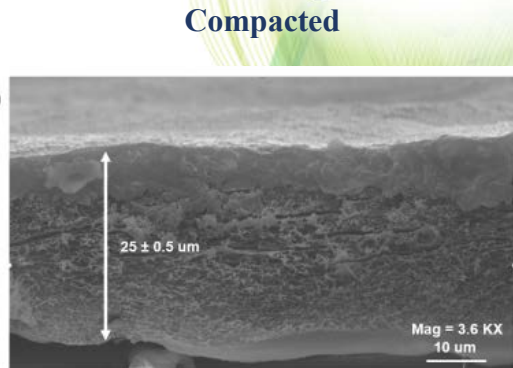
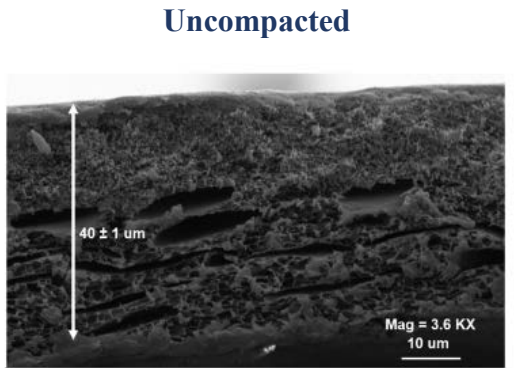
- 2.2 billion people across the world live in regions of water scarcity
- 2 million tons of industrial, sewage and agriculture waste discharged worldwide every day
- 14000 people die every day due to health reasons arising from drinking unhealthy water
- 140 million people regularly drink water with contaminants more than WHO provided guidelines

1. <https://www.wri.org/insights/domestic-water-use-grew-600-over-past-50-years>, Otto and Schleifer (2020)
2. Carrao et al., *Climate Dynamics* (2018) (50) 2137-2155
3. Caretta et al., *Climatic Change* (2023) 176:100

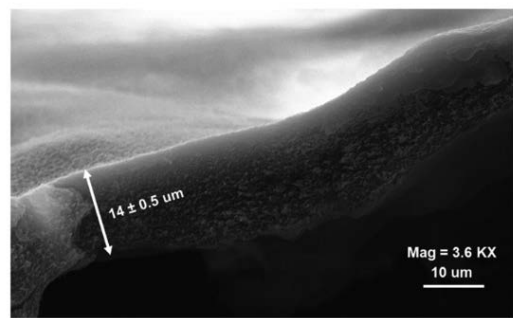
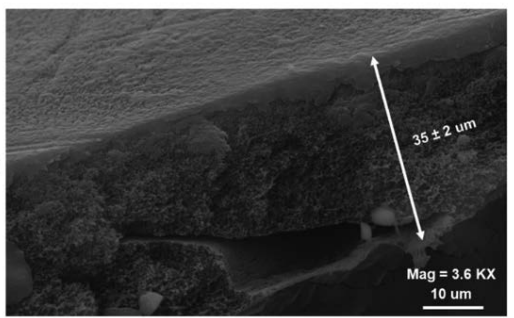
Introduction- UHPRO membrane compaction



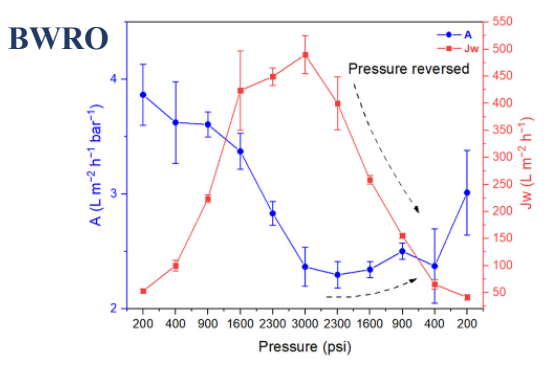
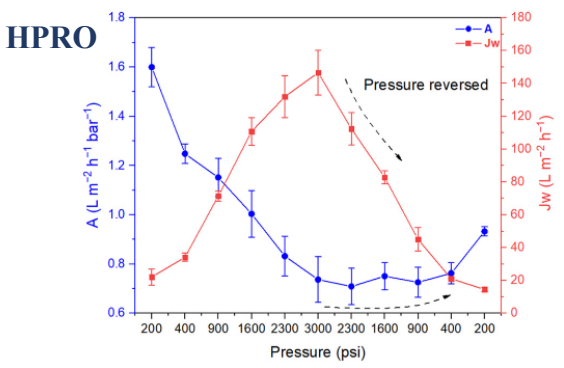
HPRO



BWRO

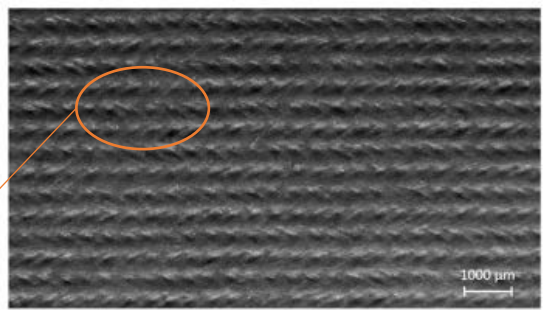


X-sectional SEM images of pristine and compacted membranes¹



Reduction of membrane permeance and water flux at higher pressures due to compaction

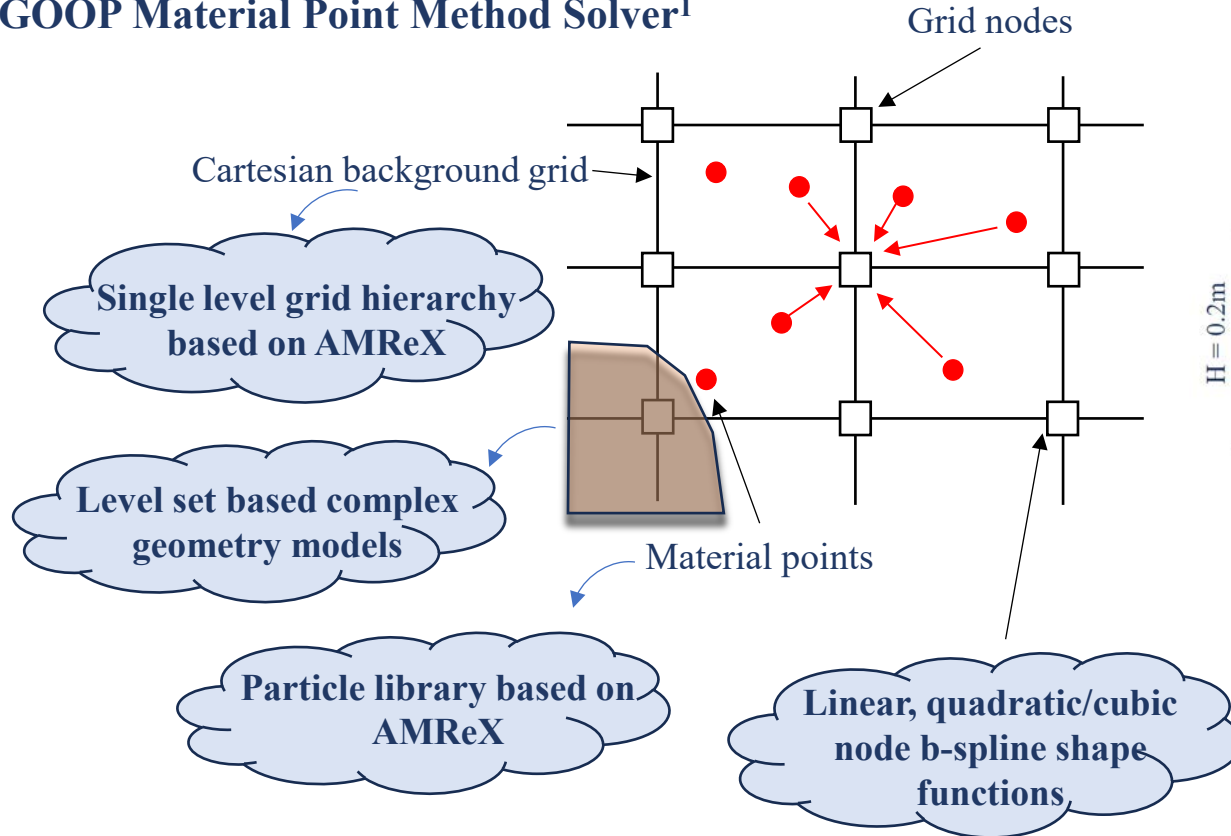
Clear imprinting of spacer shape on membrane surface



SEM images of compacted HPRO membrane fabric layer

ExaGOOP MPM Solver

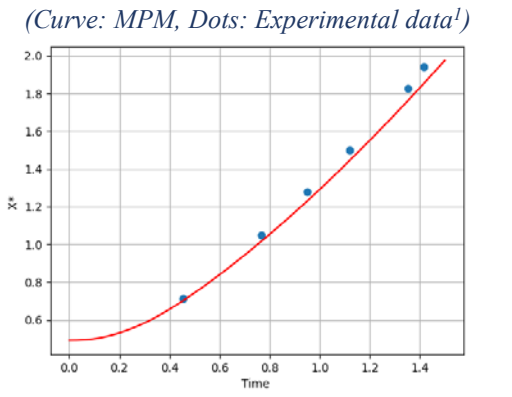
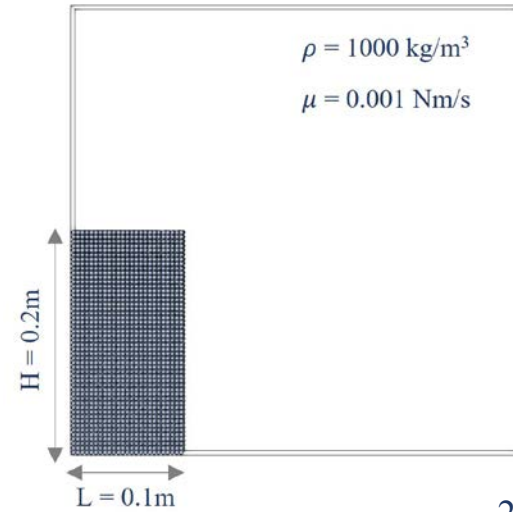
ExaGOOP Material Point Method Solver¹



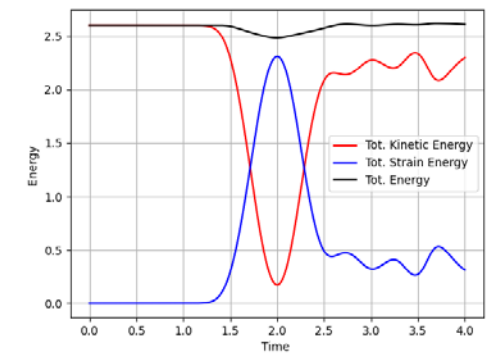
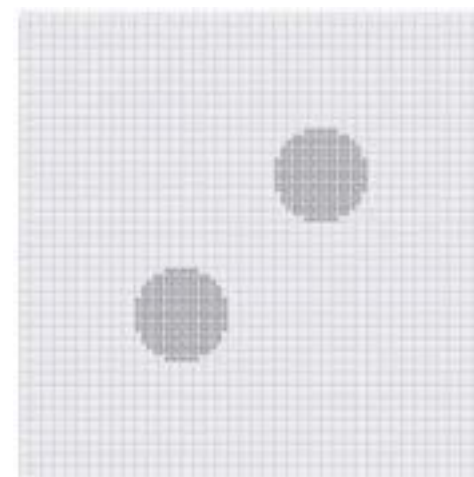
AMReX library provides parallelism for heterogenous (CPU+GPU) computing platforms

2D- dam break simulation

Evolution of normalized position of water-front with time.



2D Elastic Disk Collision



Validation and verification of ExaGOOP solver

1. <https://github.com/NREL/Exagoop>

2. "An experimental study of the collapse of liquid columns on a rigid horizontal plane", Martin & Moyce, 1952, *Philosophical Transactions of the Royal Society of London*

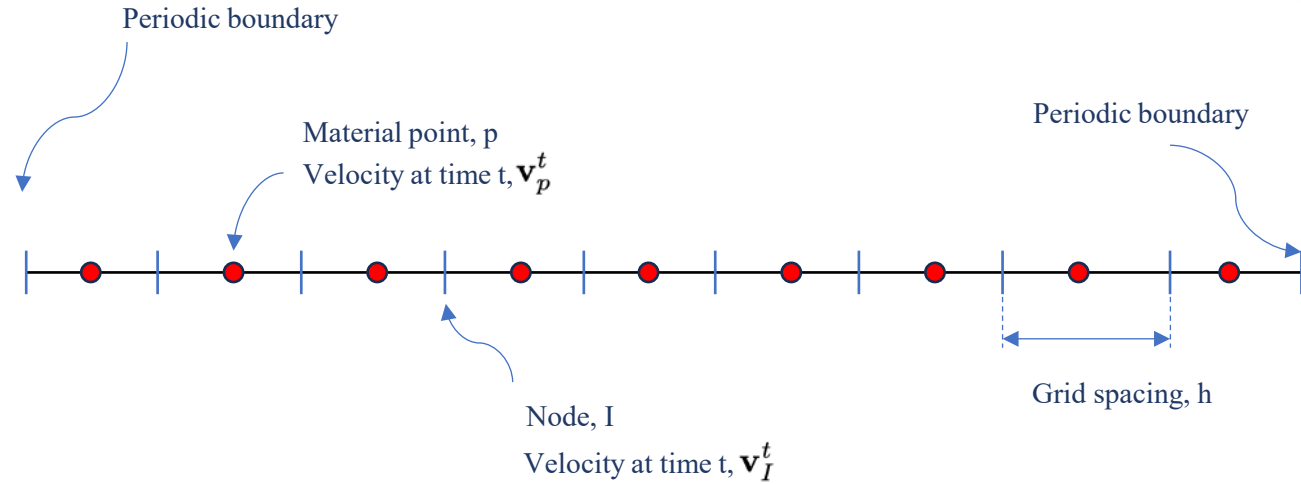
Analysis of MPM

Spectral Stability Analysis-Methodology

Governing Equation:

$$\rho \frac{D\mathbf{v}}{Dt} = \mathbf{F}_i + \mathbf{F}_e \quad \nearrow 0$$

$$= \frac{\partial}{\partial x} \left[\nu \frac{\partial \mathbf{v}}{\partial x} \right]$$



MPM Governing Equation at nodes:

$$\sum_{p=1}^{N_{part}} m_p N_I(\mathbf{x}_p) N_J(\mathbf{x}_p) \mathbf{a}_J = - \sum_{p=1}^{N_{part}} m_p \sigma_p^s \nabla N_I(\mathbf{x}_p)$$

Assumptions:

- One-dimensional
- Periodic boundaries
- External forces assumed to zero
- All material point masses are equal and constant
- Stability studied assuming *frozen* material point locations at a particular time instant

Total number of nodes: N_{nodes}

Total number of material points: N_{part}

● Material points

+ Grid Nodes

m_p = mass of material point

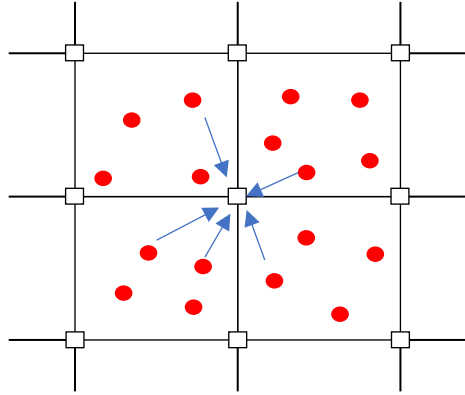
$N_I(x_p)$ = shapefunction defined at node I and evaluated at material point position x_p

σ_p^s = stress tensor defined at material point

a_J = acceleration at node J

Spectral Stability Analysis-Methodology

1. Particle to grid interpolation



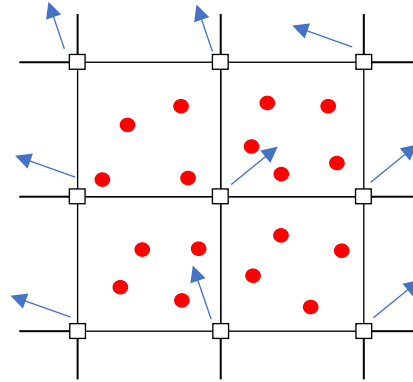
$$\mathbf{v}_I^t = \bar{\mathbf{T}}_{p \rightarrow I} \mathbf{v}_p^t$$

$$\bar{\mathbf{T}}_{p \rightarrow I} = \bar{\mathbf{M}}^{-1} \bar{\mathbf{C}}$$

Mass matrix
($N_{\text{nodes}} \times N_{\text{nodes}}$)

Coefficient matrix, ($N_{\text{nodes}} \times N_{\text{part}}$)

2. Nodal time integration



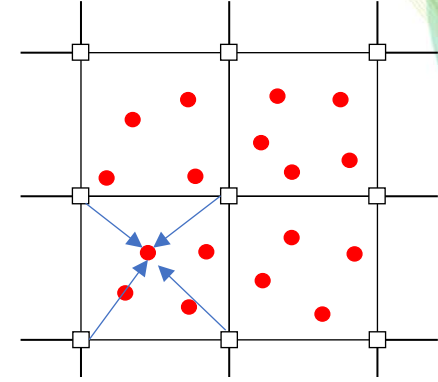
$$\bar{\mathbf{v}}_I^{t+\Delta t} = \left[\bar{\mathbf{I}} - Fo \bar{\mathbf{G}}_{P \rightarrow I} \bar{\mathbf{G}}_{I \rightarrow P} \right] \bar{\mathbf{v}}_I^t$$

$$Fo = \frac{\nu \Delta t}{h^2}$$

P2G Gradient matrix

G2P Gradient matrix

3. Grid to particle interpolation



$$\mathbf{v}_p^{t+\Delta t} = \alpha \left(\mathbf{v}_p^t + \sum_I N_I(\mathbf{x}_p^t) [\mathbf{v}_I^{t+\Delta t} - \mathbf{v}_I^t] \right) + (1 - \alpha) \sum_I N_I(\mathbf{x}_p^t) \mathbf{v}_I^{t+\Delta t}$$

$$\bar{\mathbf{v}}_p^{t+\Delta t} = \left[\bar{\alpha} + \bar{\mathbf{T}}_{I \rightarrow P} \bar{\Theta} \bar{\mathbf{T}}_{P \rightarrow I} + (\bar{\mathbf{I}} - \bar{\alpha}) \bar{\mathbf{T}}_{I \rightarrow P} \bar{\Phi} \bar{\mathbf{T}}_{P \rightarrow I} \right] \bar{\mathbf{v}}_p^t$$

$$\bar{\Theta} = -Fo \bar{\mathbf{G}}_{P \rightarrow I} \bar{\mathbf{G}}_{I \rightarrow P}$$

$$\bar{\Phi} = \bar{\mathbf{I}} - \bar{\Theta}$$

Spectral Stability Analysis-Methodology

Exact amplification factor

$$\mathbf{v}(x, t) = \int \hat{\mathbf{V}}(k, t) e^{ikx} dk$$

$$\mathbf{v}(x, t + \Delta t) = \int \mathbf{G} \hat{\mathbf{V}}(k, t) e^{ikx} dk$$



Theoretical amplification factor

MPM amplification factor

$$\bar{\mathbf{v}}_p^{t+\Delta t} = \left[\bar{\alpha} + \bar{\mathbf{T}}_{I \rightarrow P} \bar{\Theta} \bar{\mathbf{T}}_{P \rightarrow I} + (\bar{I} - \bar{\alpha}) \bar{\mathbf{T}}_{I \rightarrow P} \bar{\Phi} \bar{\mathbf{T}}_{P \rightarrow I} \right] \bar{\mathbf{v}}_p^t$$

$$\mathbf{v}_{p,l}^{t+\Delta t} = \underbrace{\left[\bar{\alpha} + \bar{\mathbf{T}}_{I \rightarrow P} \bar{\Theta} \bar{\mathbf{T}}_{P \rightarrow I} + (\bar{I} - \bar{\alpha}) \bar{\mathbf{T}}_{I \rightarrow P} \bar{\Phi} \bar{\mathbf{T}}_{P \rightarrow I} \right]}_{\bar{\mathbf{A}}} \bar{\mathbf{v}}_p^t$$

$$\begin{aligned} \mathbf{v}_{p,l}^{t+\Delta t} &= \int \bar{\mathbf{A}}_{l,m} \hat{\mathbf{V}}(k, t) e^{ikx_m} dk \\ &= \int \bar{\mathbf{A}}_{l,m} \hat{\mathbf{V}}(k, t) e^{ikx_l} e^{ik(x_m - x_l)} dk \\ &= \int \underbrace{\bar{\mathbf{A}}_{l,m} \bar{\mathbf{P}}_{m,l}}_{G_{MPM}} \hat{\mathbf{V}}(k, t) e^{ikx_l} dk \end{aligned}$$

Function of kh and Fo

Knowing shape functions evaluated at specified material points location, one can calculate amplification factor

Spectral Stability Analysis- Results ($|G|$)

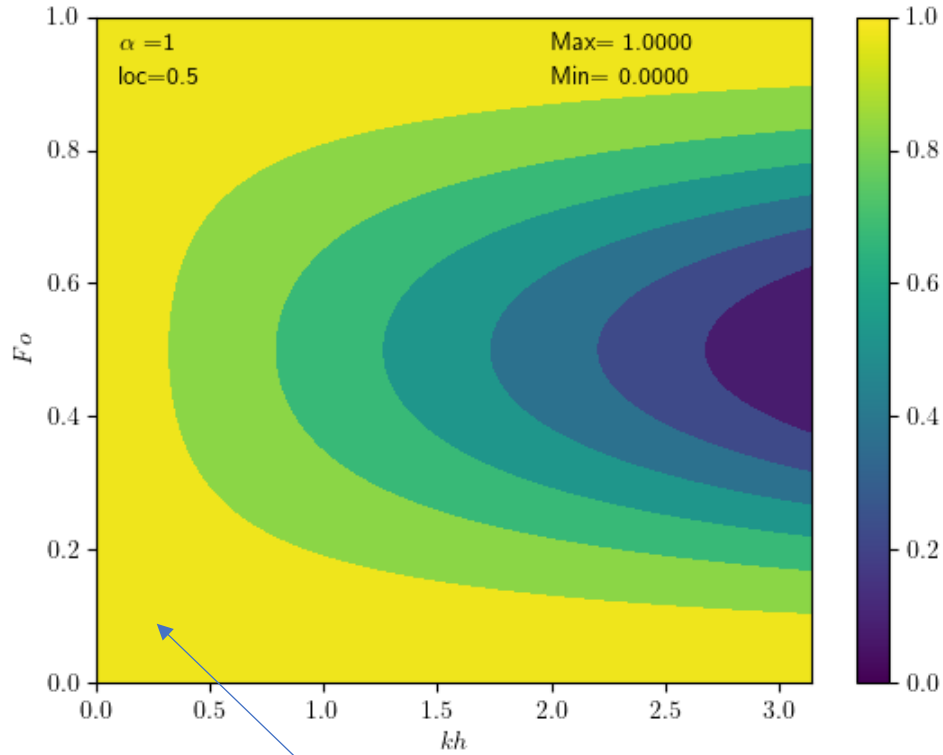
Effect of α (PIC and FLIP update)

Shape Function: Linear Hat
Material point location: Mid-cell

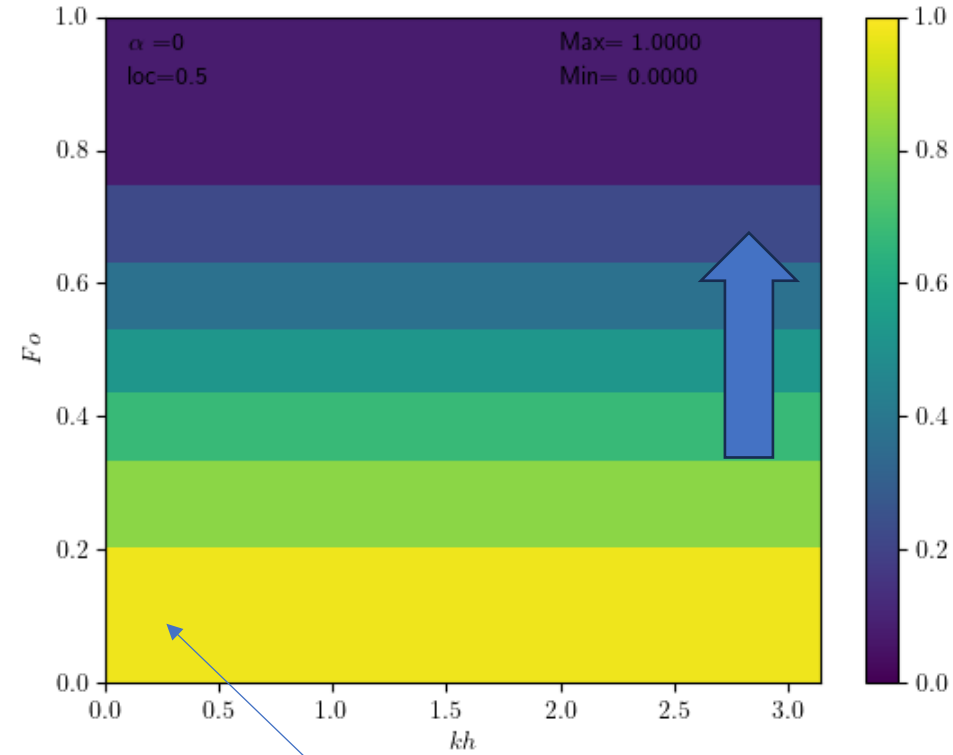
$$\mathbf{v}_p^{t+\Delta t} = \alpha \left(\mathbf{v}_p^t + \sum_I N_I(\mathbf{x}_p) [\mathbf{v}_I^{t+\Delta t} - \mathbf{v}_I^t] \right) + (1 - \alpha) \sum_I N_I(\mathbf{x}_p) \mathbf{v}_I^{t+\Delta t}$$

$\alpha = 1.0$

$\alpha = 0.0$



Good region to compute



Good region to compute

Progressive damping with higher Δt for all wavenumbers

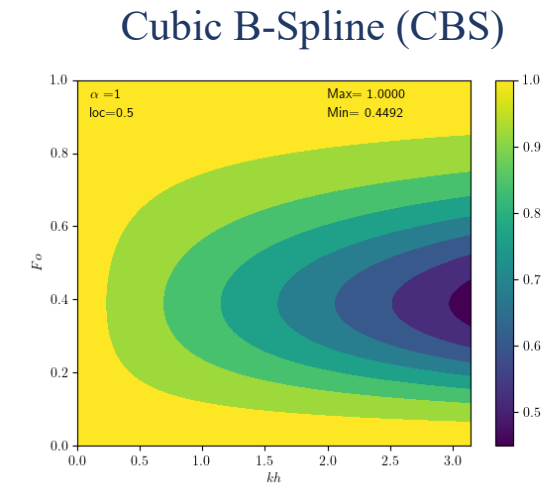
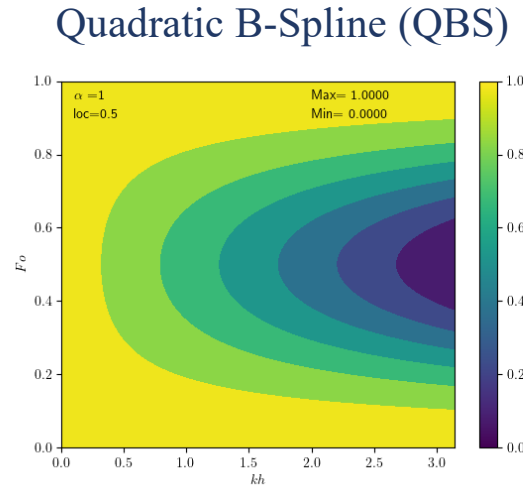
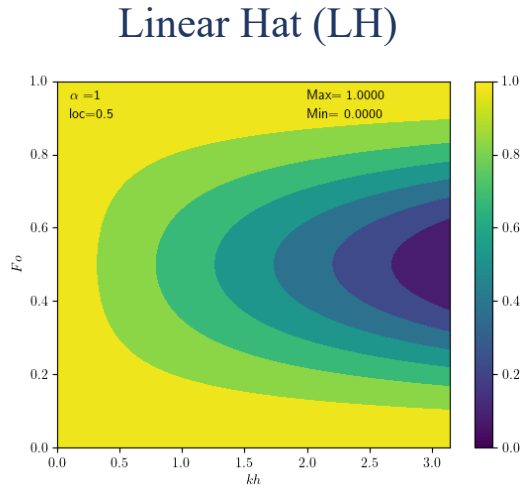
Damping at all spatial frequencies for $\alpha = 0.0$

Spectral Stability Analysis- Results ($|G|$)

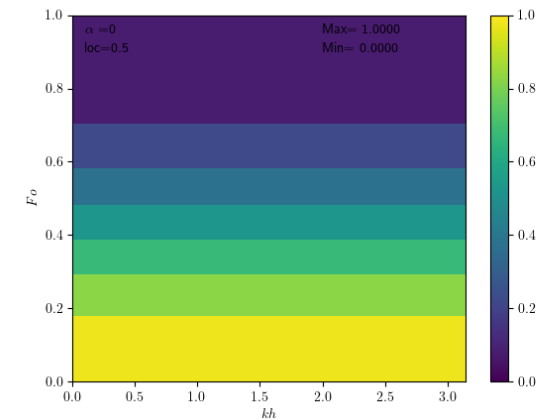
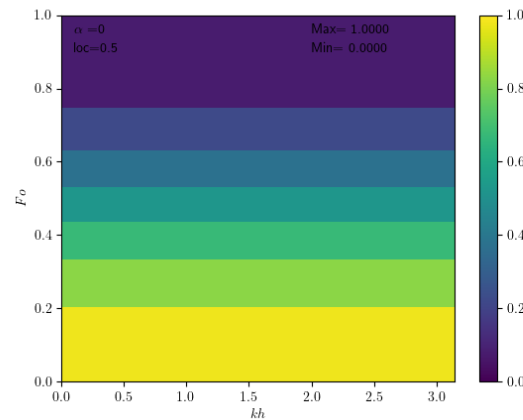
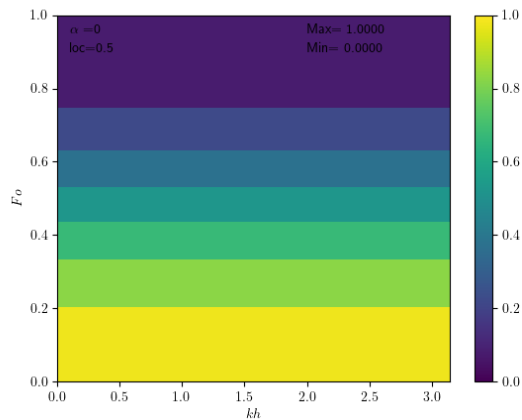
Effect of shape functions

Material point location: Mid-cell

$\alpha = 1.0$



$\alpha = 0.0$



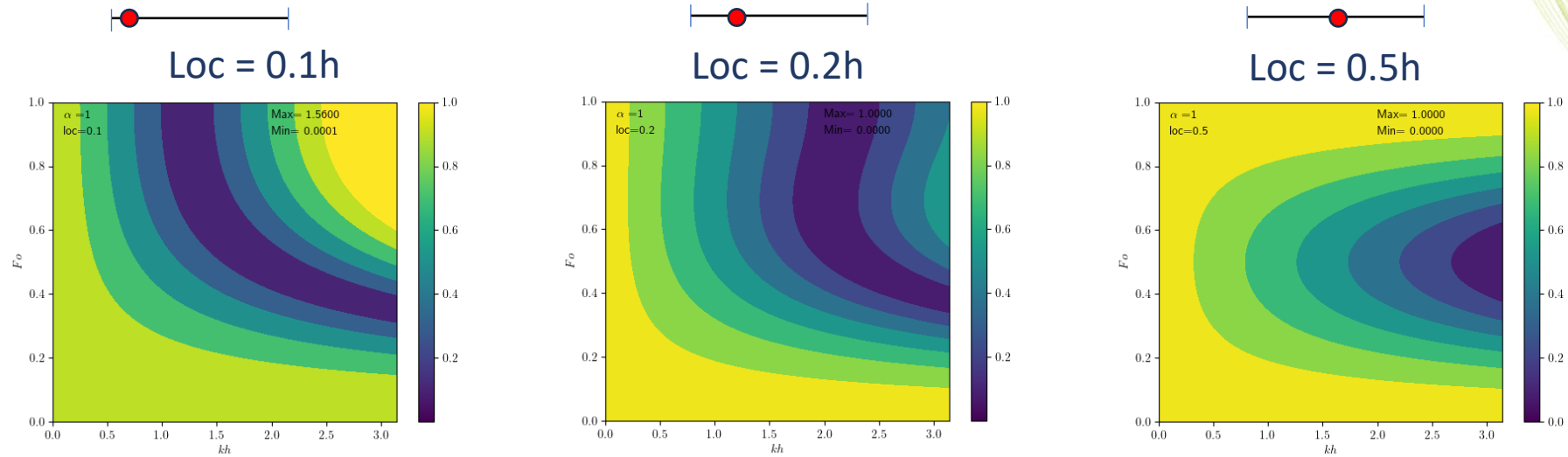
All schemes behave alike at $\alpha = 0.0$

Spectral Stability Analysis- Results ($|G|$)

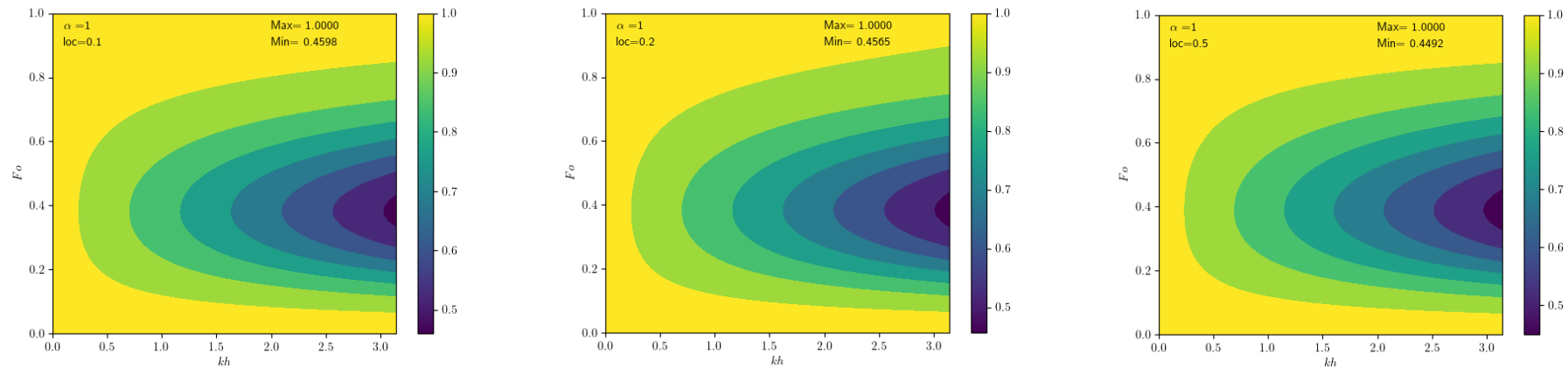
Effect of material point location

$\alpha = 1.0$

Linear Hat (LH)



Cubic B-Spline (CBS)



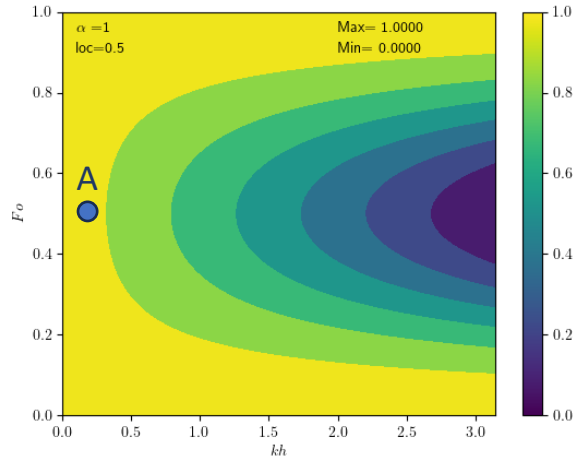
Cubic spline properties least sensitive to material point location

Linear hat susceptible to grid crossing instability

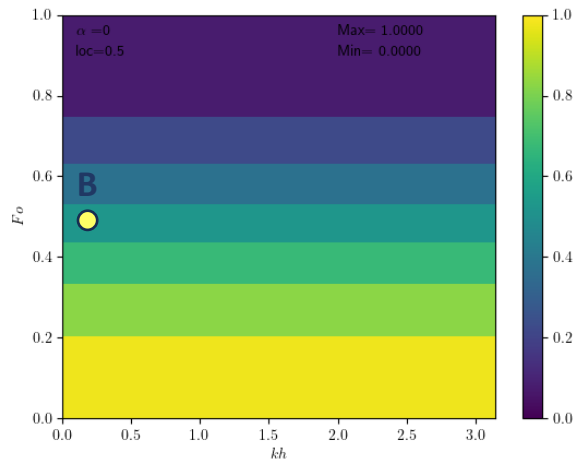
Spectral Stability Analysis- Validation

Test Case Description: Effect of α

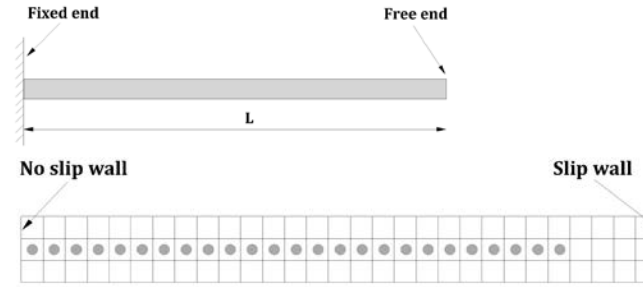
$\alpha = 1.0$
 Shape Function: LH
 $kh = 0.13$
 $Fo = 0.5$



$\alpha = 0.0$
 Shape Function: LH
 $kh = 0.13$
 $Fo = 0.5$



Validation test case



Initial solution

$$u(x, 0) = 0 \quad \frac{\partial u}{\partial t}(x, 0) = V_0 \sin\left(\frac{\pi x}{2L}\right)$$

Exact solution

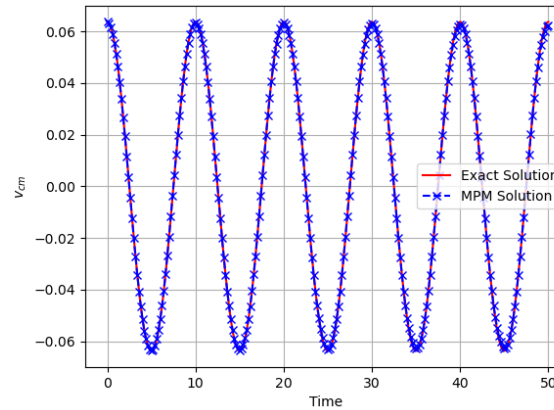
$$u(x, t) = V_0/\omega_1 \sin\left(\frac{\pi x}{2L}\right) \sin(\omega_1 t)$$

$$v(x, t) = V_0 \sin\left(\frac{\pi x}{2L}\right) \cos(\omega_1 t)$$

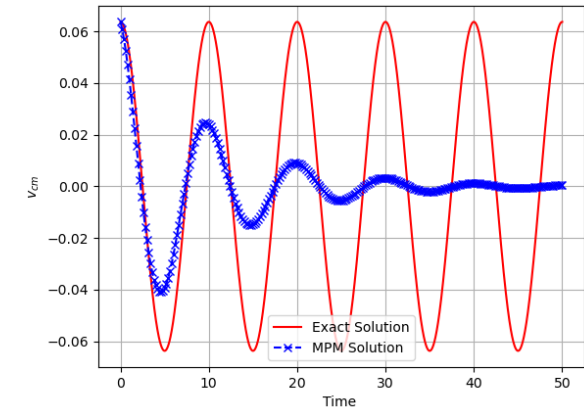
|G| computed from analysis

	Kh	Fo	Scheme	α	G
Test A	0.126	0.5	LH	1.0	0.96
Test B	0.126	0.5	LH	0.0	0.5

Test A



Test B

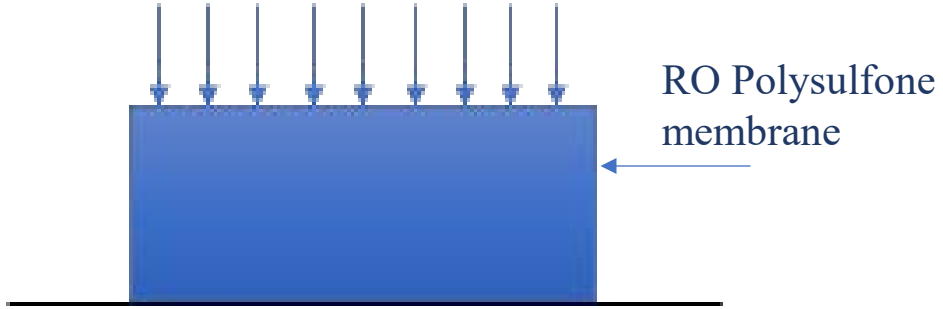


$\alpha = 0.0$ induces solution damping

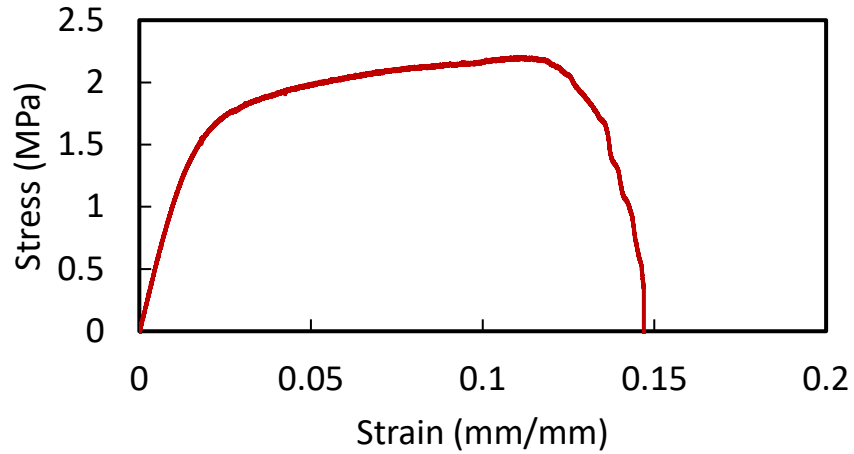
Application to UHPRO Membrane Compaction

Simulation of HPRO membrane compaction

Pressure=200 bar



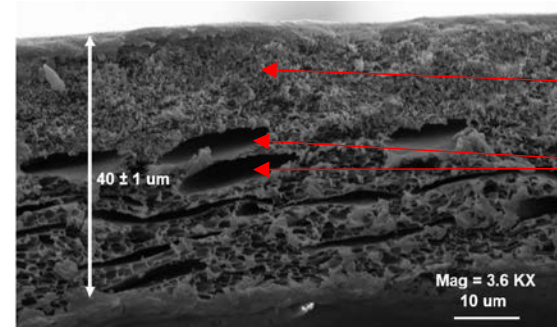
PS membrane modeled as linear elastic body



Young's modulus, $E = 100\text{MPa}$ obtained from tensile test

MPM Model:

SEM image of uncompact membrane cross-section

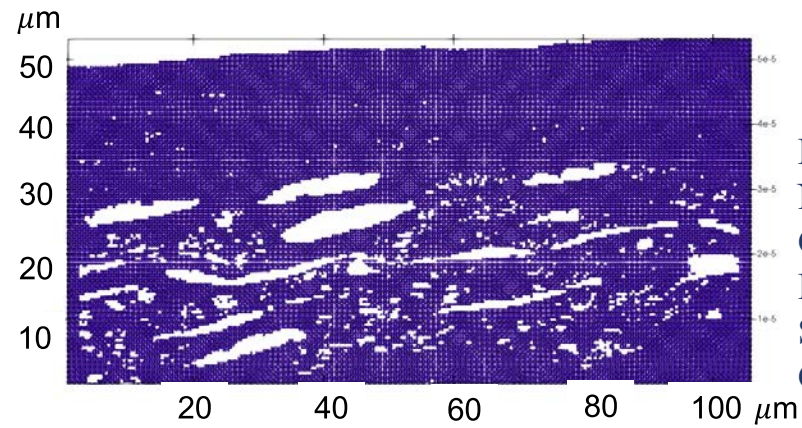


Fine porous structures

Macro voids



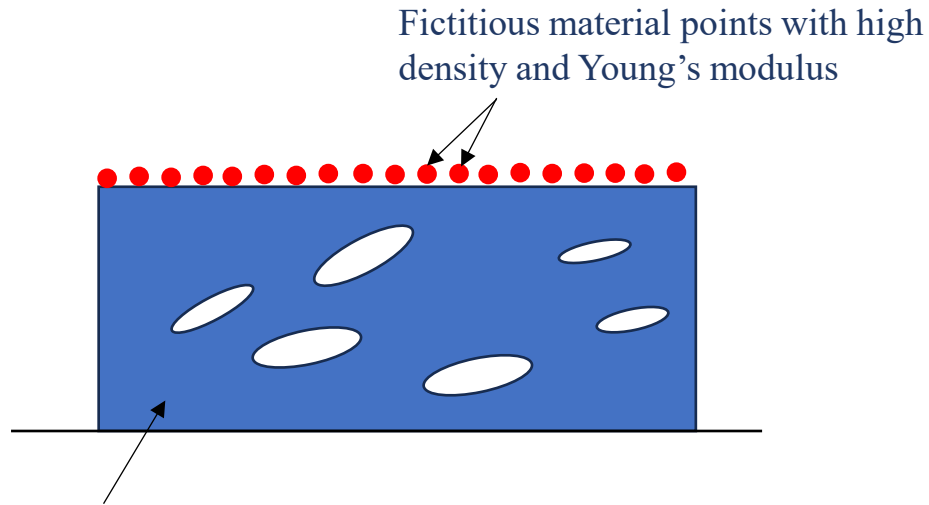
Image converted to material point collection using python script



Domain size: 100um x 60um
 Number of material points: 180K
 Constitutive Model: Linear Elastic
 Shape Function: Linear Hat
 CFL = 0.1

Load Application Strategy

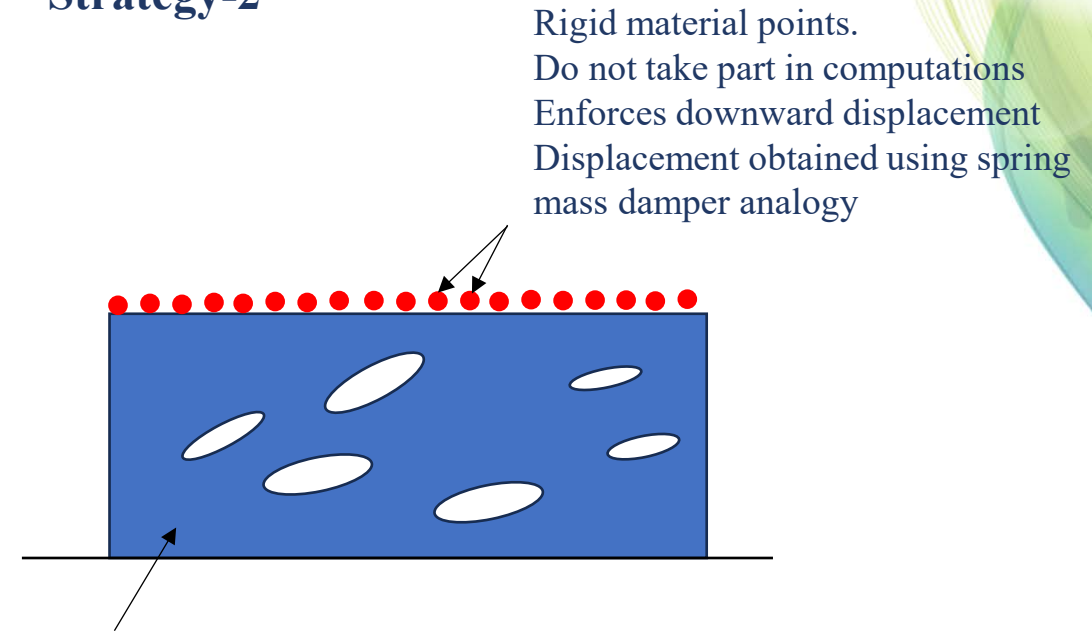
Strategy-1



Membrane material points

- Weight of fictitious material points enforces the desired pressure
- Scaling Young's modulus and density \rightarrow Δt remains unaltered
- Numerical damping induced by reducing α

Strategy-2



Membrane material points

- Reactive force from membrane calculated by interpolating stress on rigid material points
- External damping can be varied to reduce oscillations and reach steady state

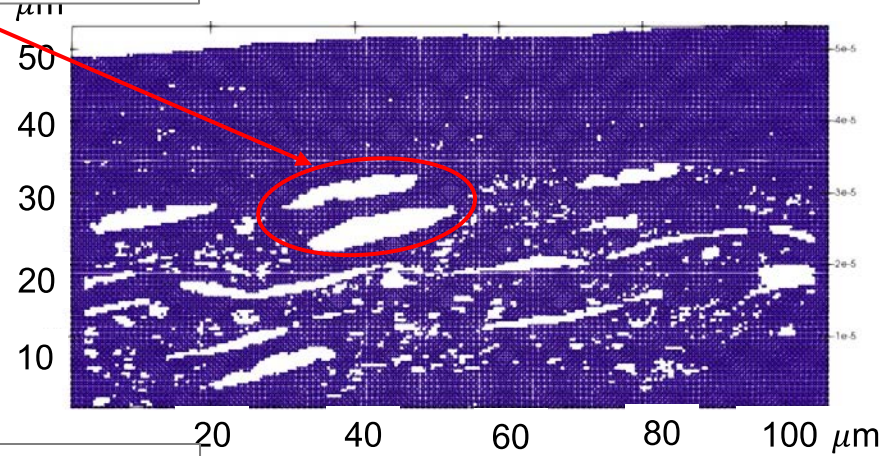
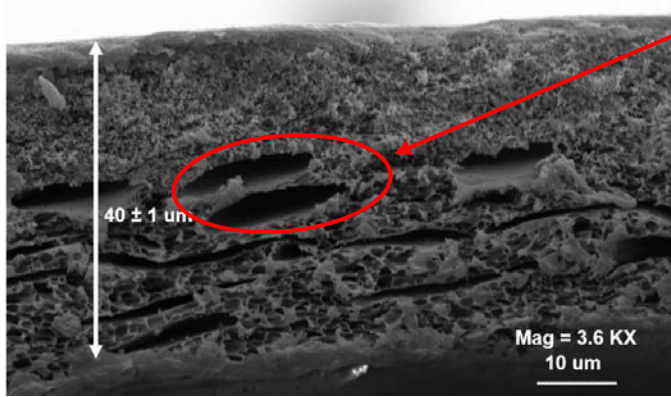
Fictitious body forces added to match applied pressures due to numerical instabilities

Application to simulation of RO membrane compaction

SEM Image

Uncompacted macro voids

MPM

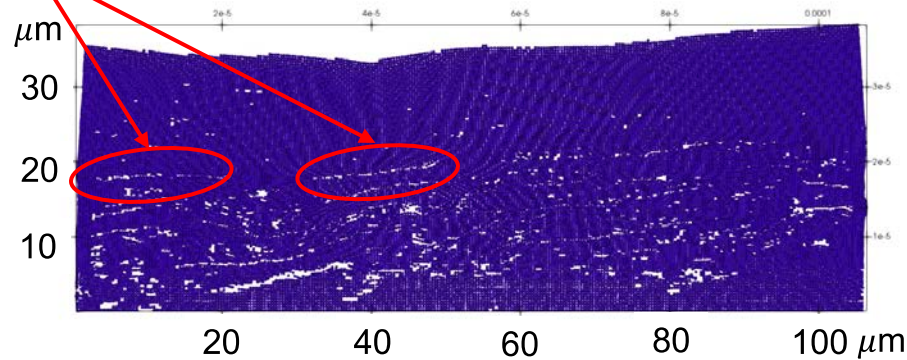
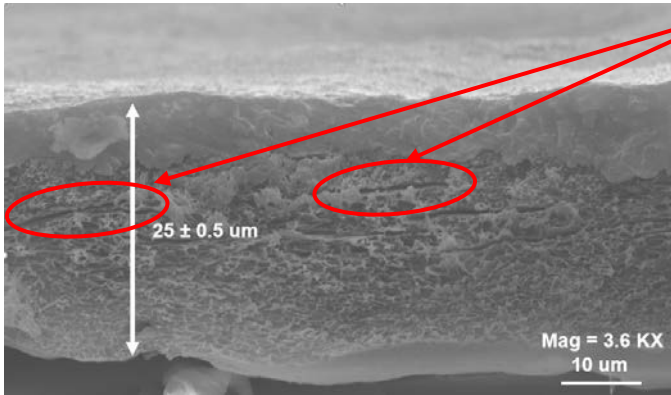


Uncompacted membrane

(a)

Compacted macro voids

(b)



Compacted membrane

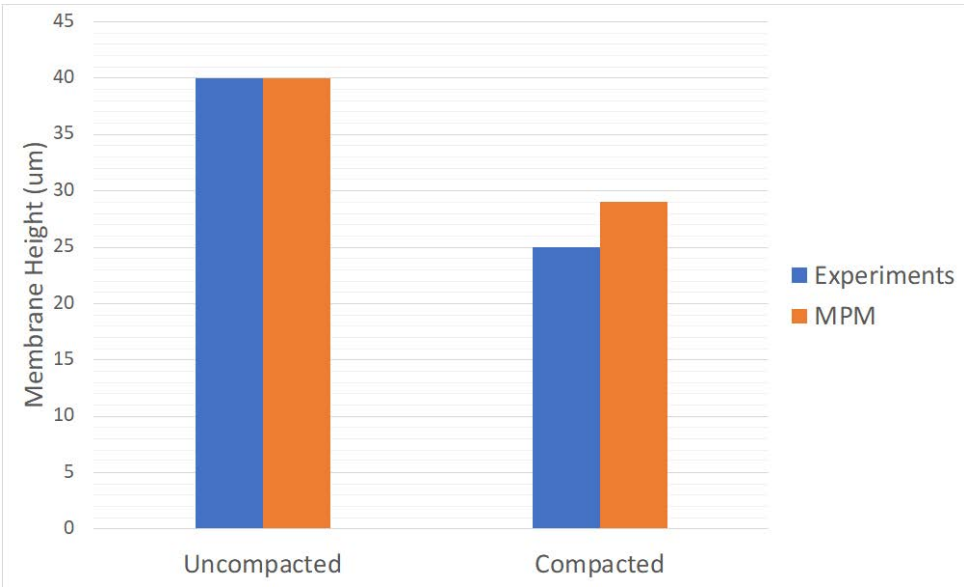
(c)

(d)

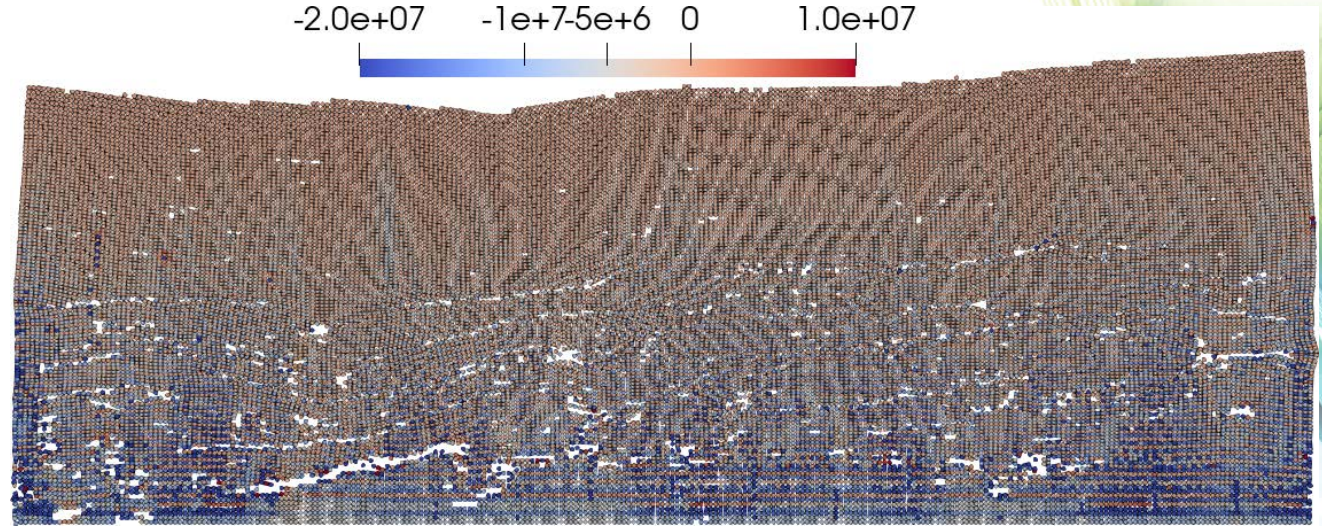
Good qualitative match between MPM results and SEM images

National Alliance for Water Innovation

Application to simulation of RO membrane compaction



Comparison of membrane heights observed in experiments and MPM



Normal stress contours at material points

Conclusions & Perspectives

- MPM solver ExaGOOP developed based on AMReX library. Works on heterogenous platforms. Validated against experimental and analytical solutions
- Spectral analysis of regular MPM method reveals numerical properties of regular MPM methods using linear hat, B- spline shape functions with explicit time integration schemes
- MPM applied to study HPRO membrane compaction. Numerical instabilities observed with load application strategies- a simplified approach adopted for now. 3-D, full-membrane simulations in progress.

THANK YOU

NREL/PR-2C00-91212

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